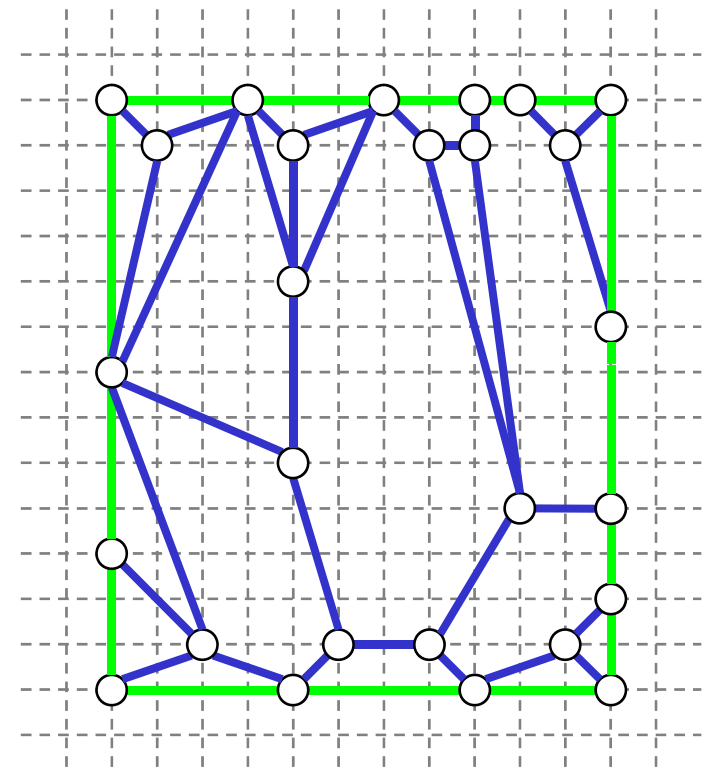
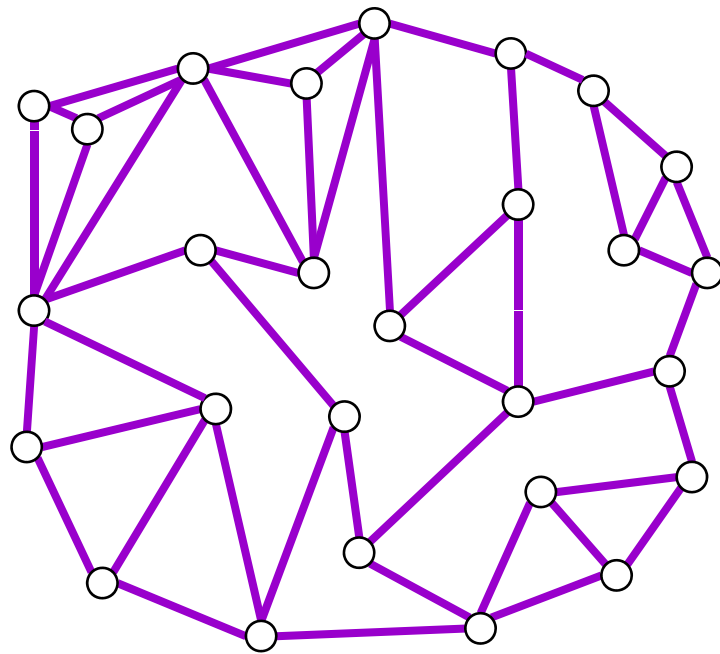


Convex Grid Drawings of Plane Graphs with Rectangular Contours



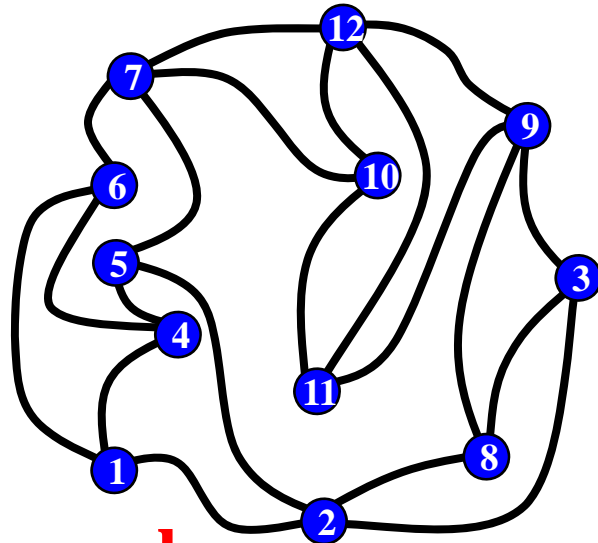
Akira Kamada (Tohoku University)

Kazuyuki Miura (Fukushima University)

Takao Nishizeki (Tohoku University)

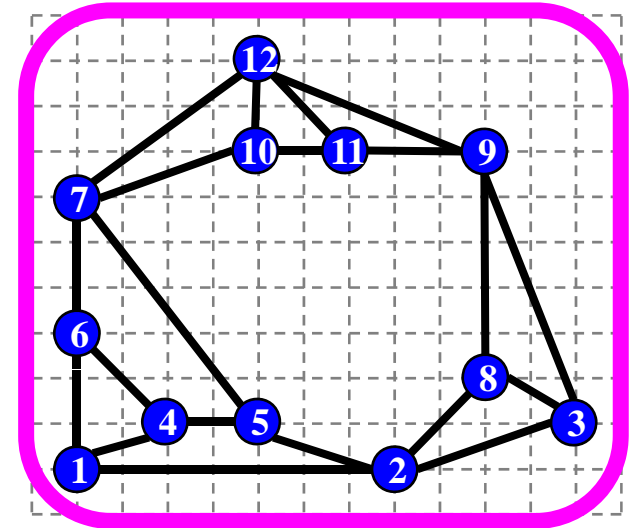
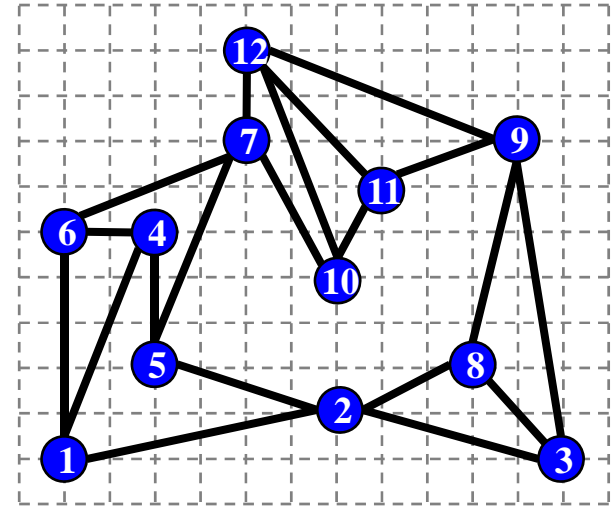
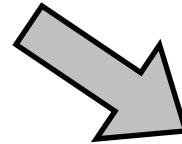
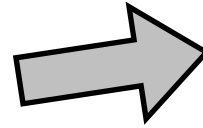
Drawings

vertex
edge

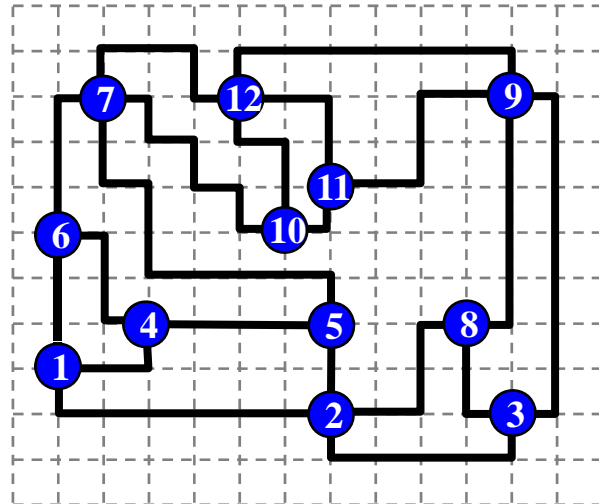


plane graph

no edge-intersection



convex grid drawing

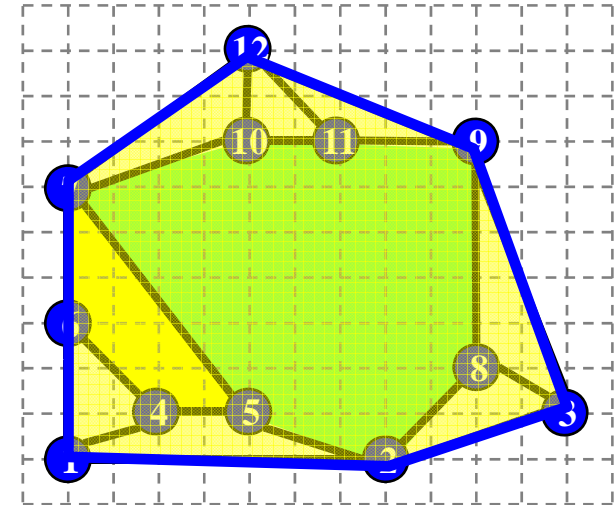
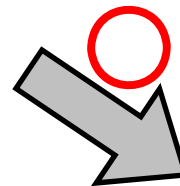
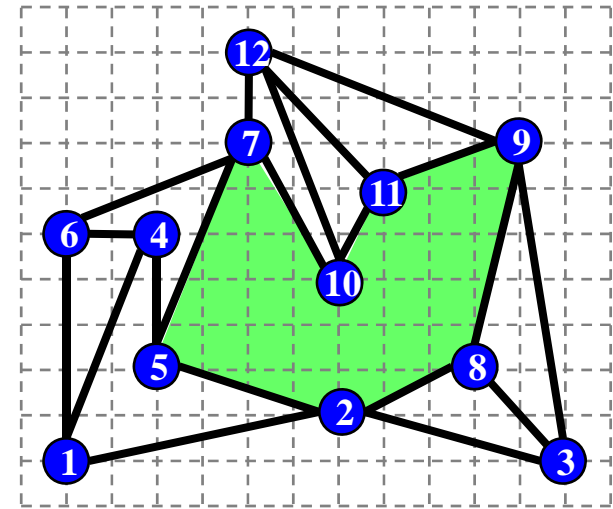
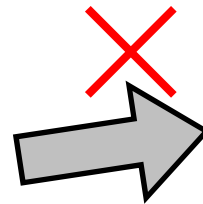
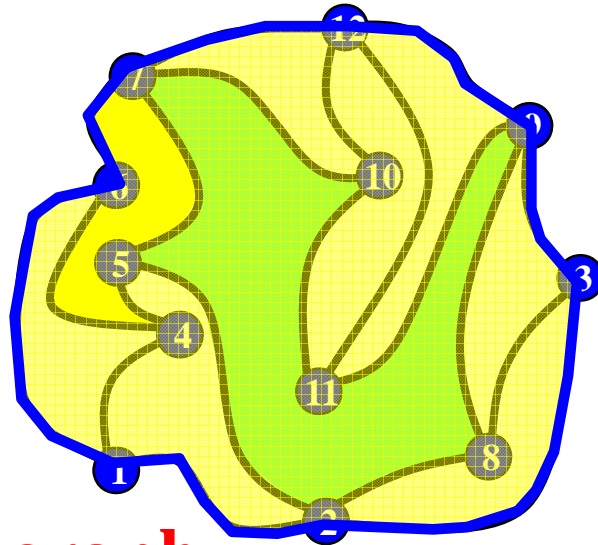


Convex grid drawing

vertex

edge

plane graph



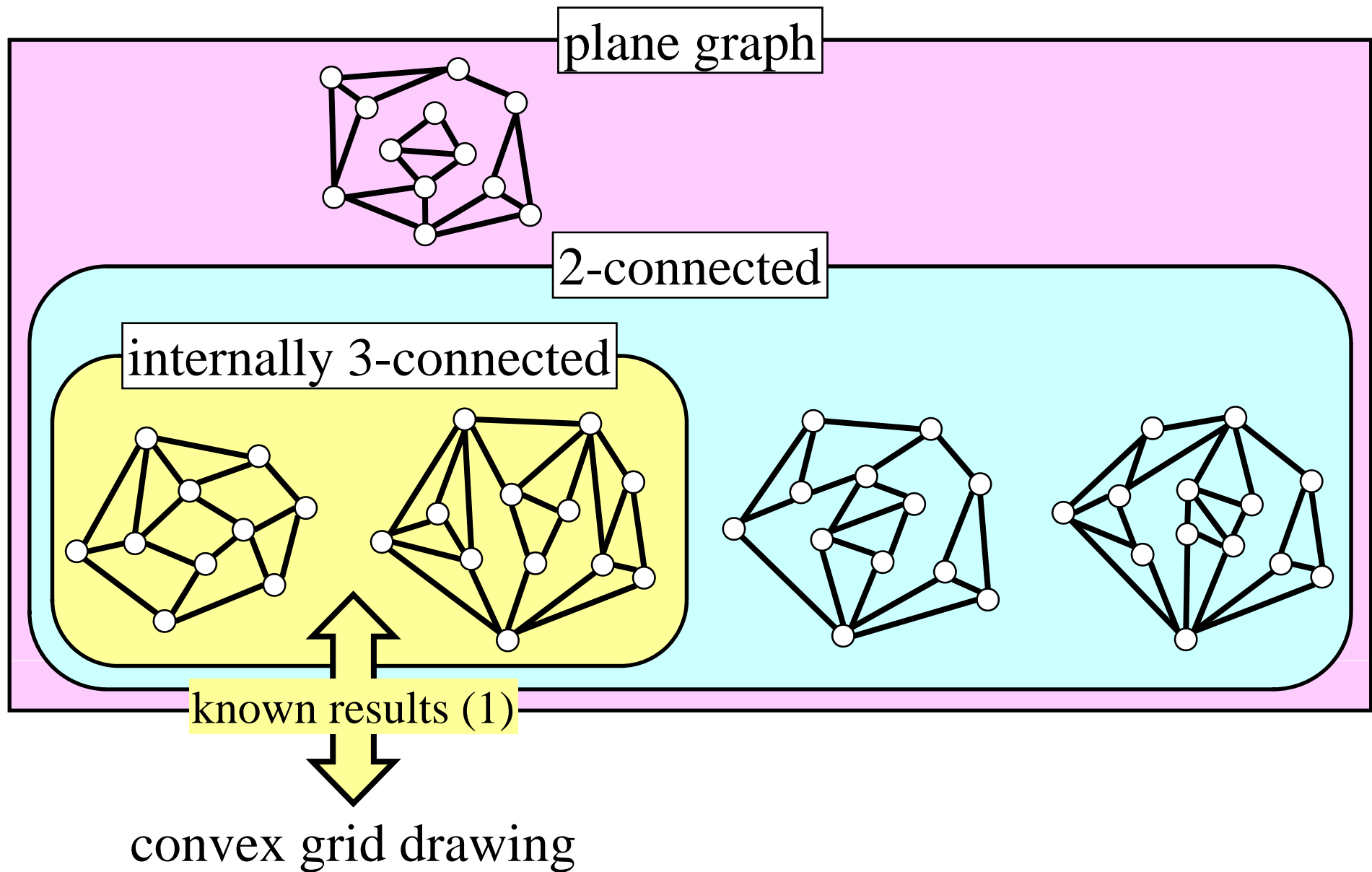
outer face

vertex : grid point

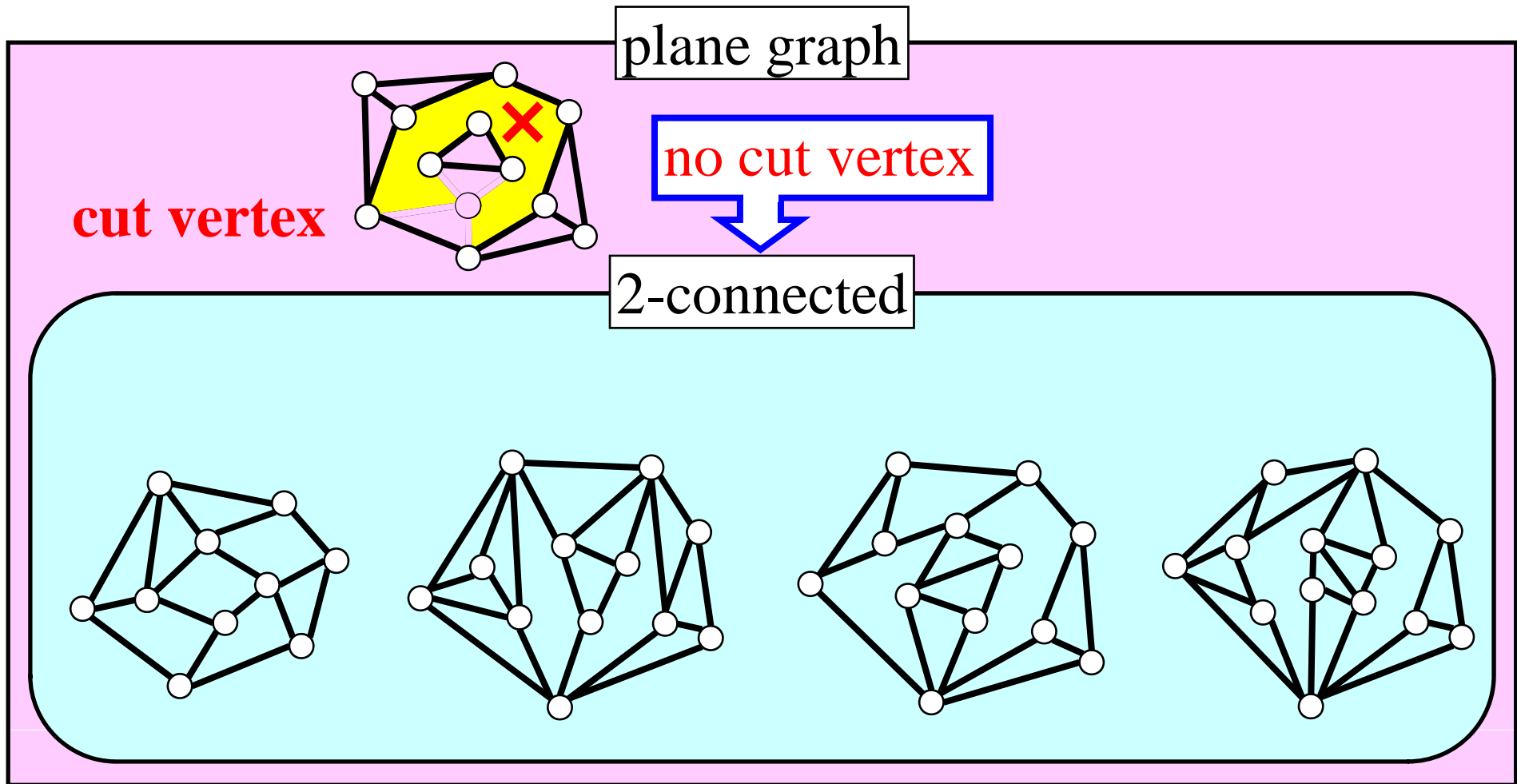
edge : straight line segment
without edge-intersection

face : convex polygon

Known results (1)

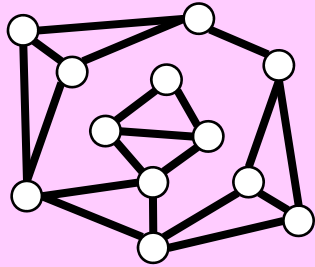


Known results (1)

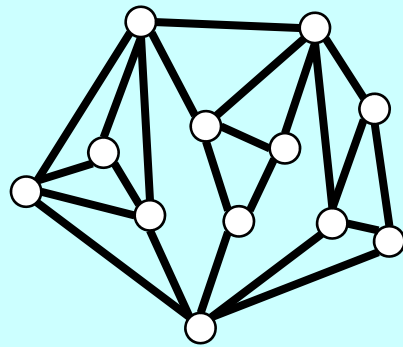
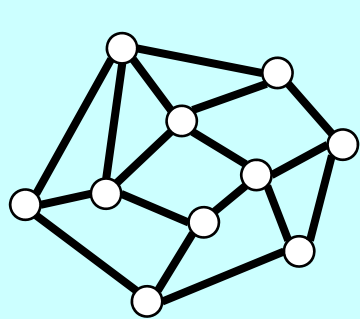


Known results (1)

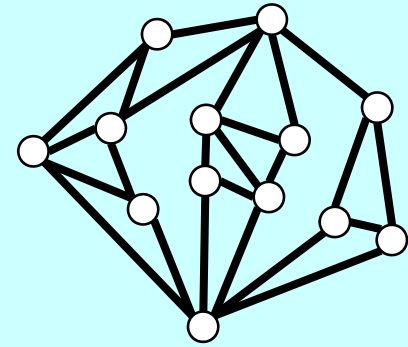
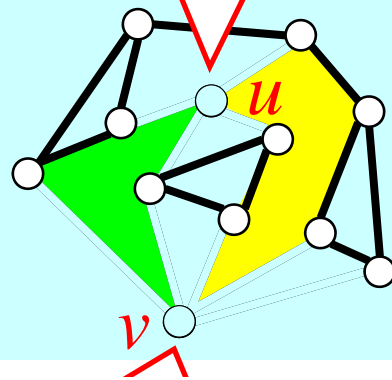
plane graph



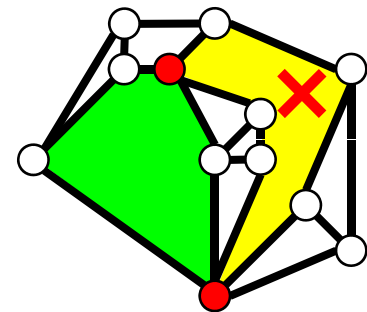
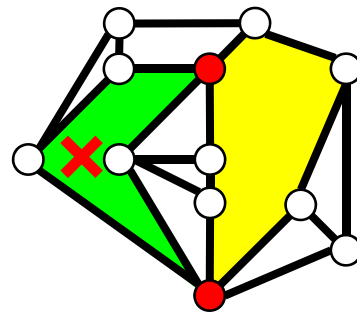
2-connected



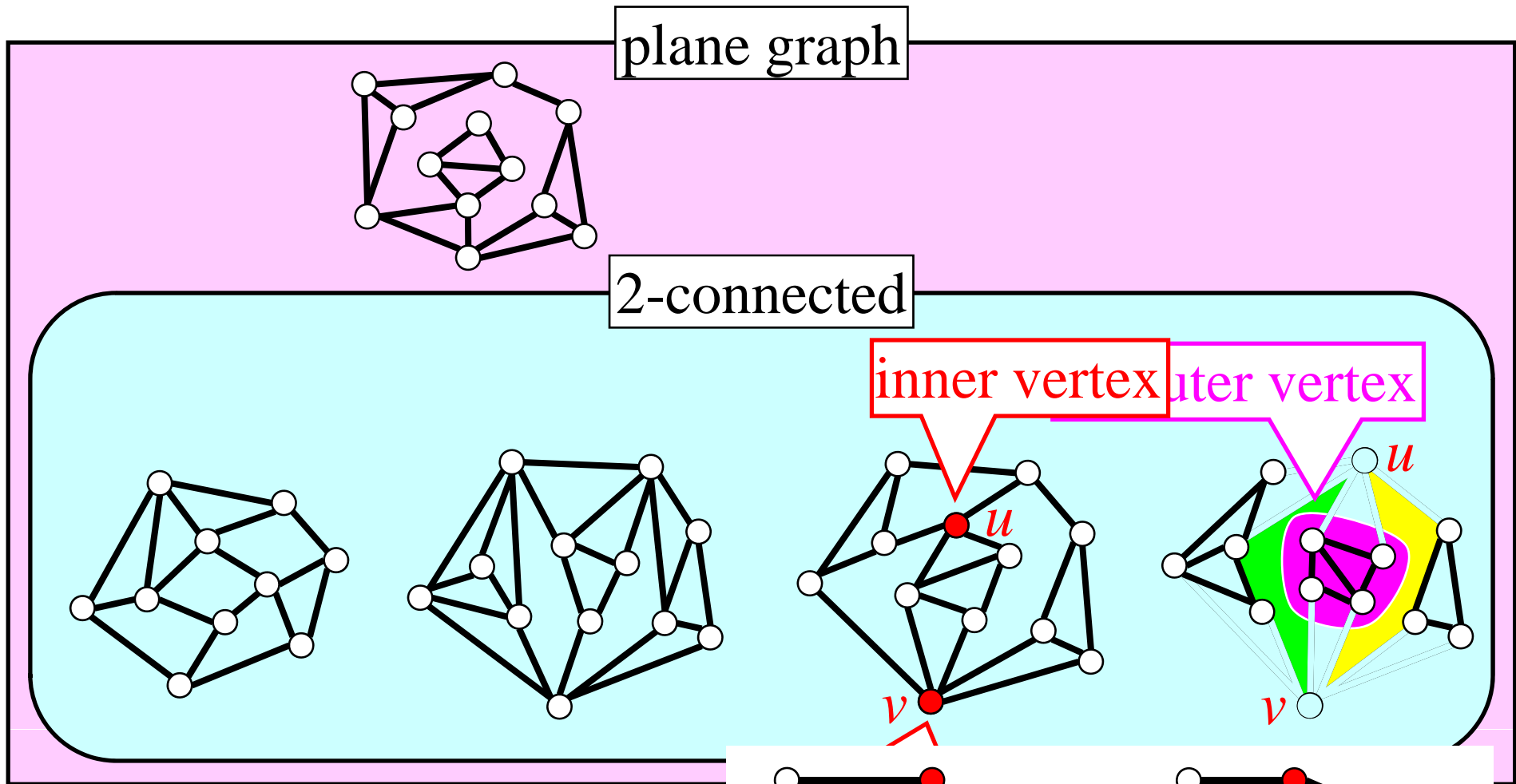
inner vertex



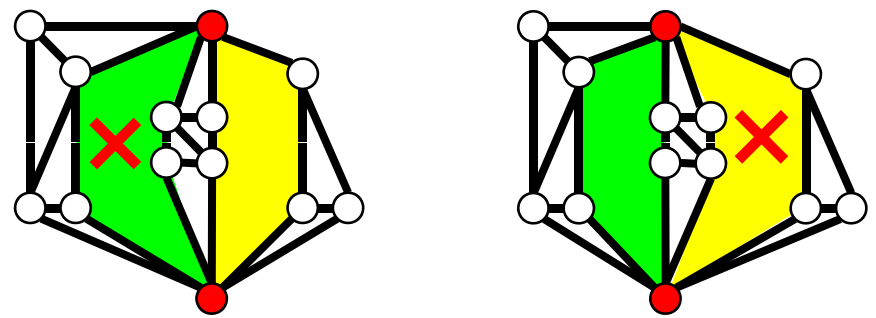
cannot be **simultaneously**
drawn as convex polygons



Known results (1)



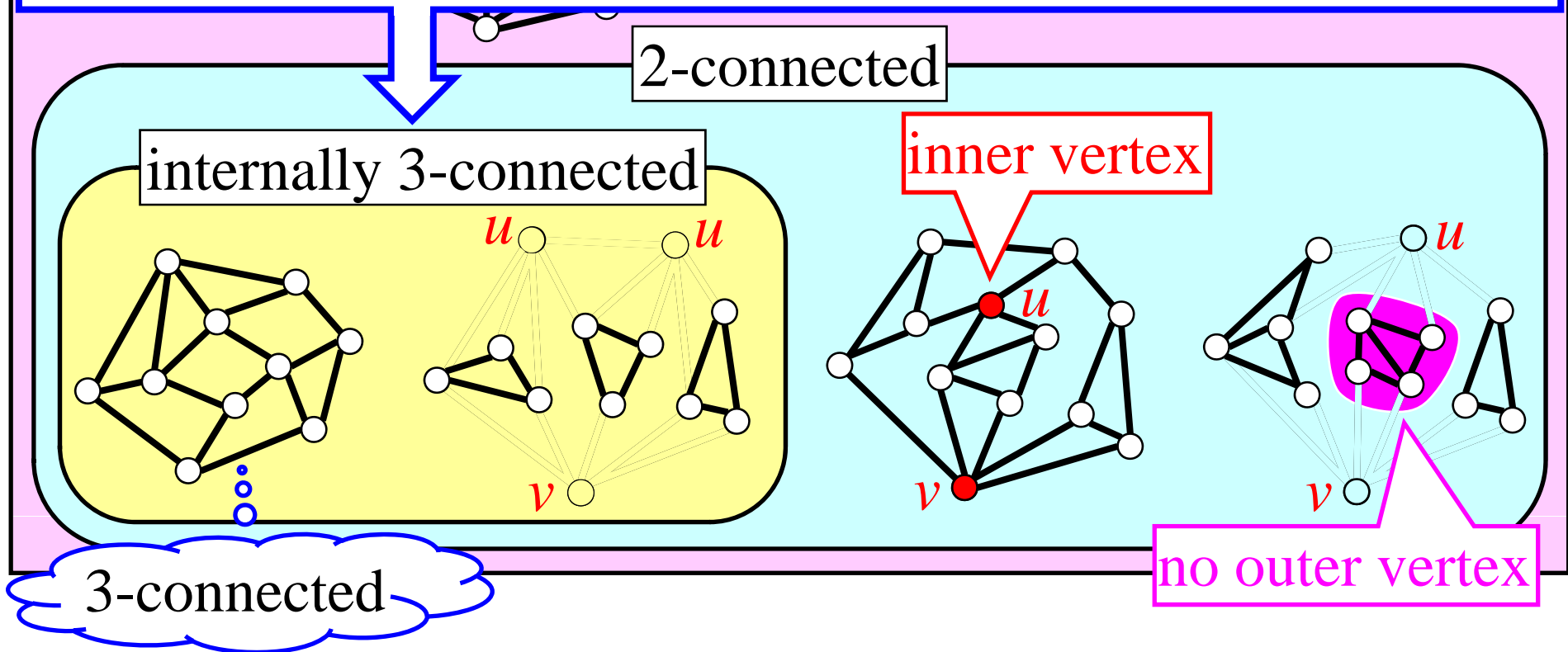
cannot be **simultaneously**
drawn as convex polygons



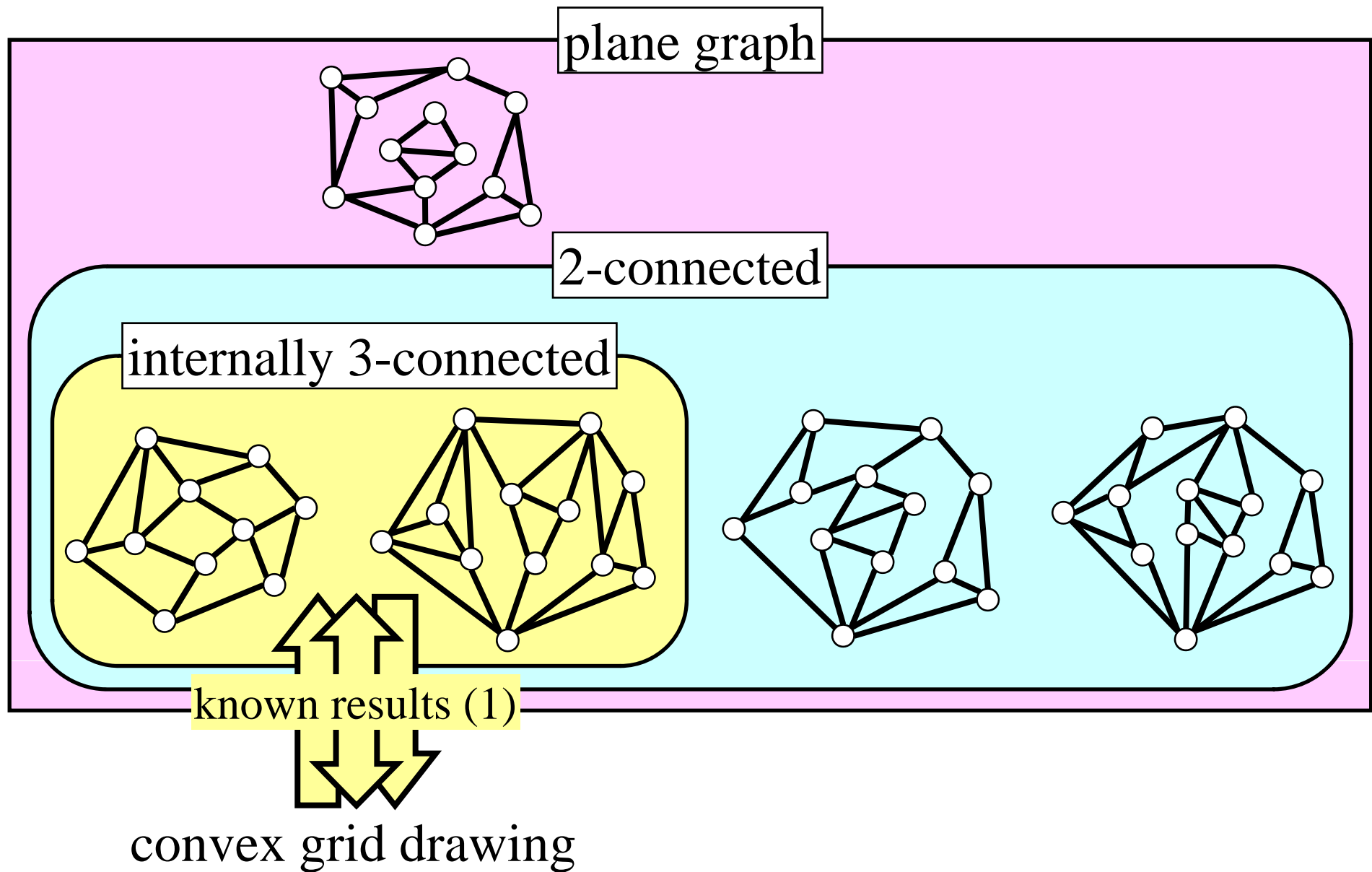
Known results (1)

for any separation pair $\{u, v\}$ of G ,

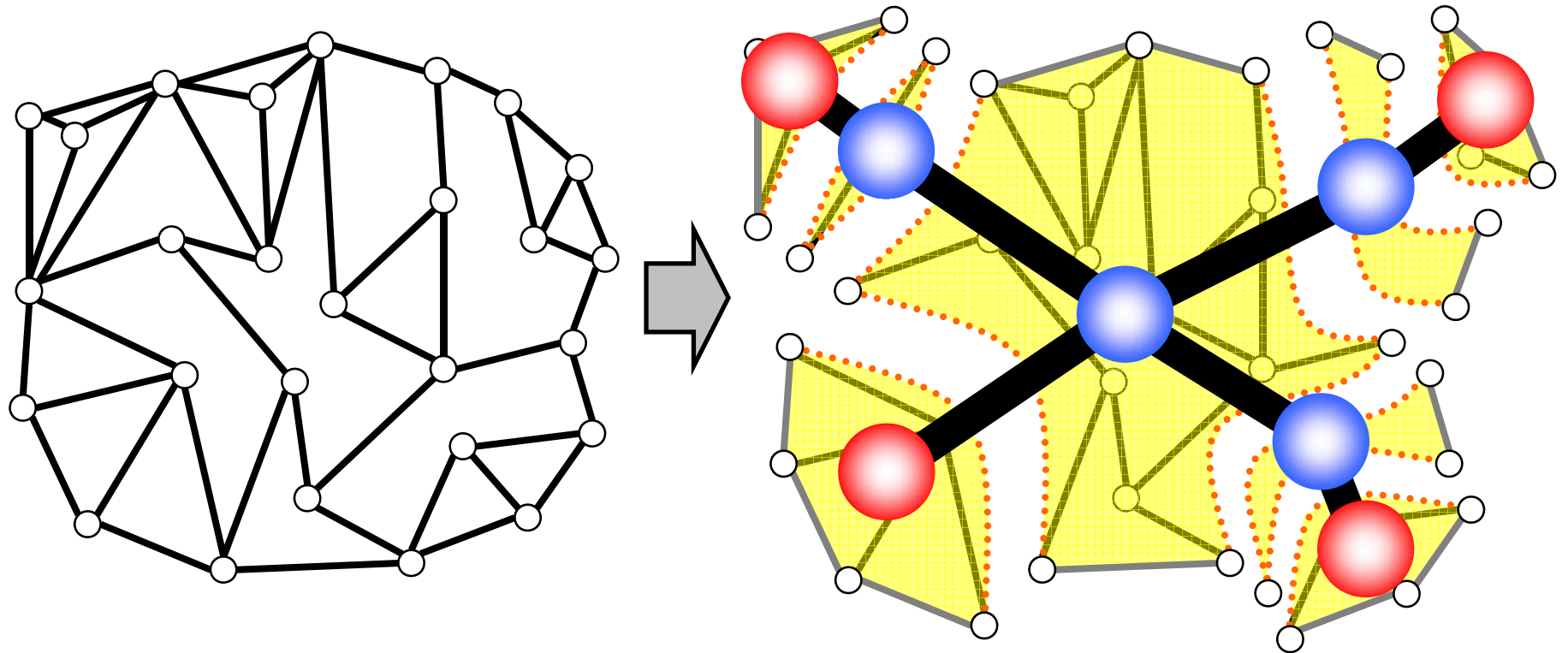
- 1) both u and v are outer vertices, and
- 2) each component of $G - \{u, v\}$ contains an outer vertex



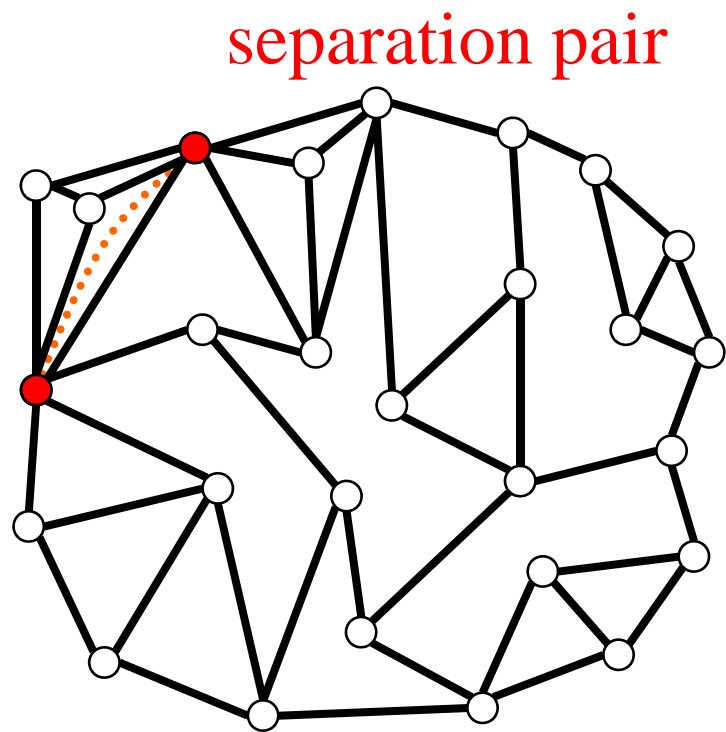
Known results (1)



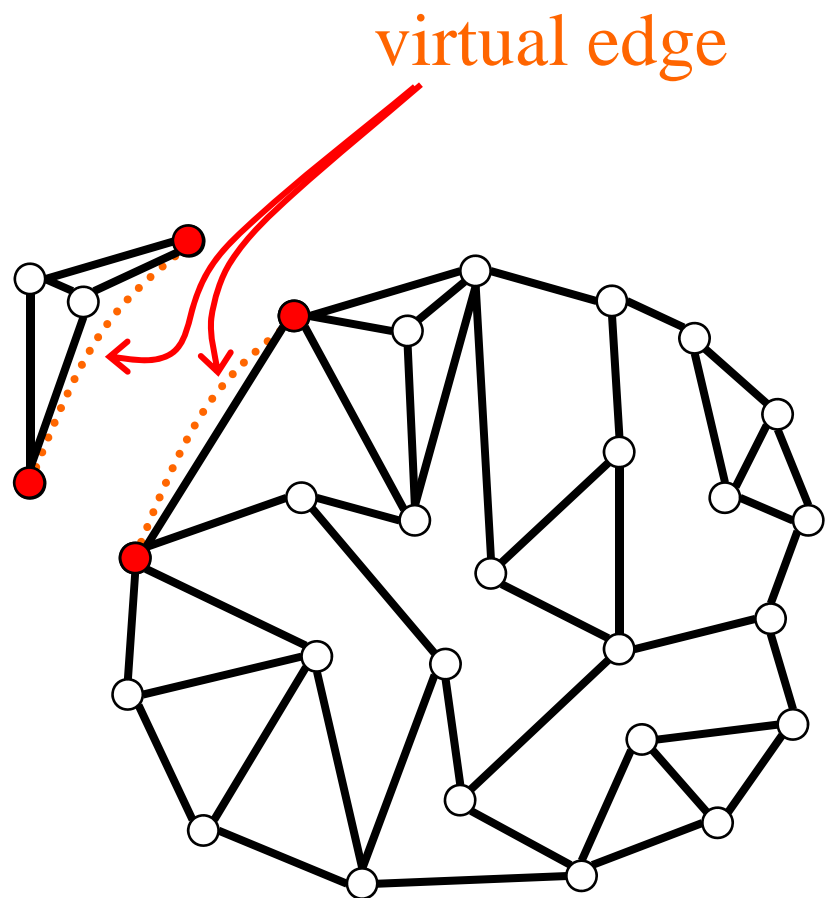
Decomposition tree



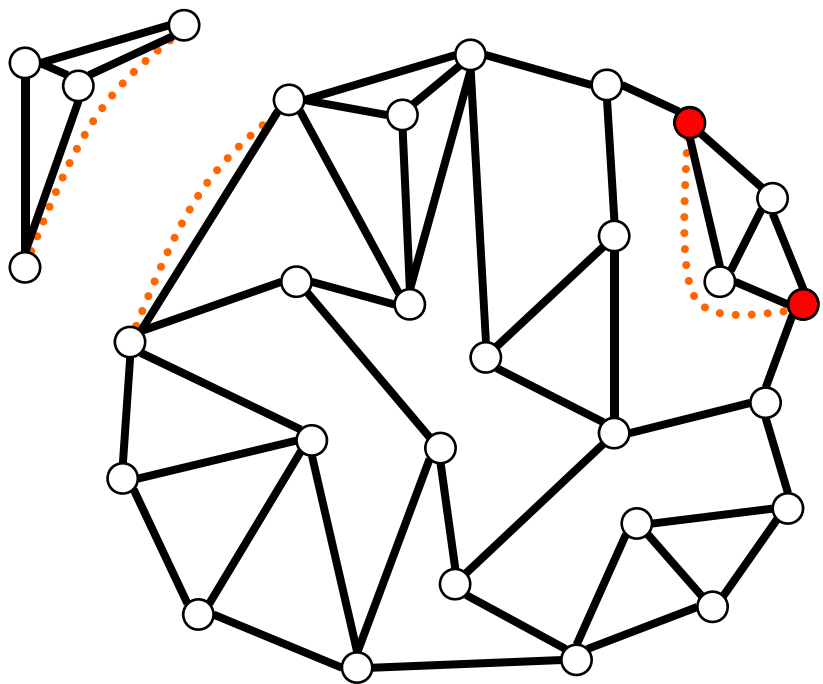
Decomposition tree



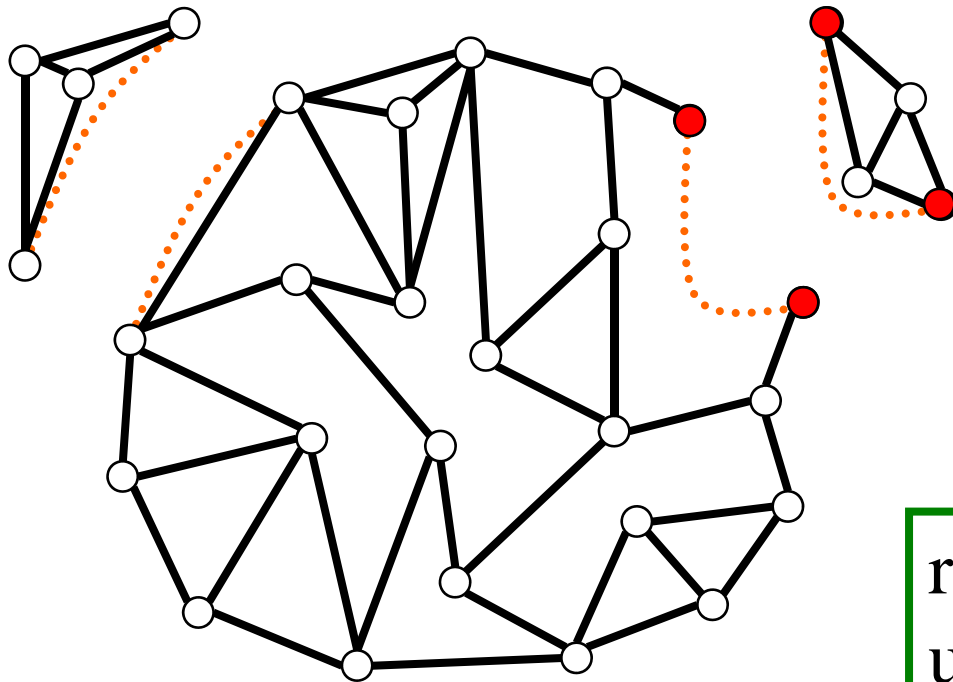
Decomposition tree



Decomposition tree

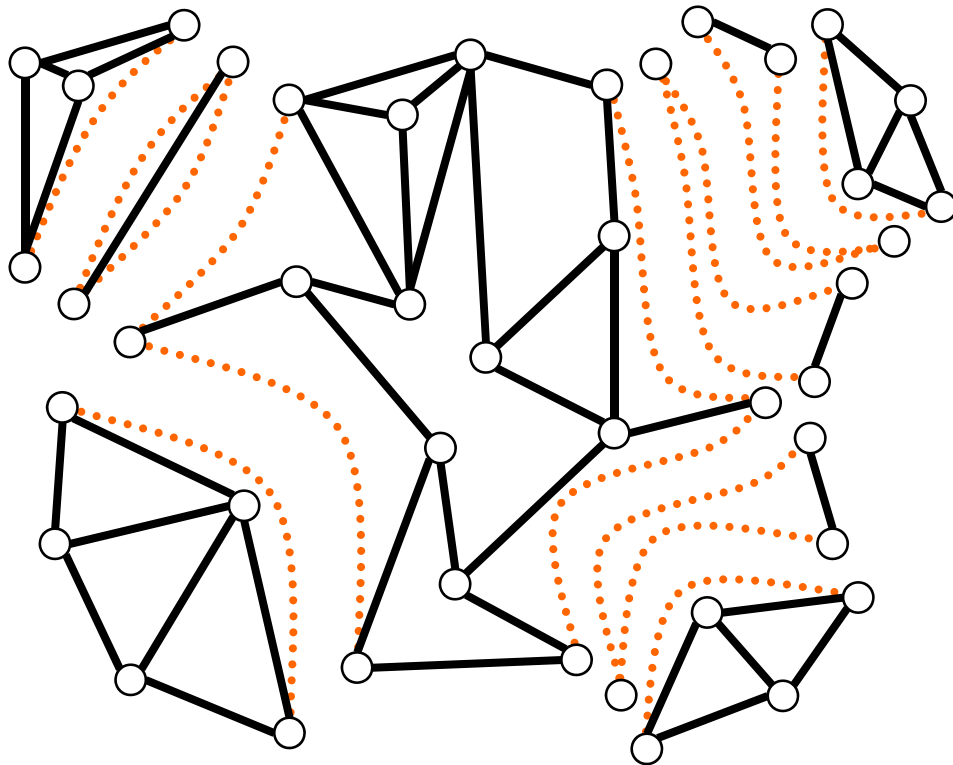


Decomposition tree



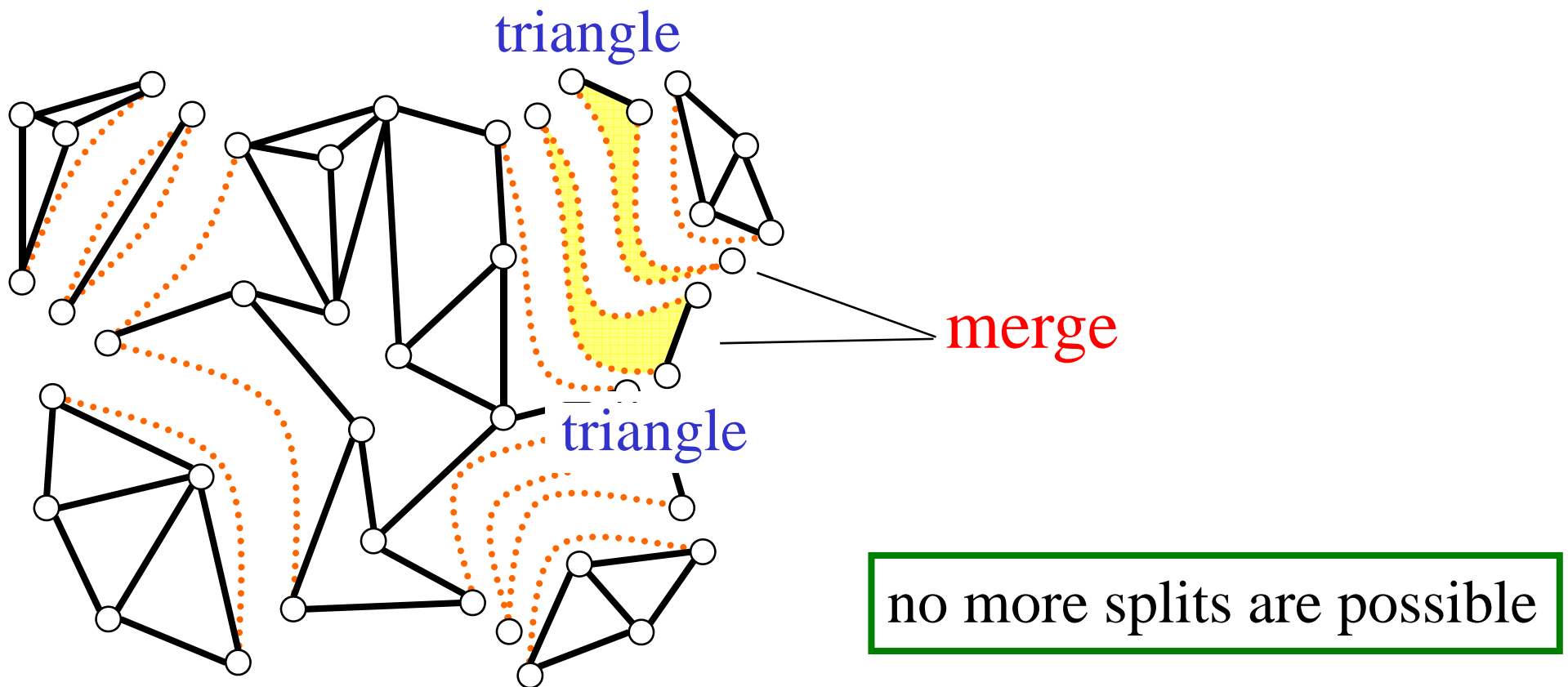
repeat this operation
until no more splits are possible

Decomposition tree

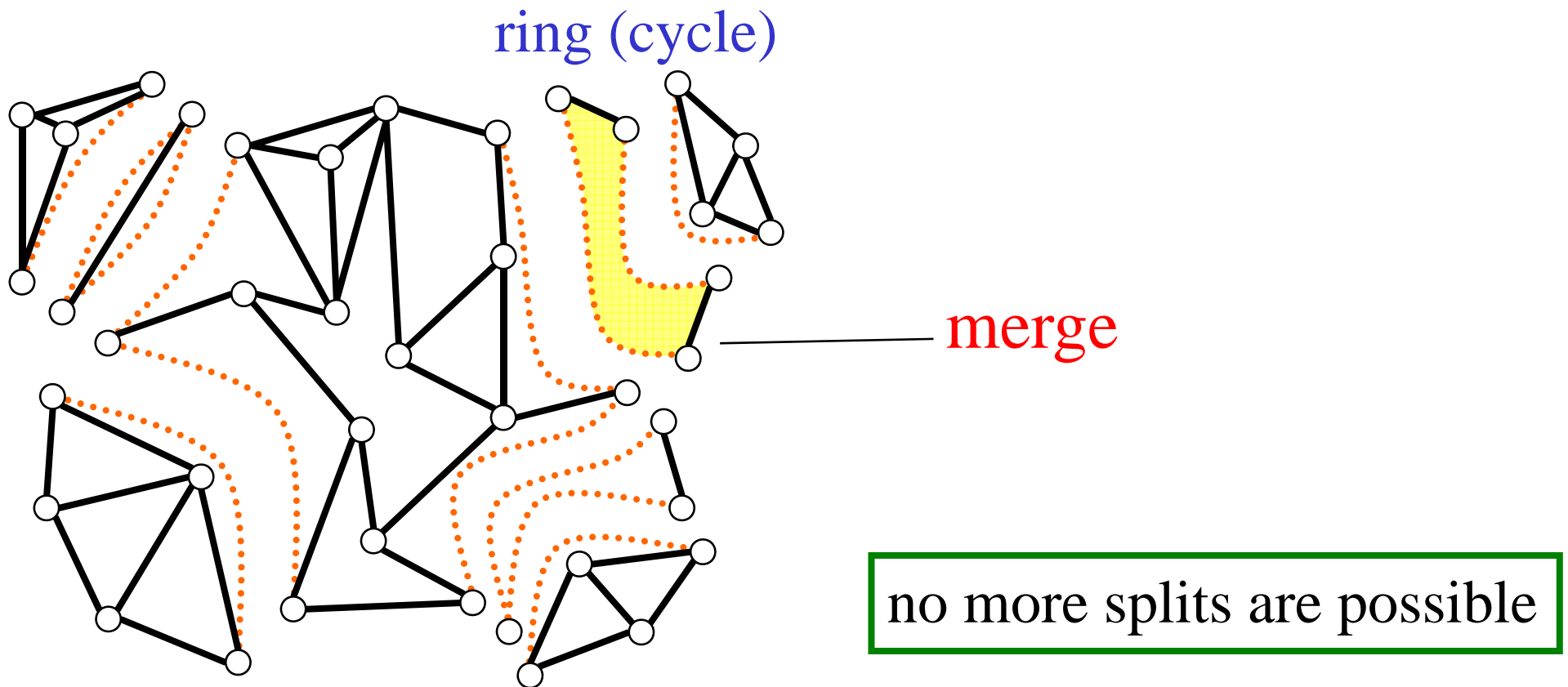


no more splits are possible

Decomposition tree

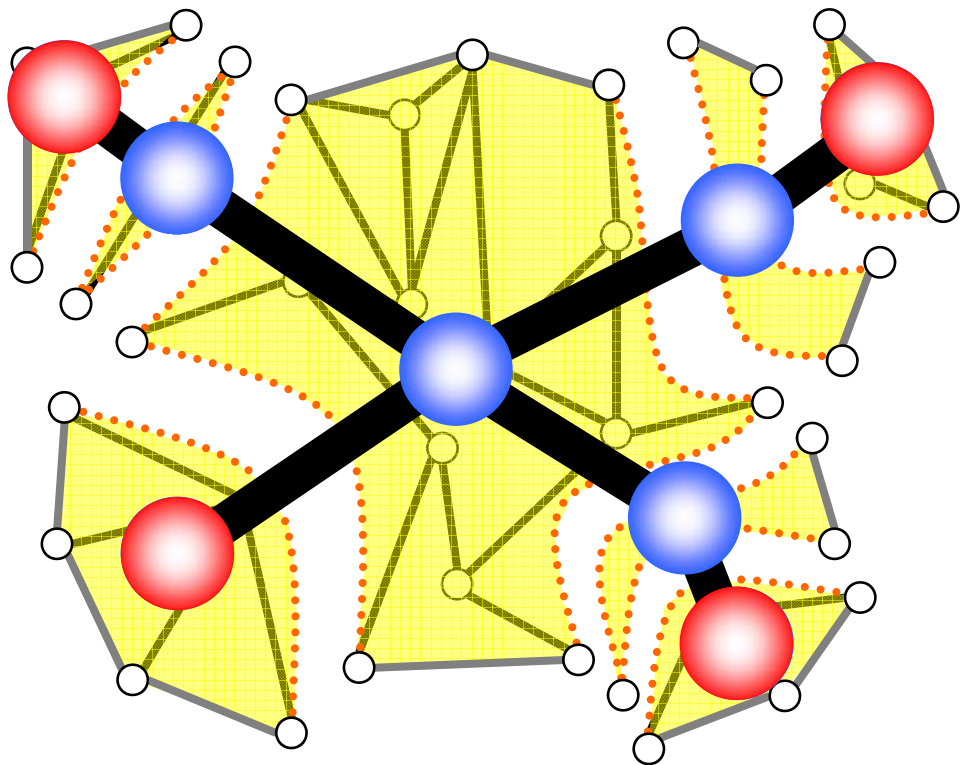


Decomposition tree



Decomposition tree

3-connected component decomposition tree [HT73]



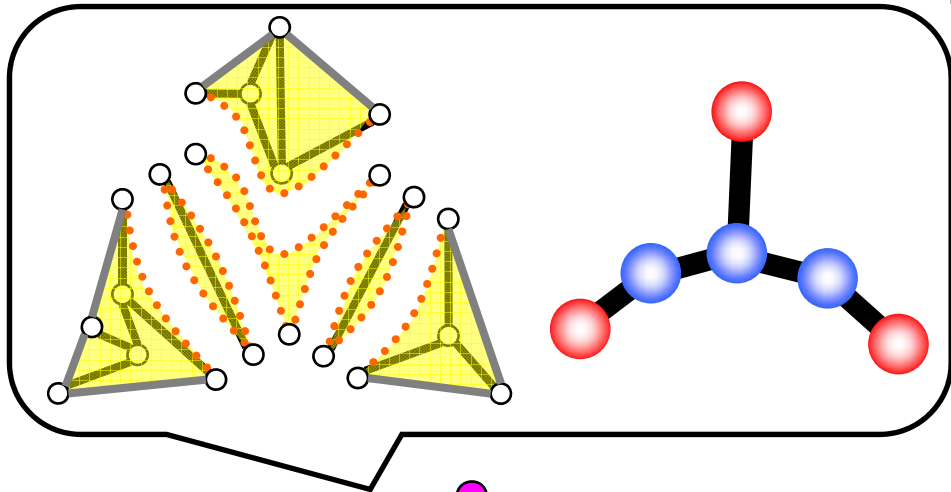
● : leaf

Known results (2)

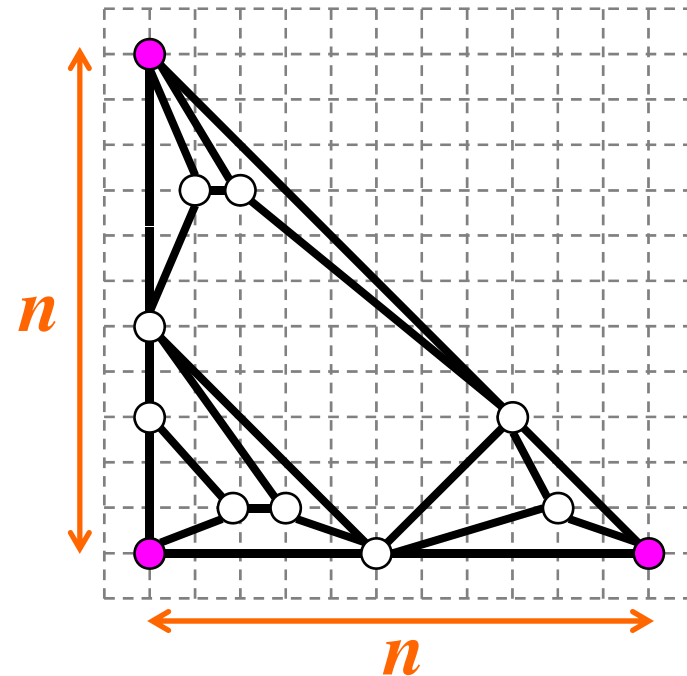
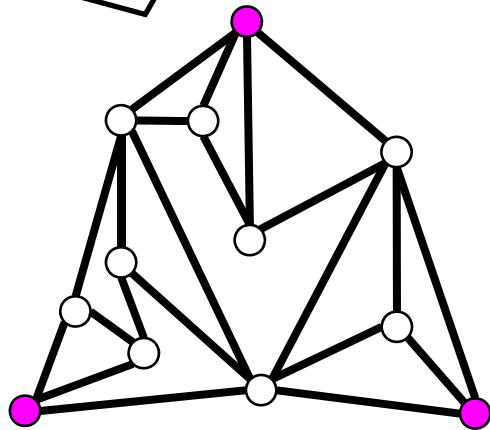
leaves ≤ 3



convex grid drawing
[CK97], [MAN05]



triangular contour



n vertices

Known results (2)

internally 3-connected

leaves ≥ 4 : open problem

leaves ≤ 3

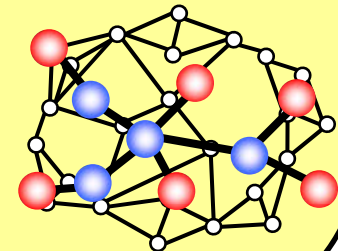
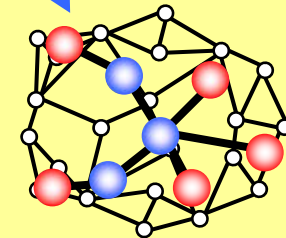
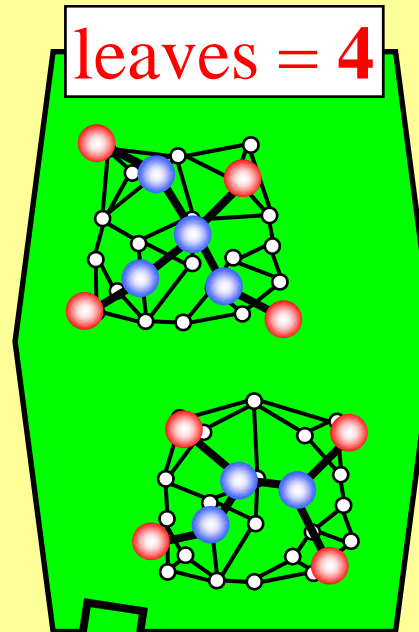
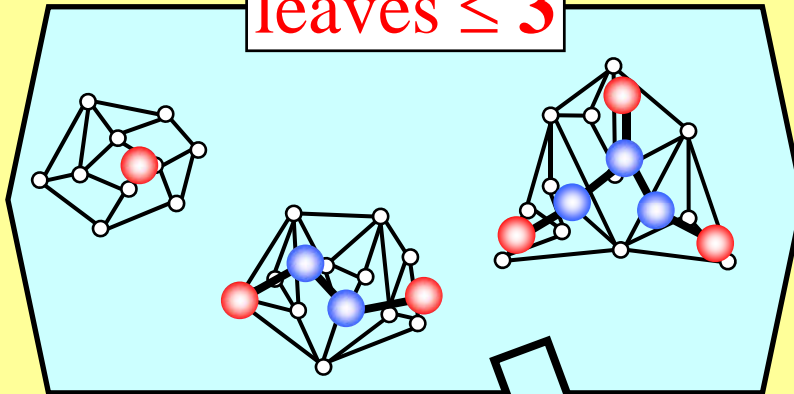
leaves = 4

known results (2)

our result

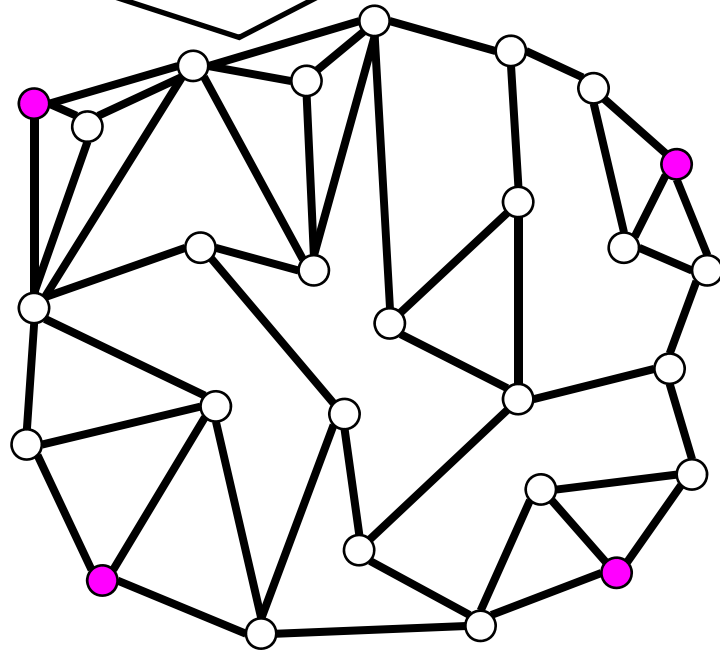
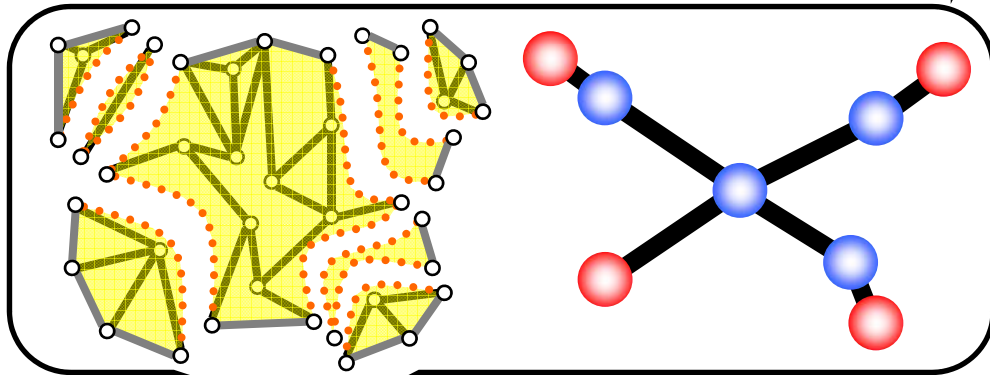
convex grid drawing

polynomial size



Our result

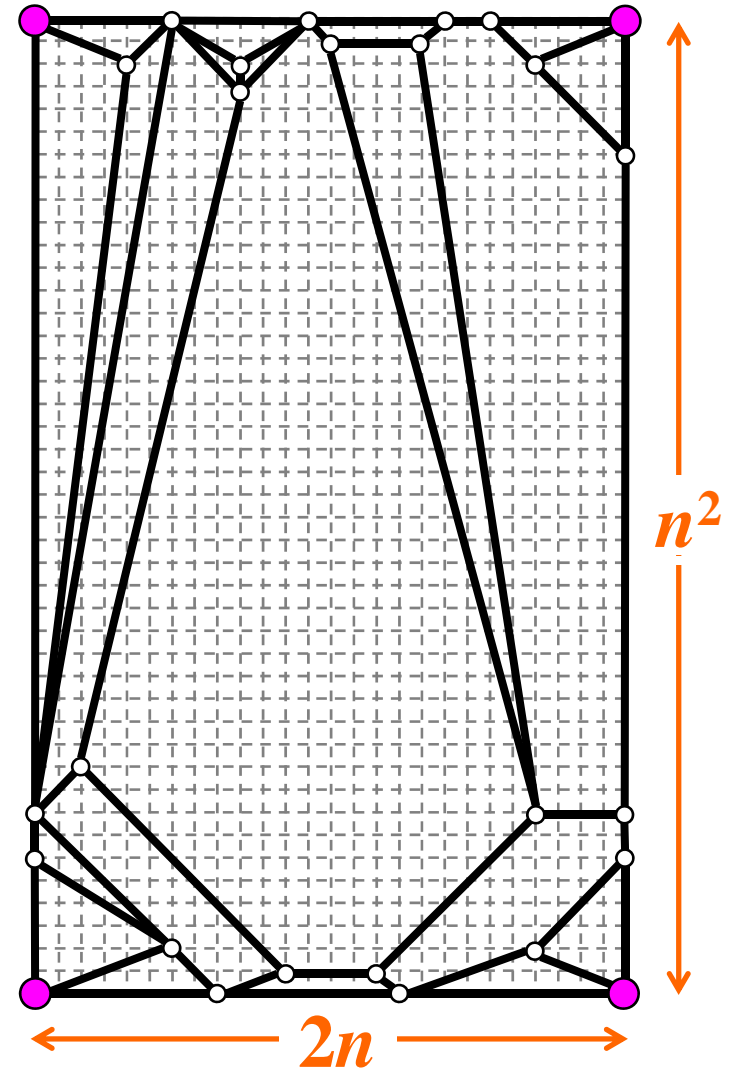
leaves = 4



n vertices

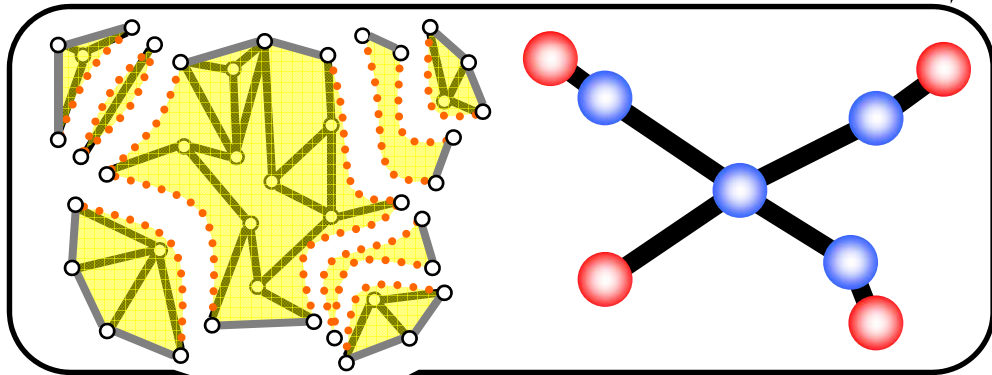
rectangular contour

convex grid drawing



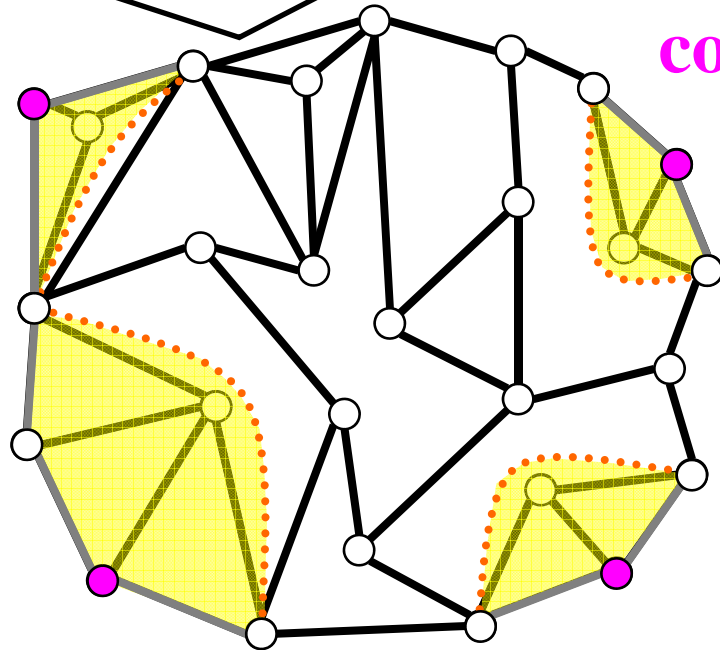
Our result

leaves = 4

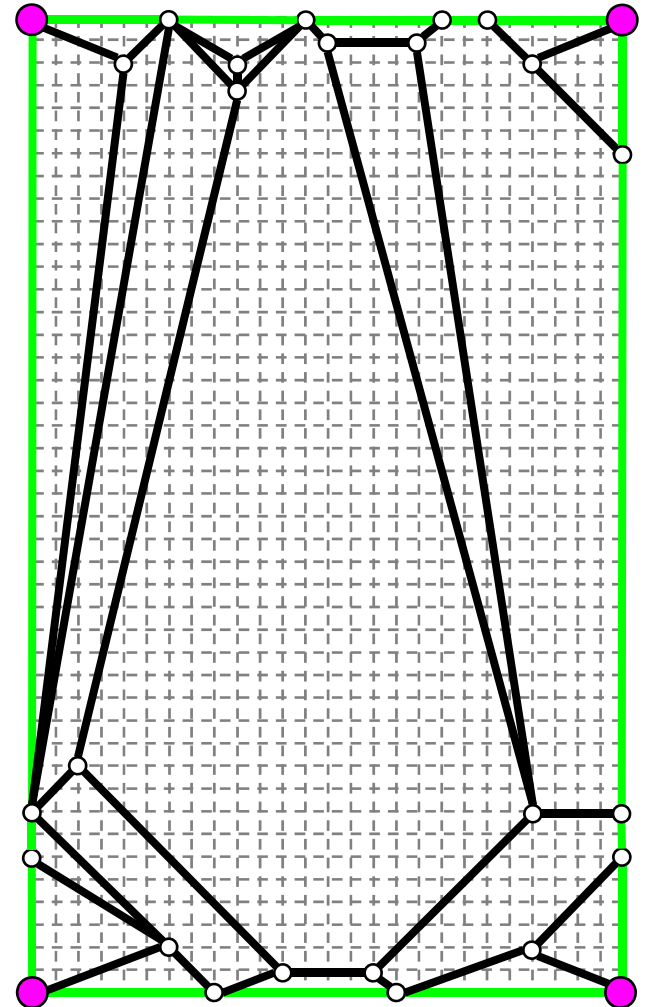


rectangular contour

convex grid drawing

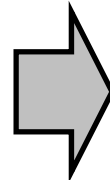
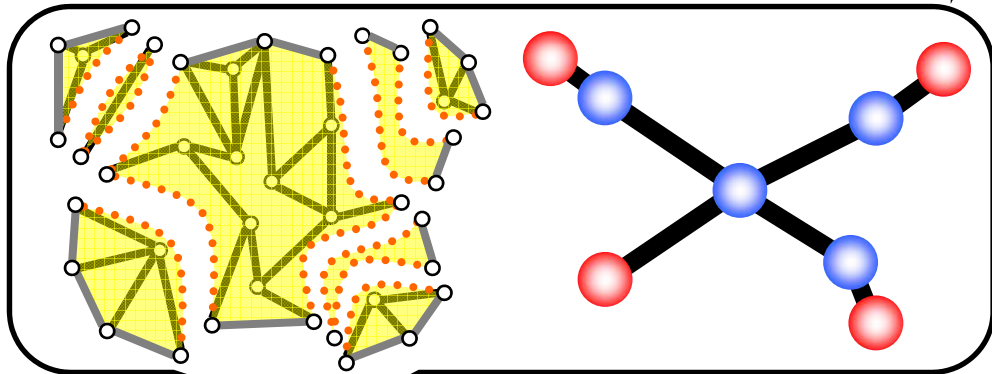


corner vertex

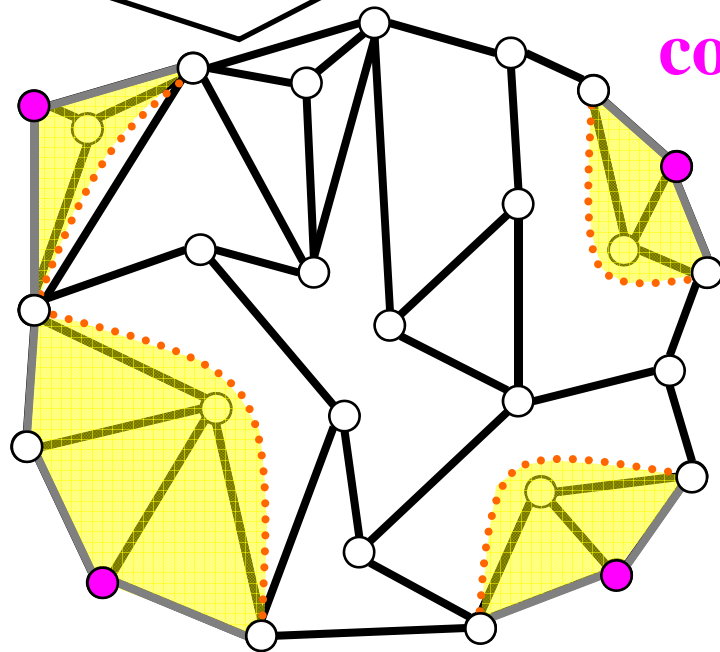
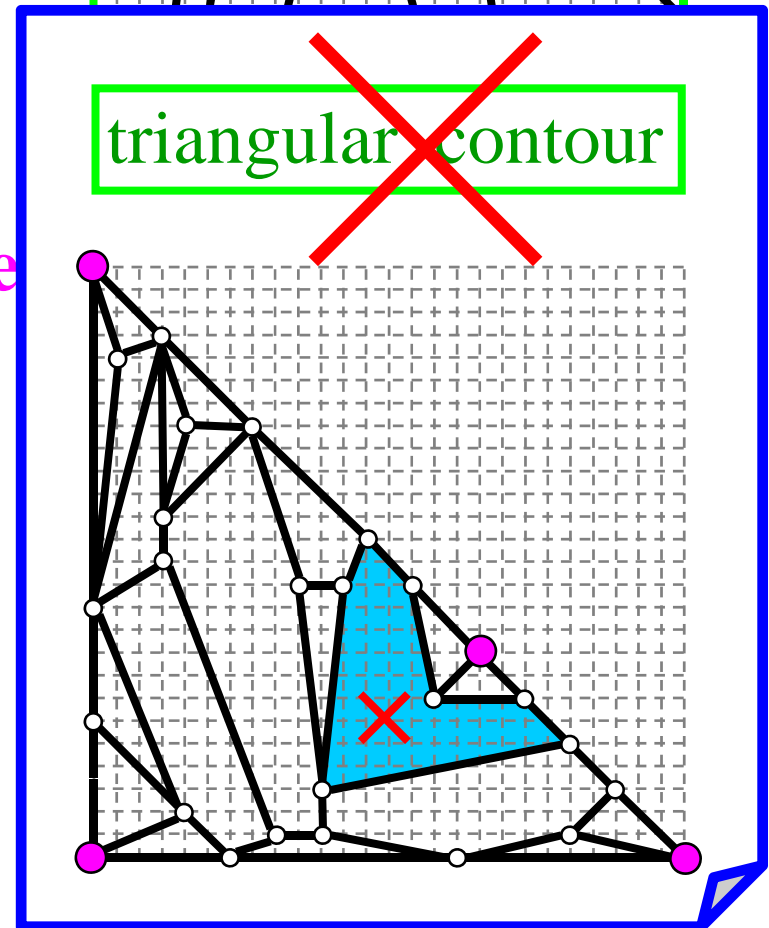
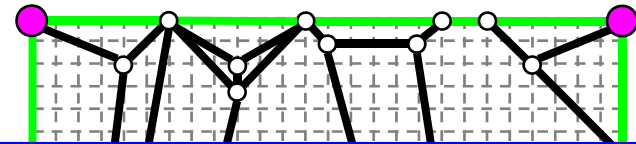


Our result

leaves = 4



rectangular contour
convex grid drawing

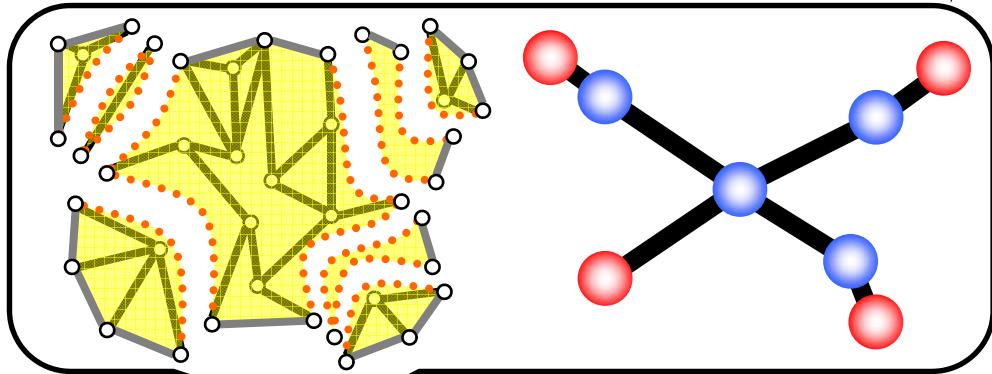


corner verte

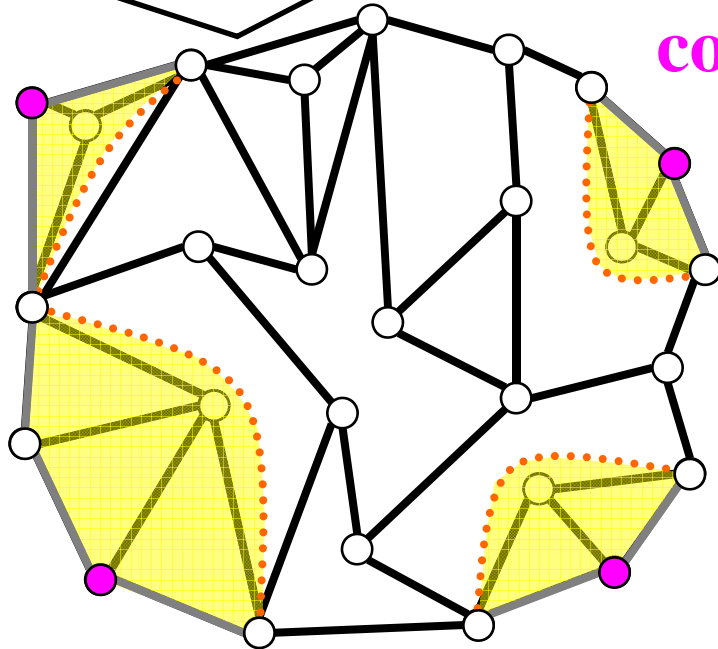


Our result

leaves = 4

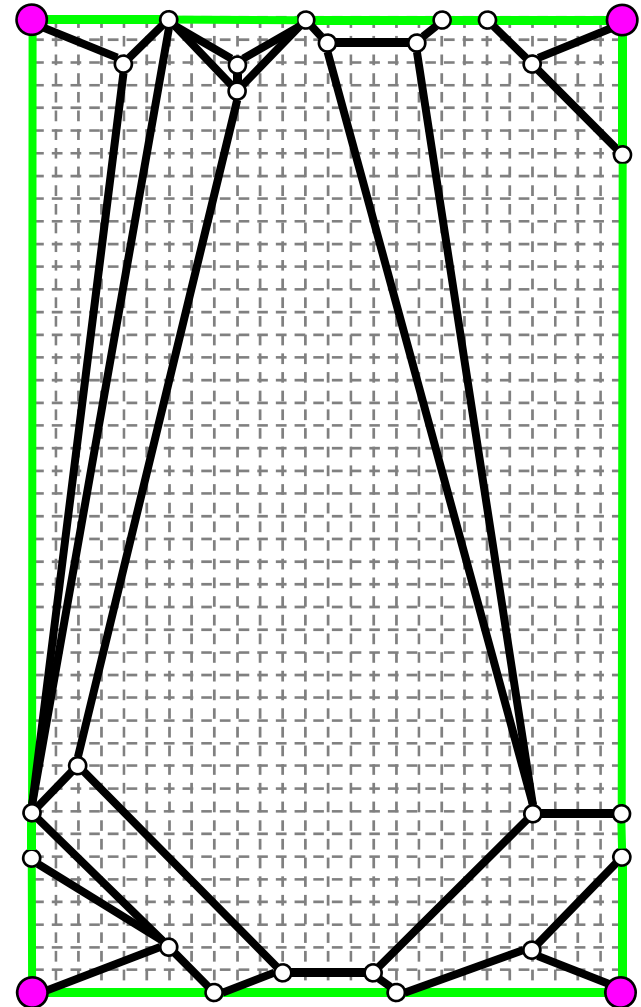


corner vertex



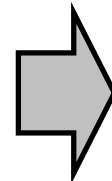
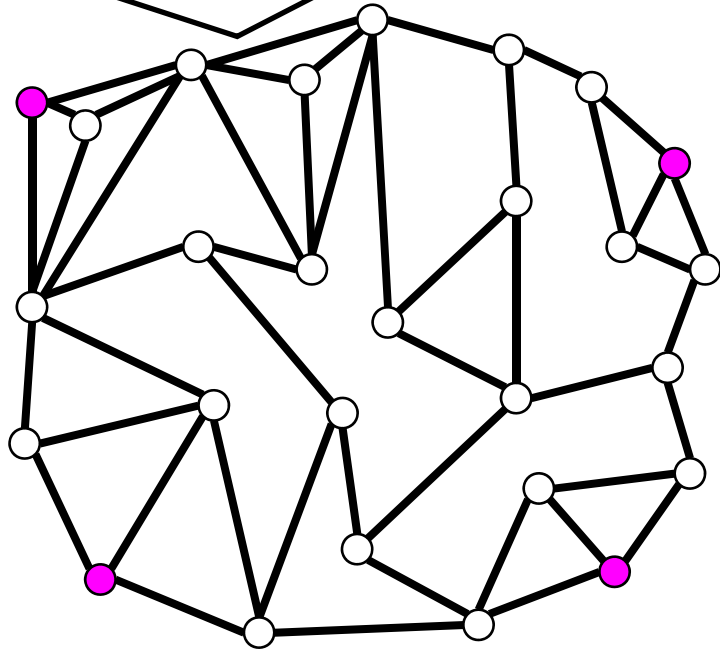
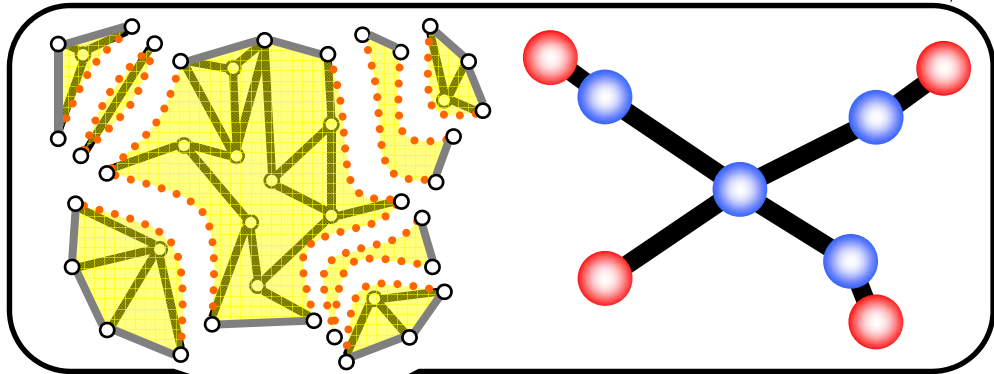
rectangular contour

convex grid drawing

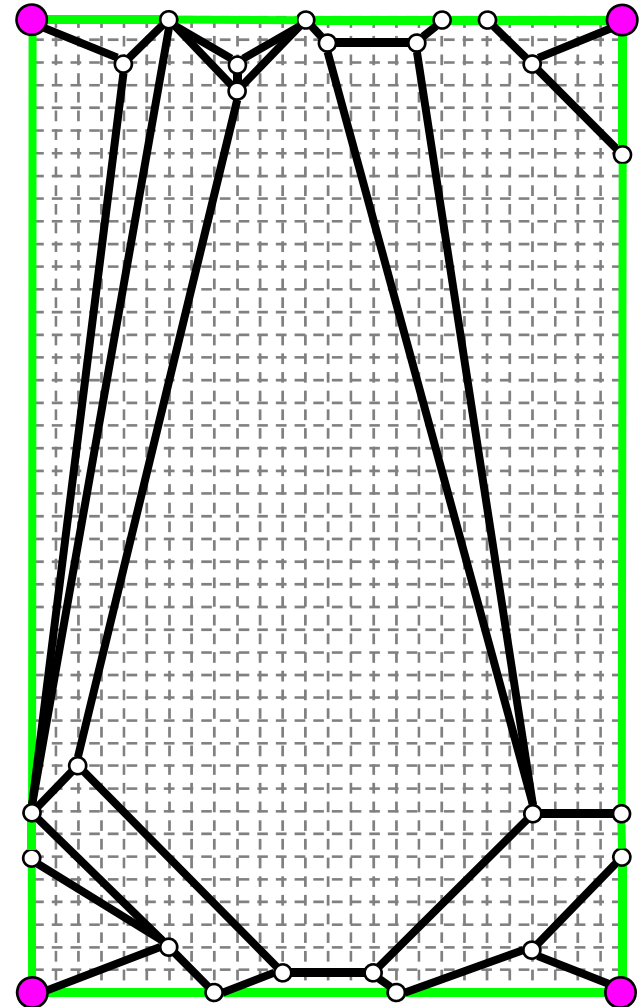


Our result

leaves = 4

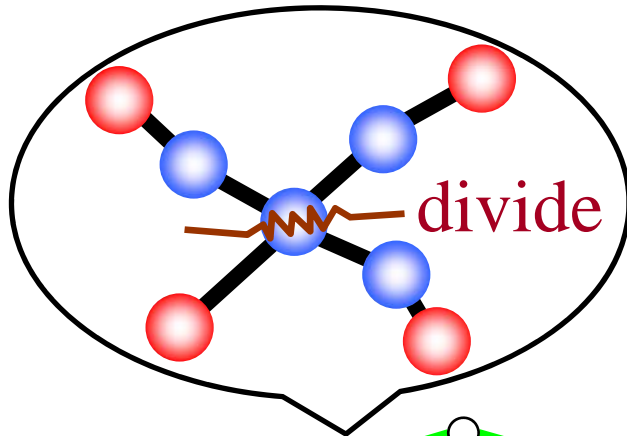


convex grid drawing



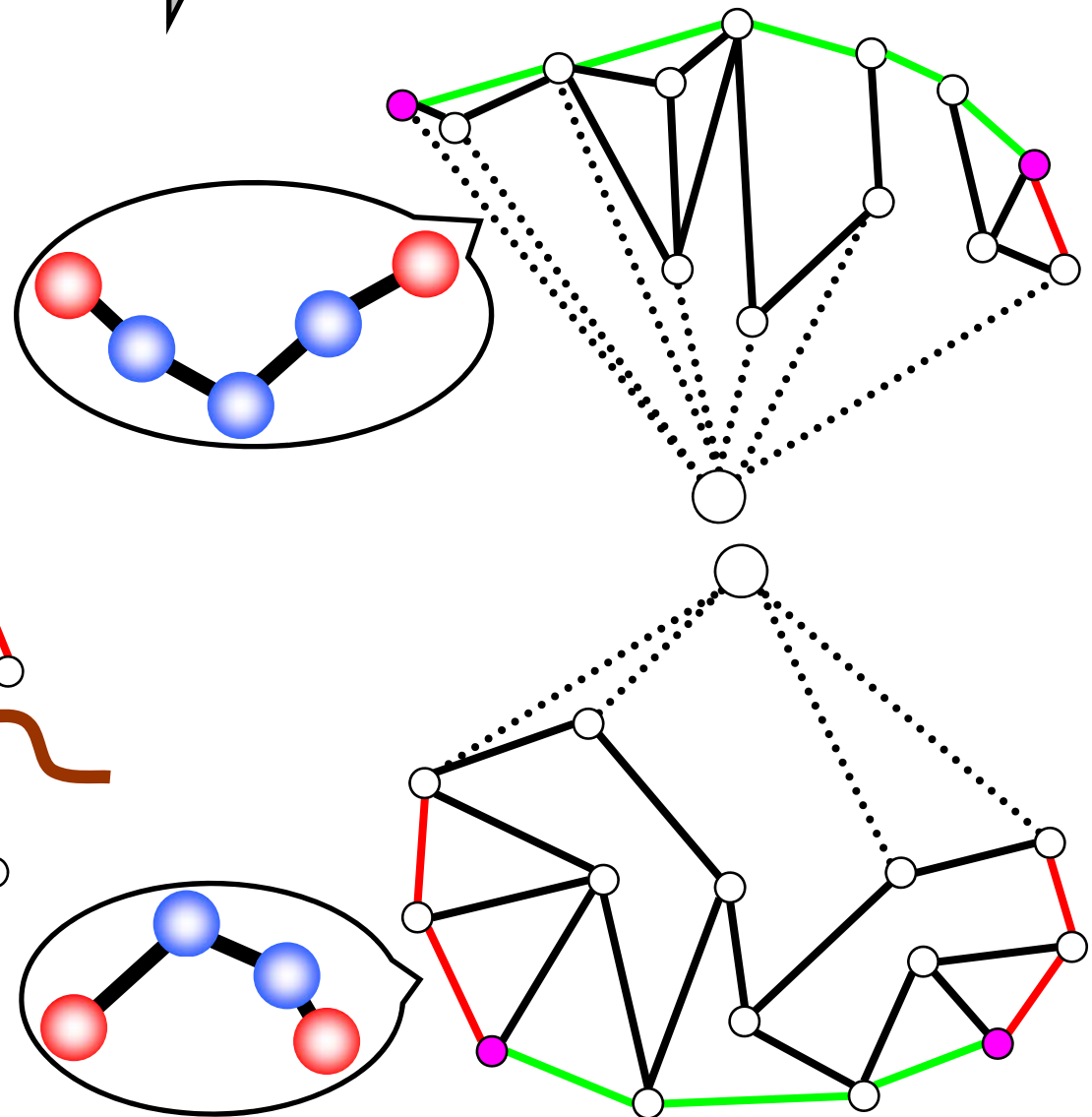
Main idea

leaves = 4



internally 3-connected graphs

leaves = 2



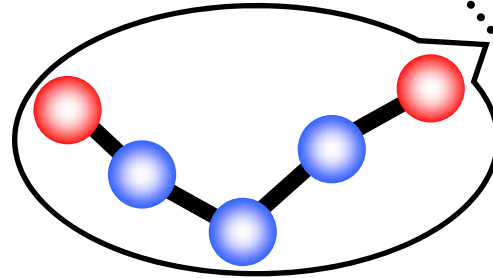
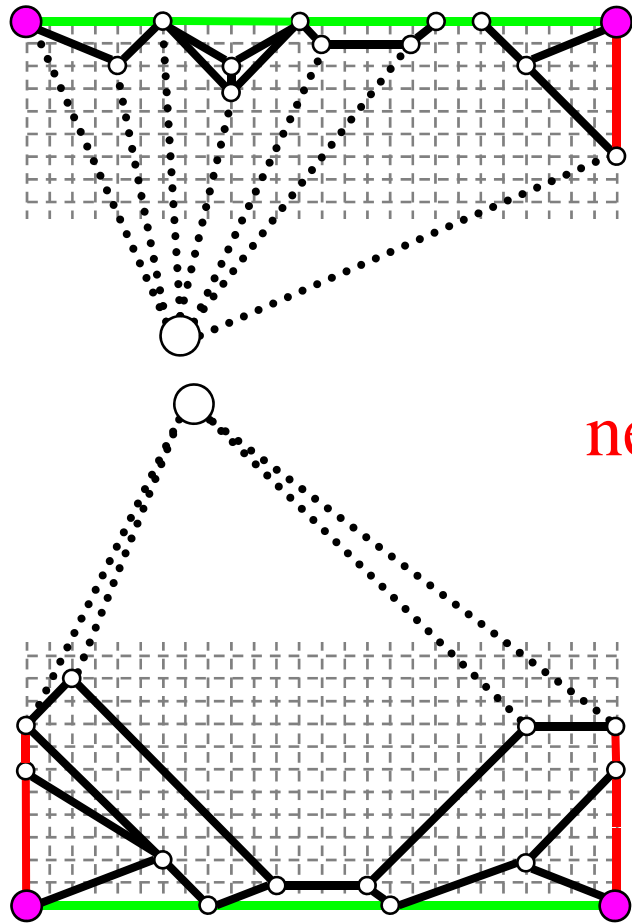
Main idea

inner convex grid drawings

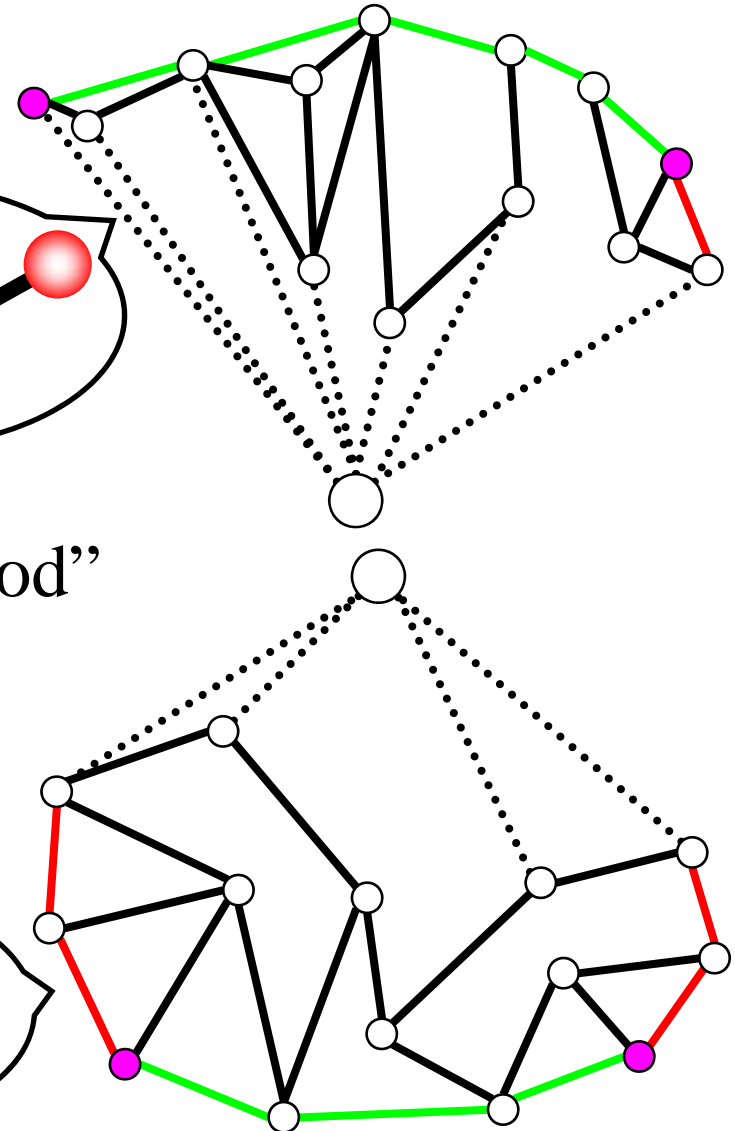
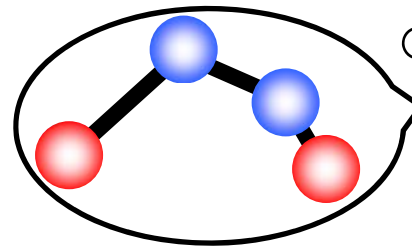


internally 3-connected graphs

leaves = 2

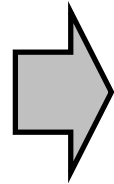


new "shift method"

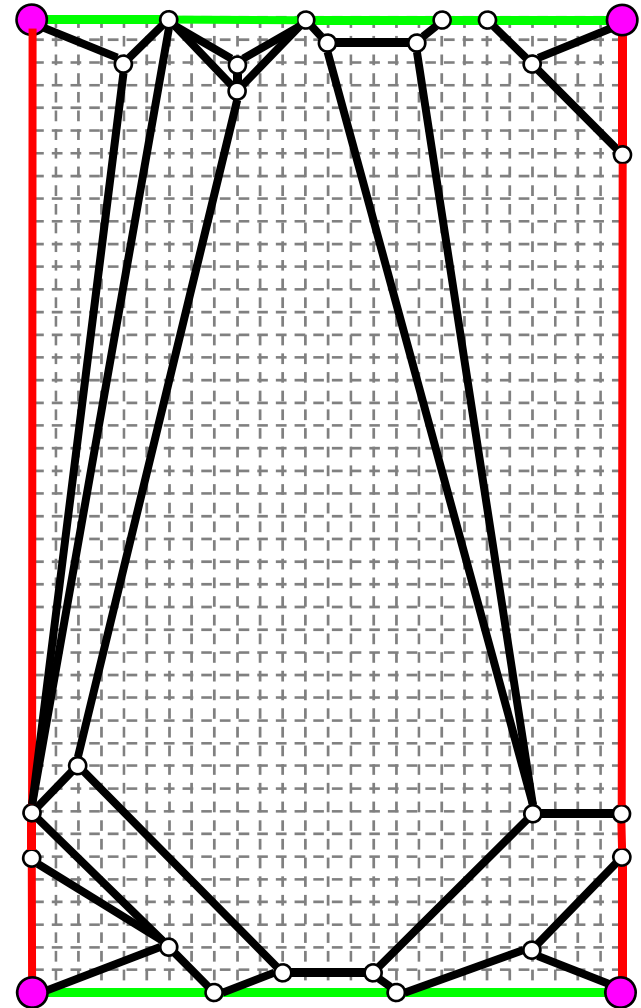
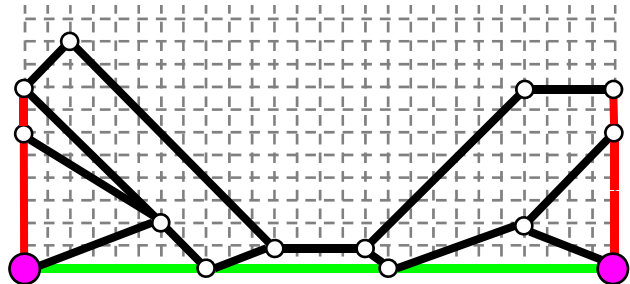
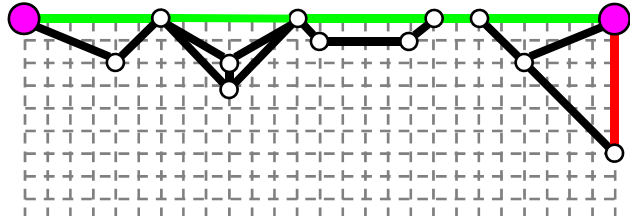


Main idea

inner convex grid drawings

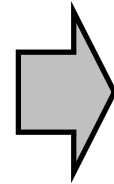


convex grid drawing

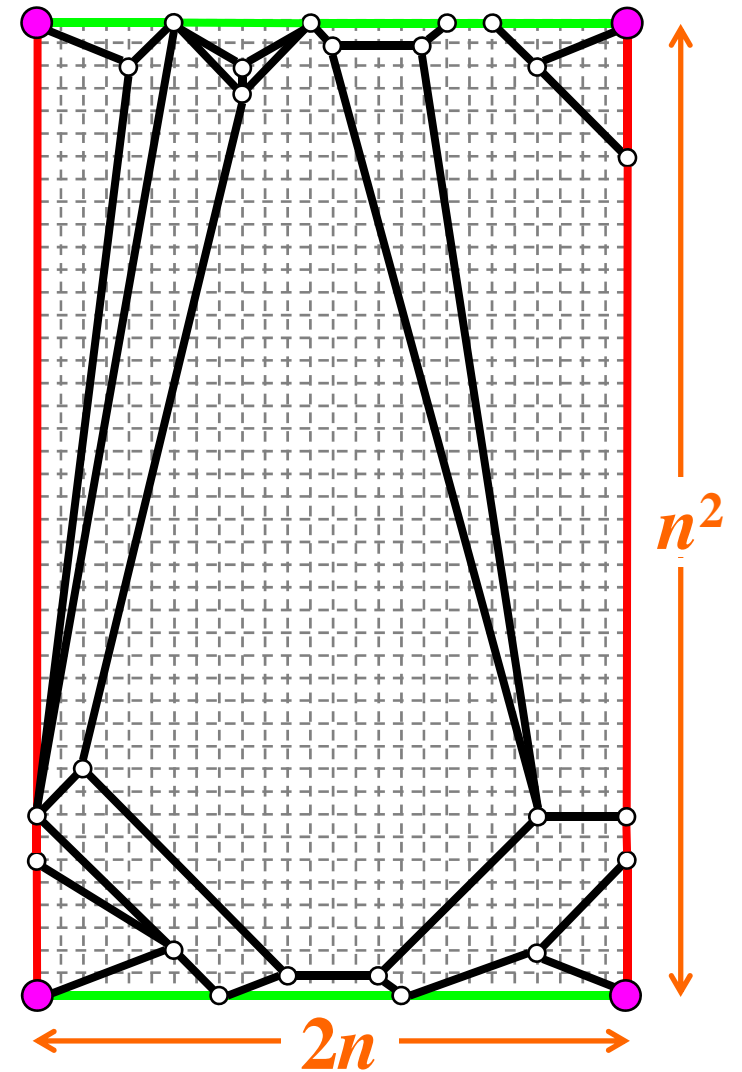
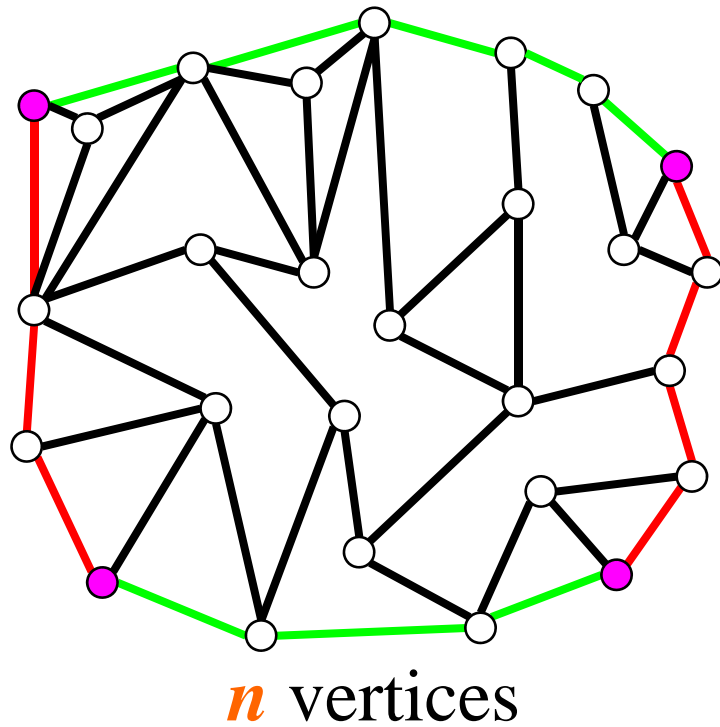


Main idea

input graph

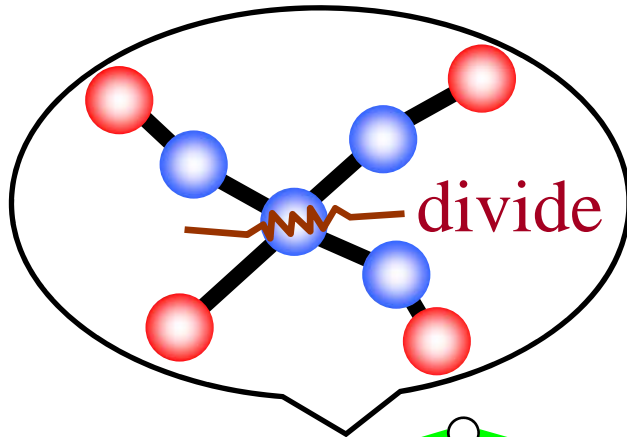


convex grid drawing



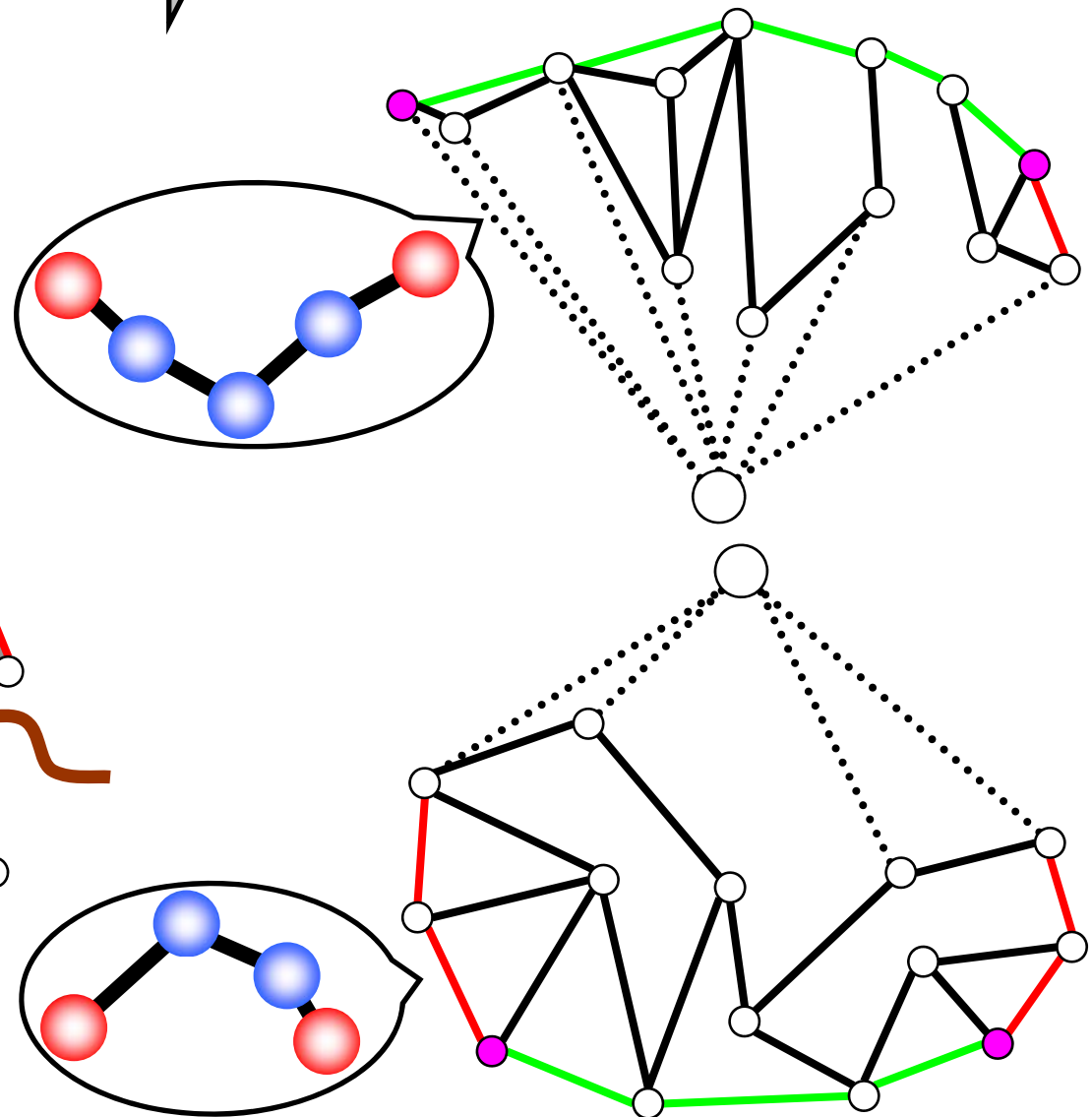
Algorithm

leaves = 4



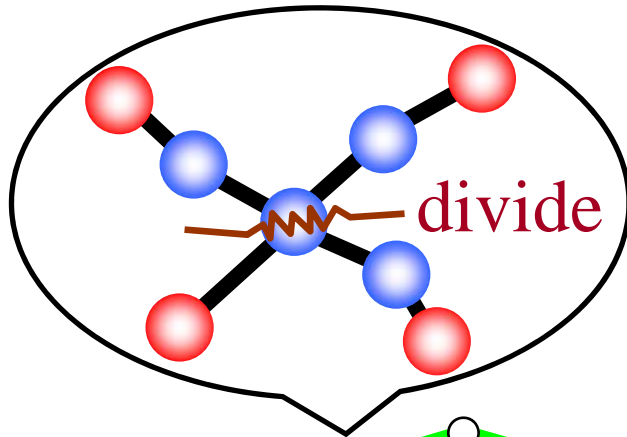
internally 3-connected graphs

leaves = 2



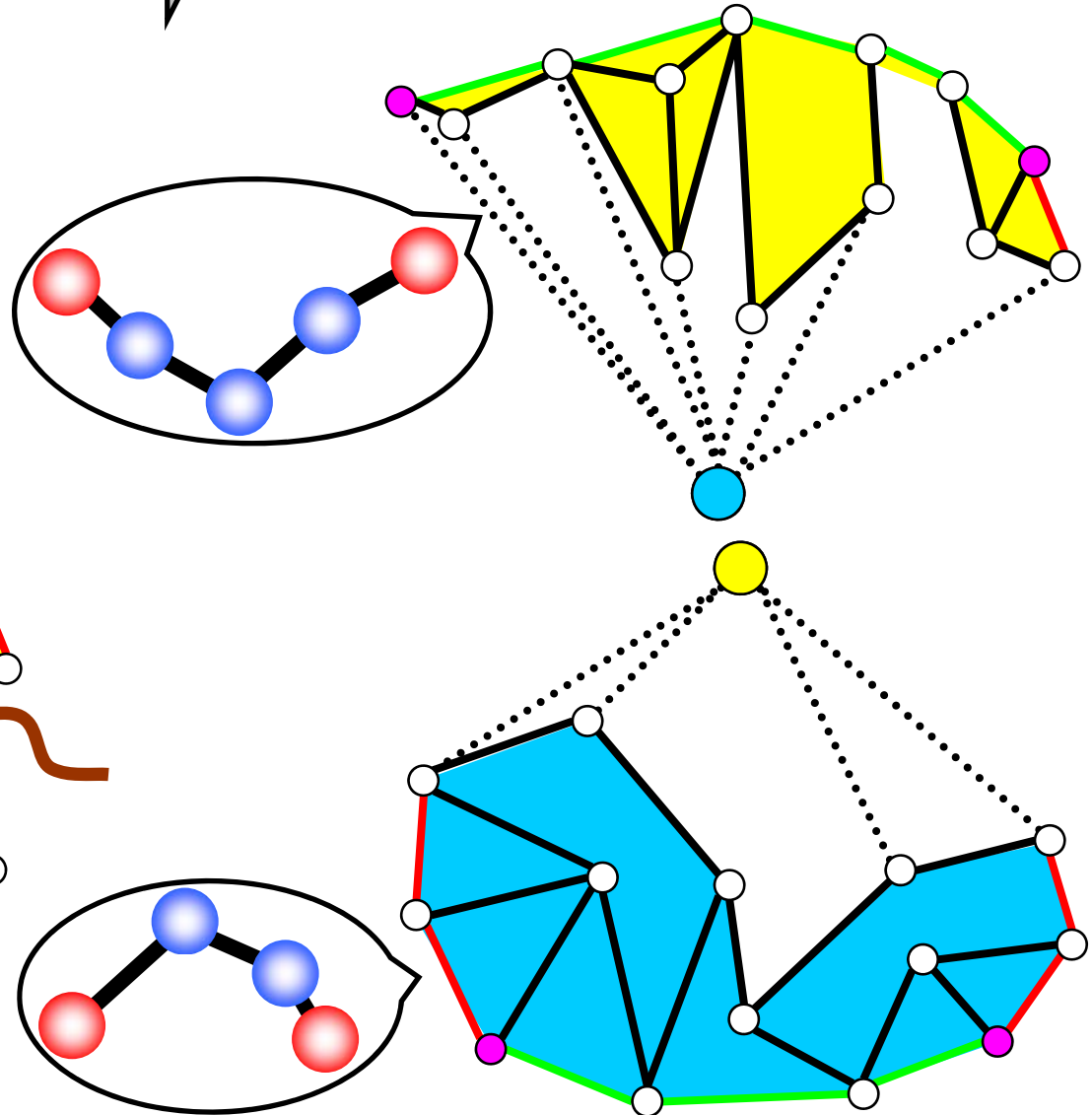
Algorithm

leaves = 4



internally 3-connected graphs

leaves = 2



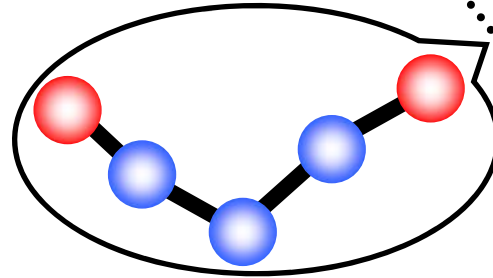
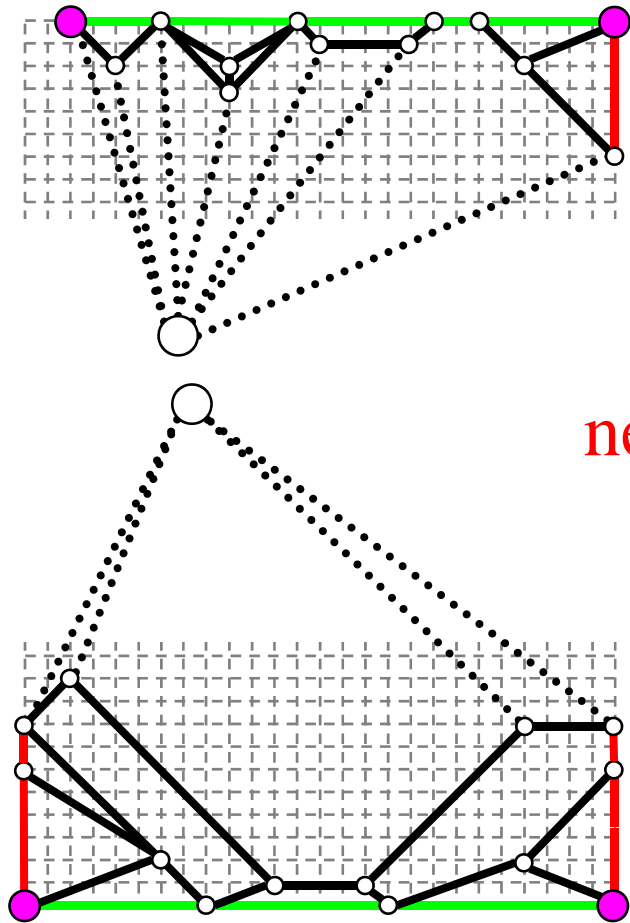
Algorithm

inner convex grid drawings

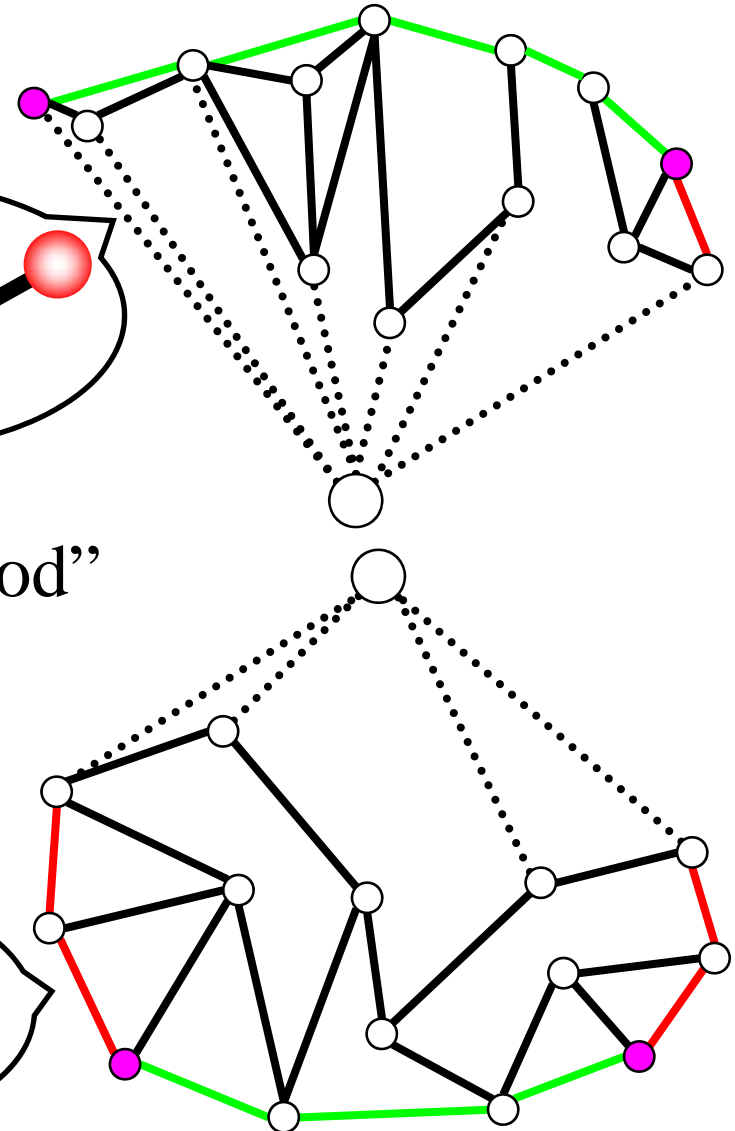
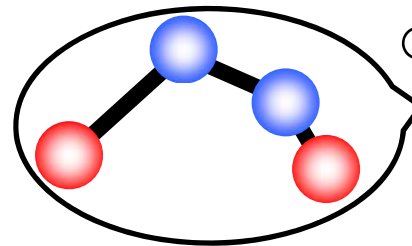


internally 3-connected graphs

leaves = 2



new “shift method”



Algorithm

inner convex grid drawing



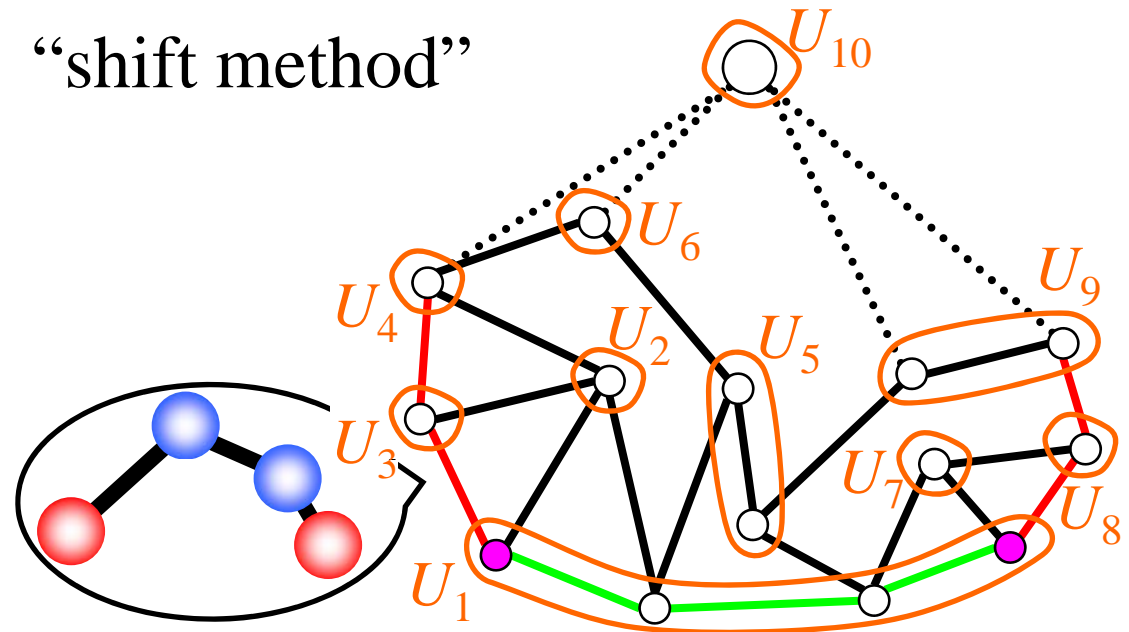
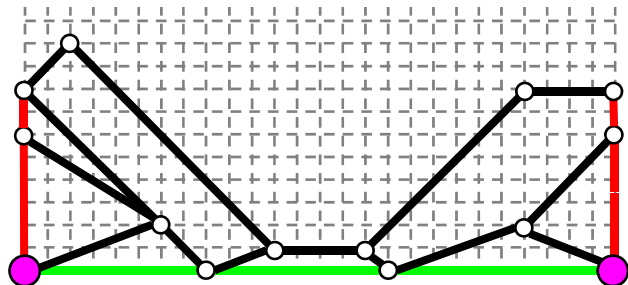
internally 3-connected graph

leaves = 2

canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

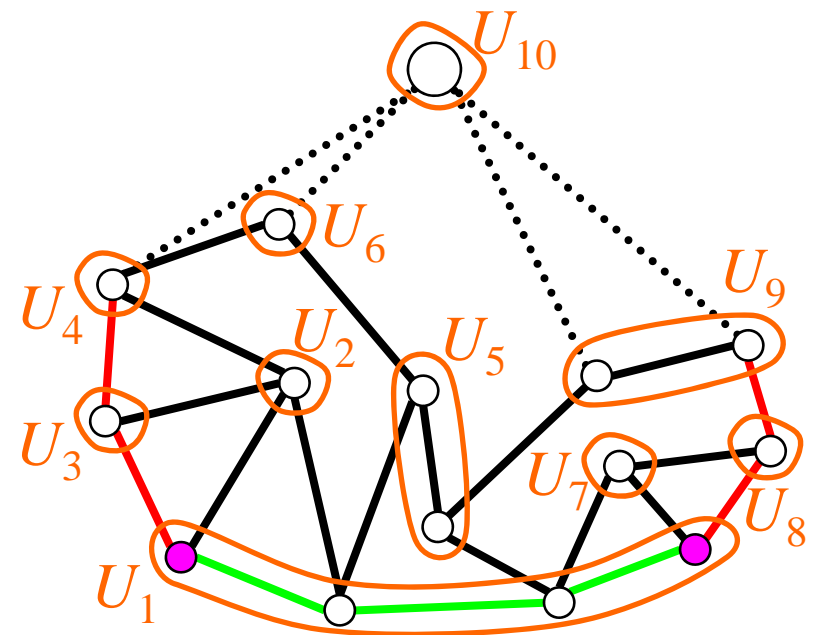
new “shift method”



Canonical decomposition

canonical decomposition

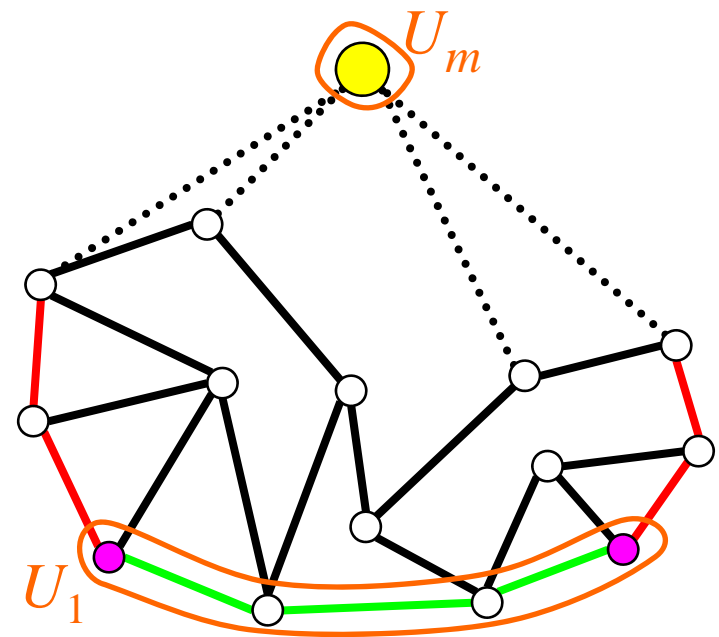
$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$



Canonical decomposition

canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

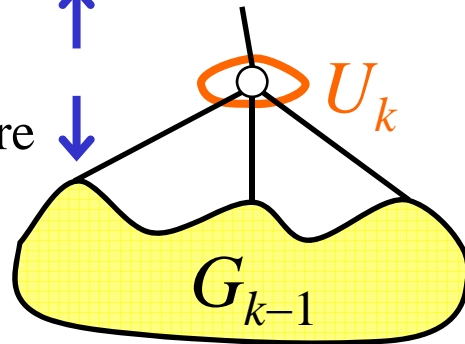


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

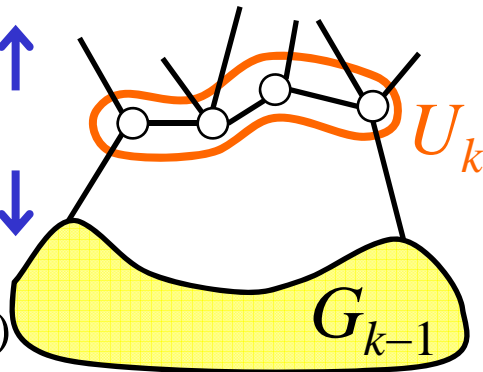
one or more
(each vertex)



exactly one

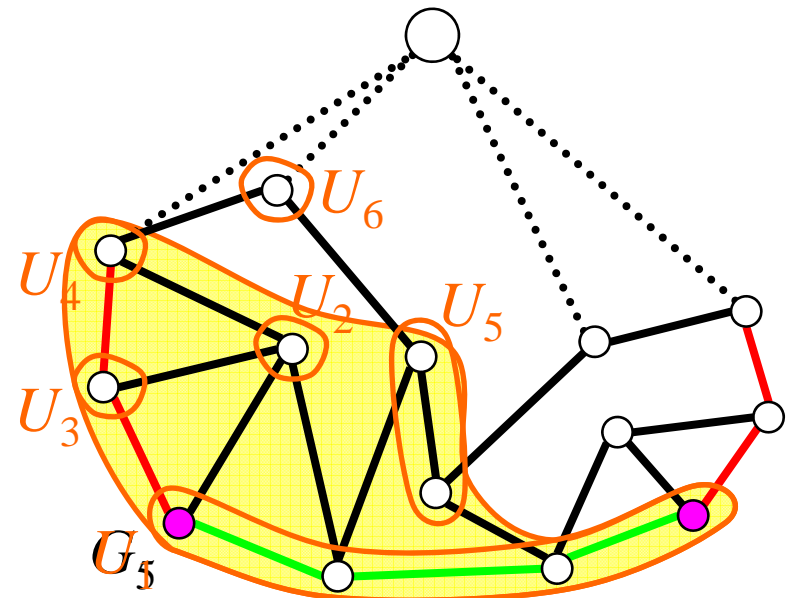


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

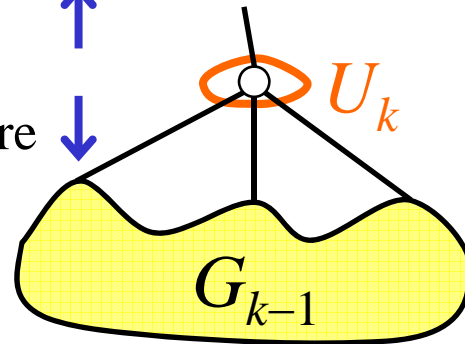


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

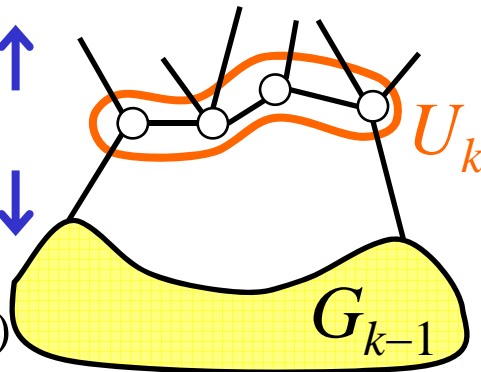
one or more
(each vertex)



exactly one

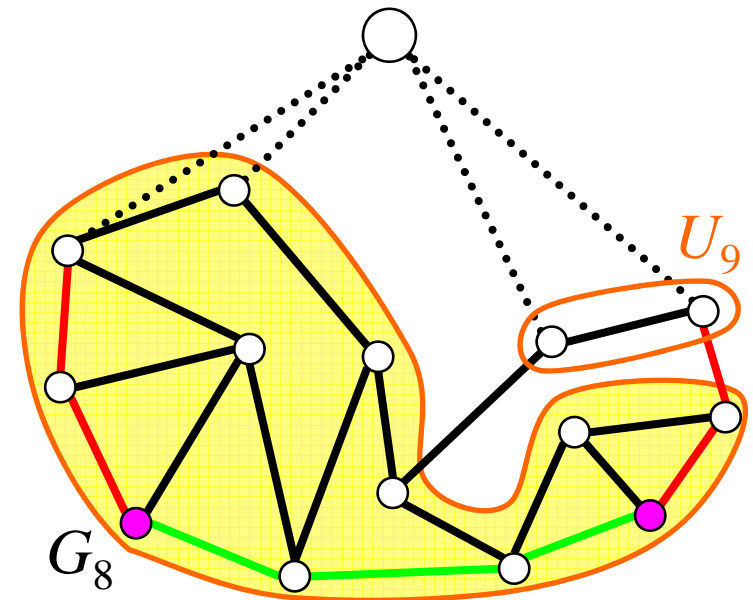


(leftmost and
rightmost vertices)

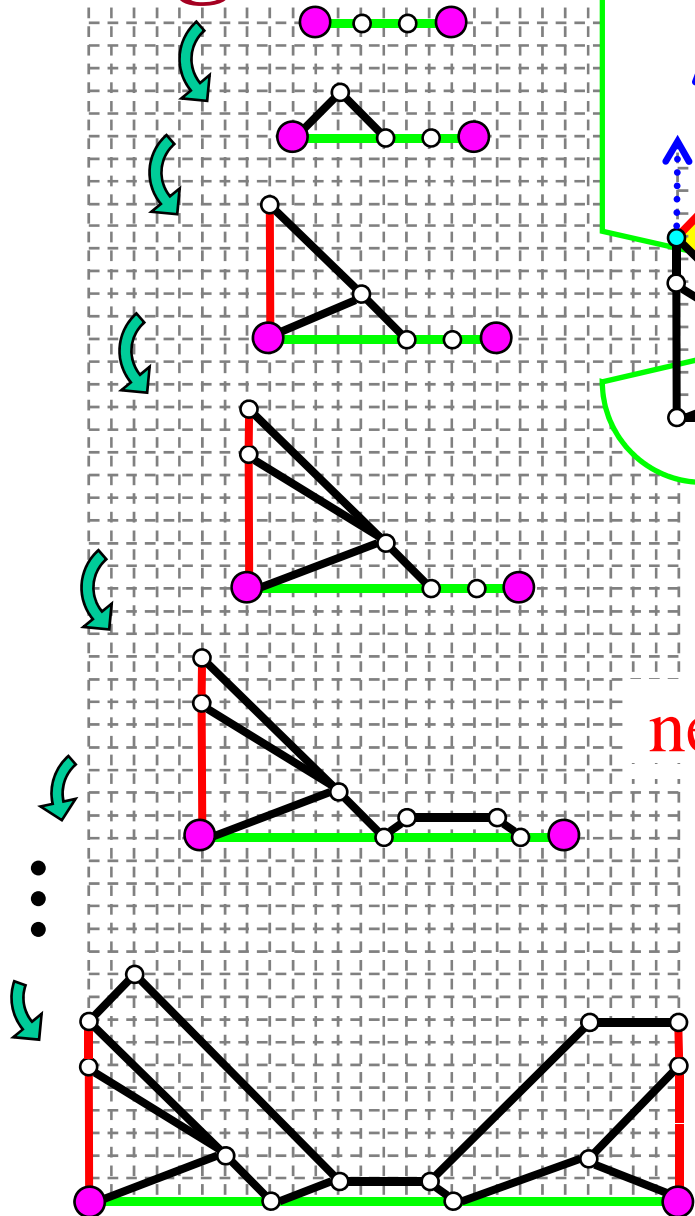


G_k is induced by

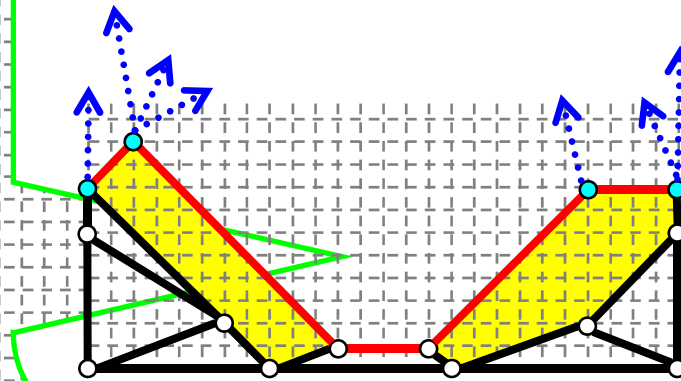
$$U_1 \cup U_2 \cup \dots \cup U_k$$



Algorithm



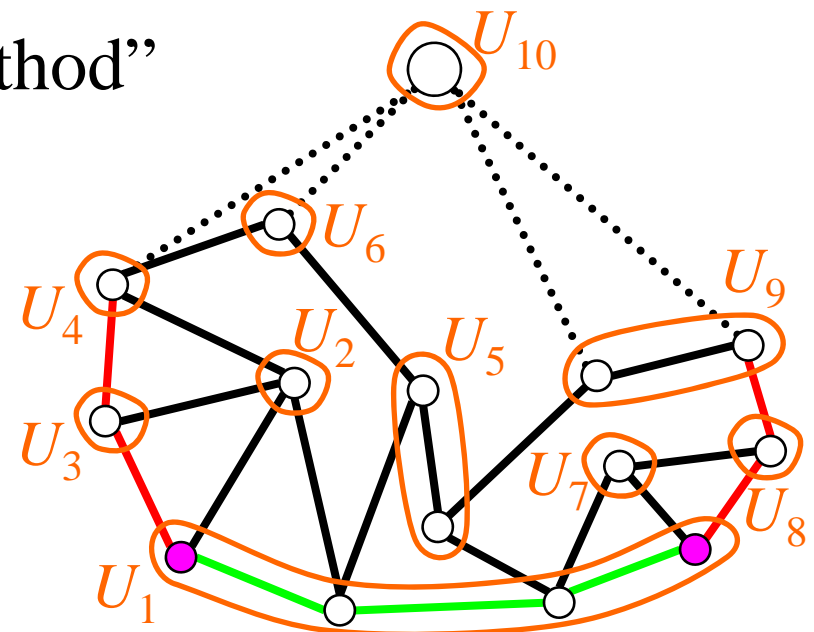
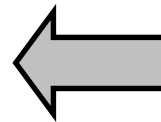
③ convex apex ● has upper neighbors



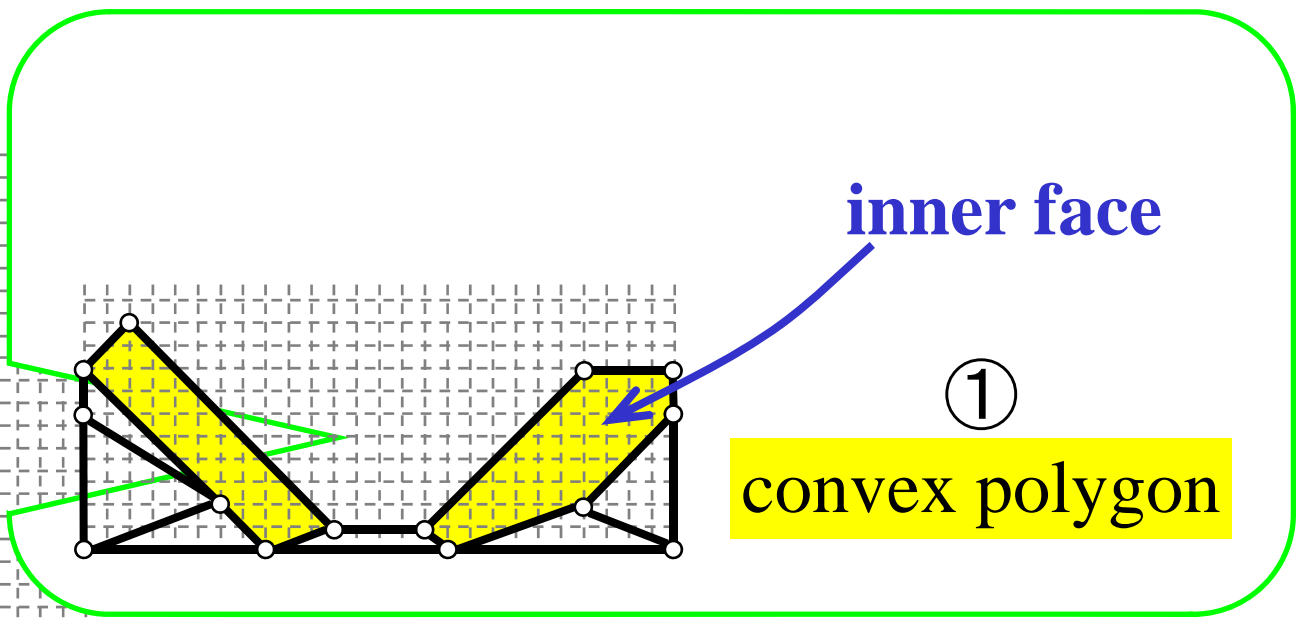
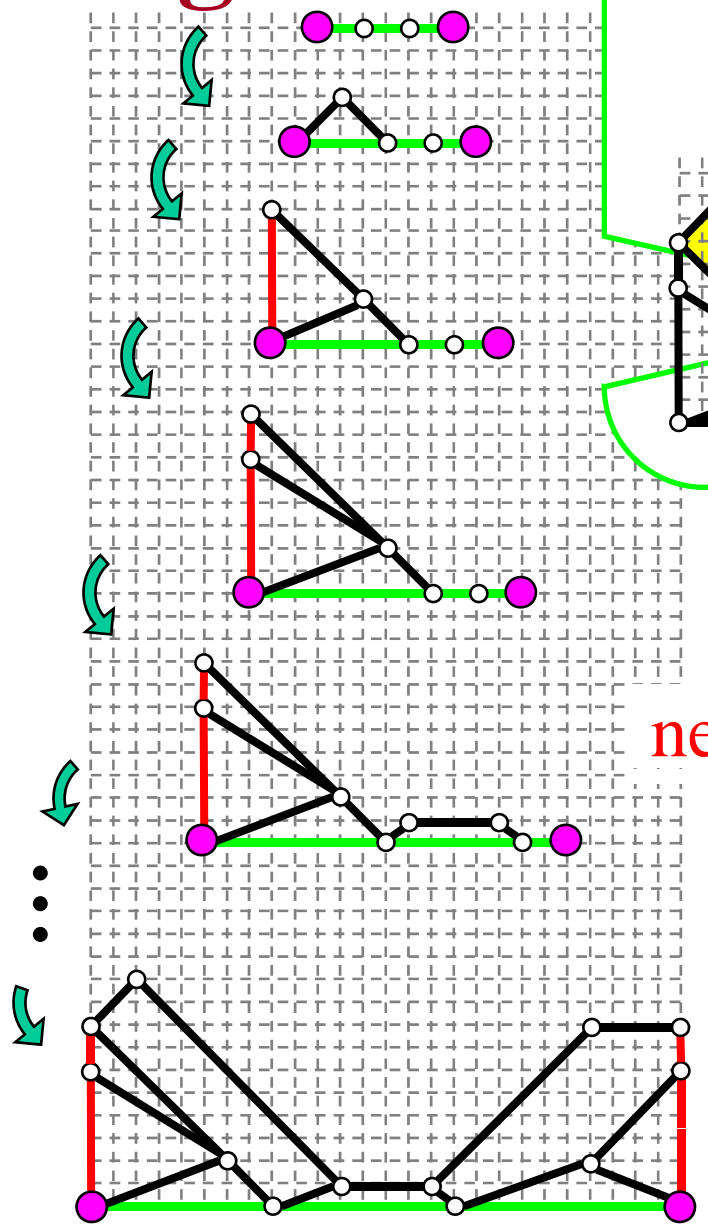
② slope = 0 or ± 1

① convex polygon

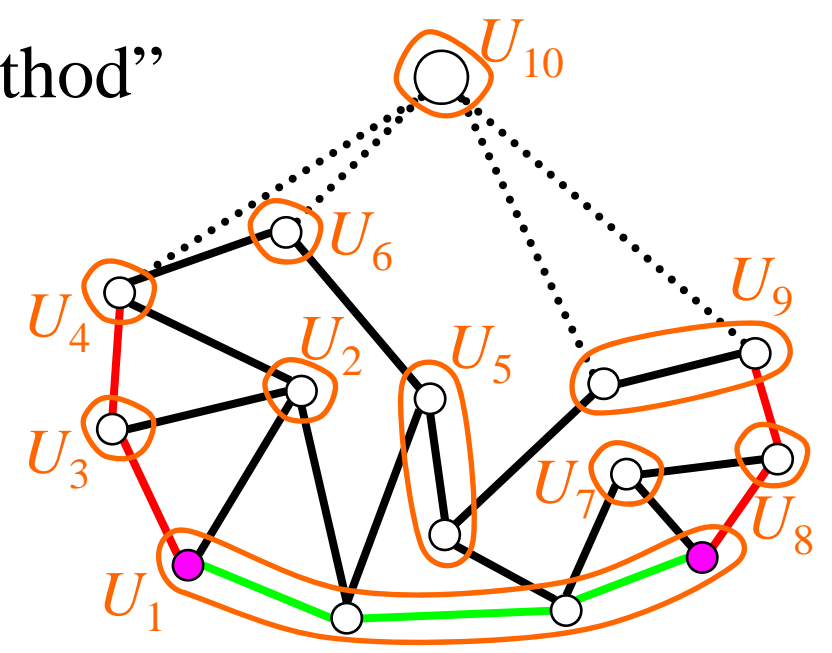
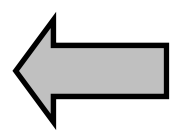
new “shift method”



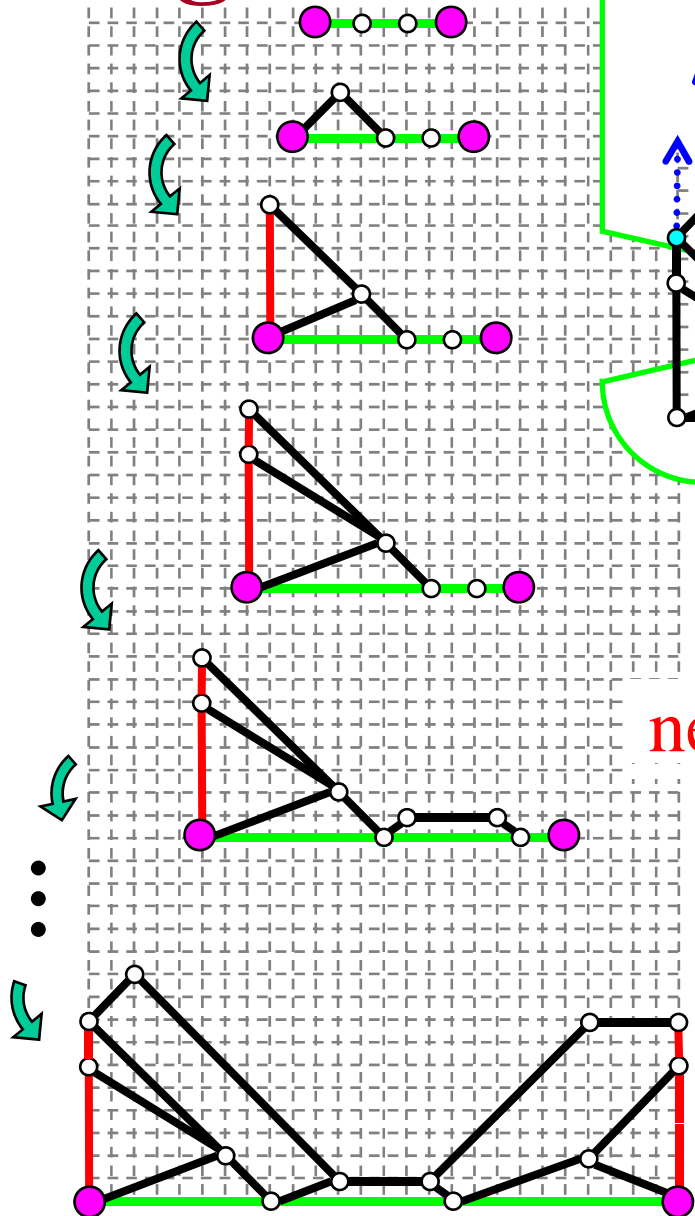
Algorithm



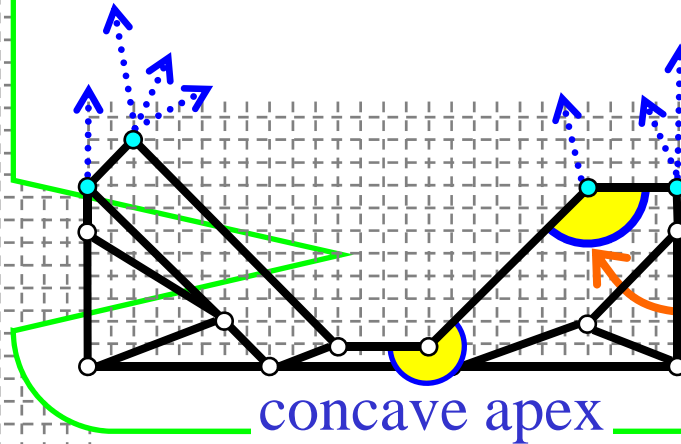
new "shift method"



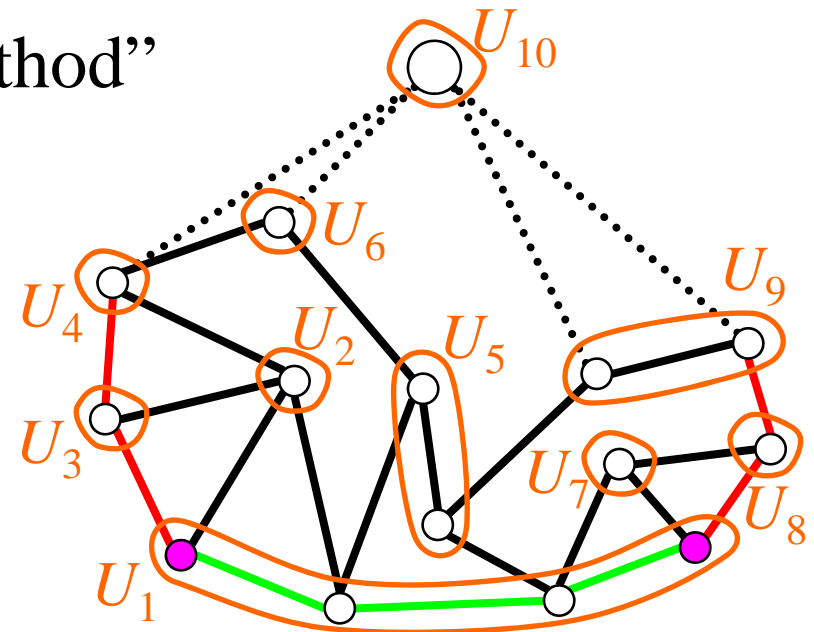
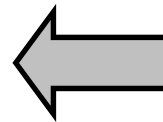
Algorithm



③ convex apex ● has upper neighbors

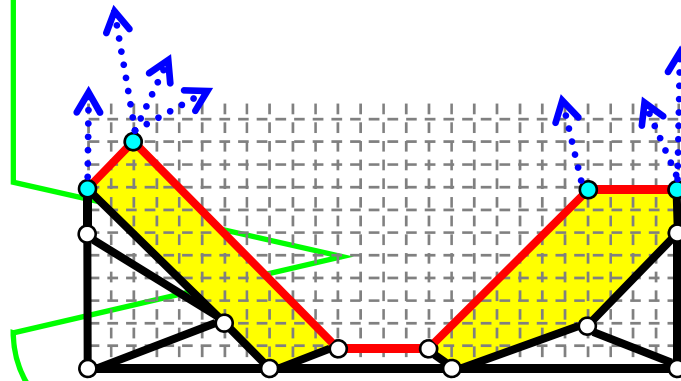


new “shift method”



Algorithm

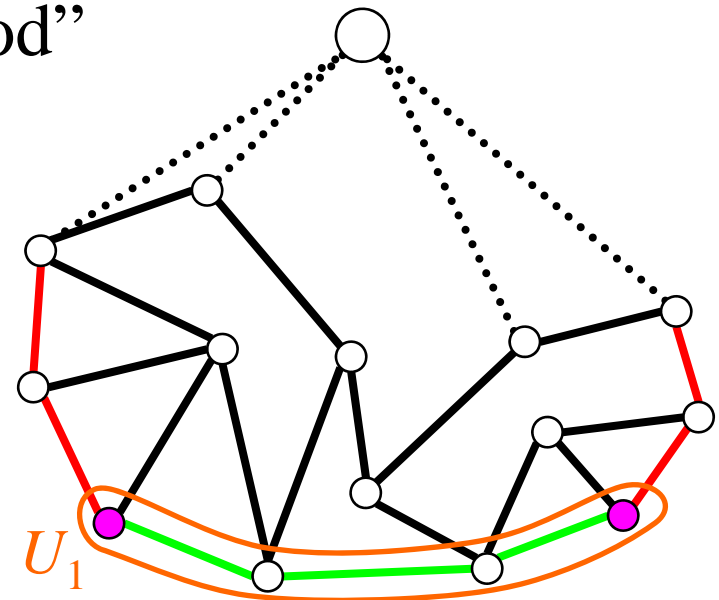
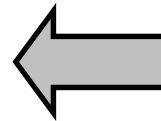
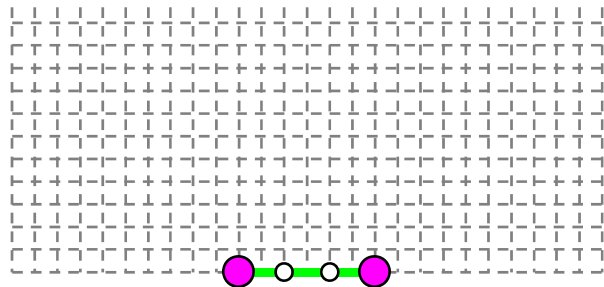
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

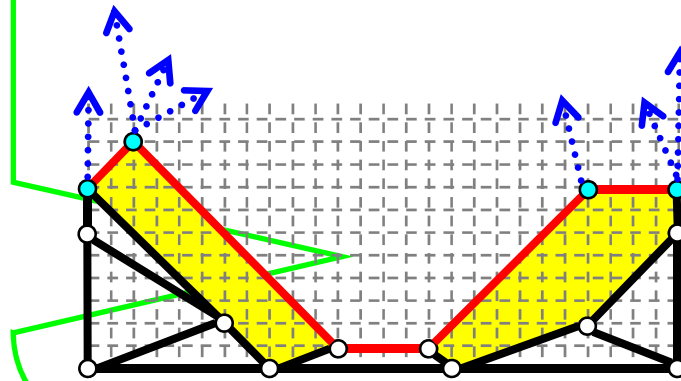
① convex polygon

new “shift method”



Algorithm

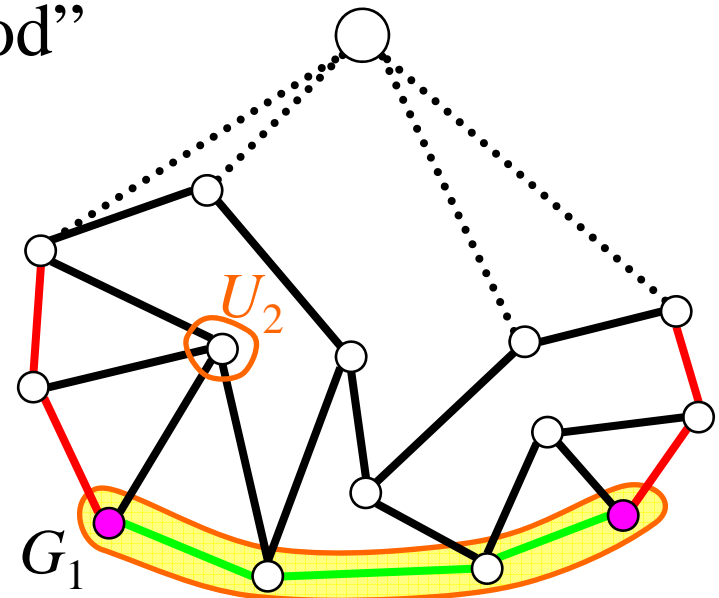
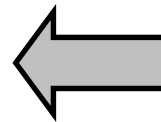
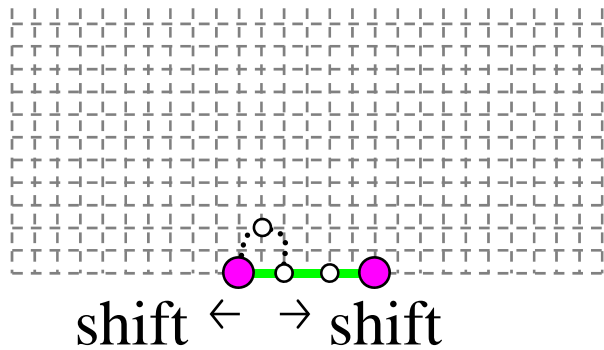
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

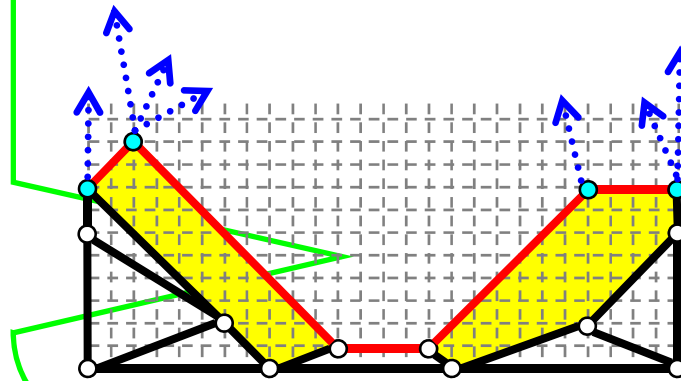
① convex polygon

new “shift method”



Algorithm

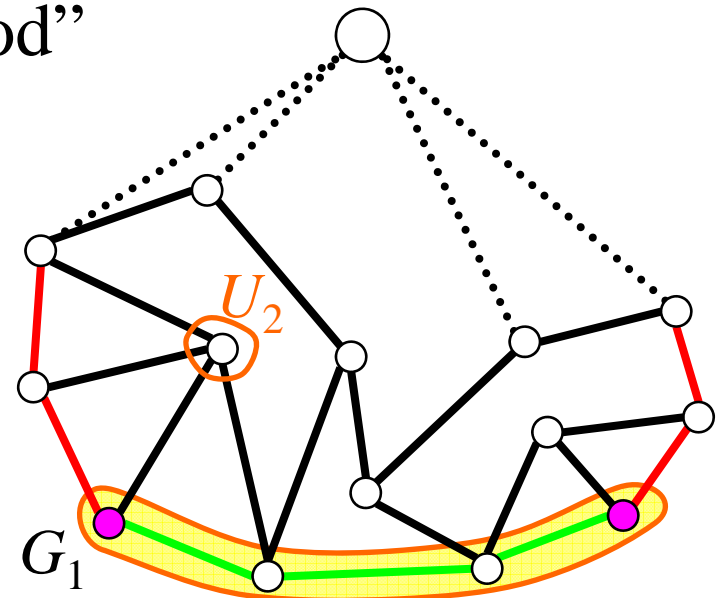
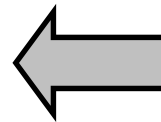
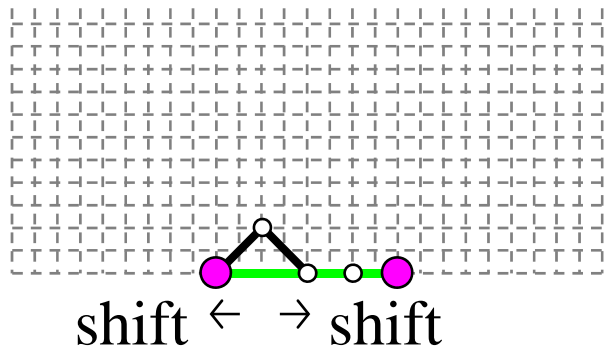
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

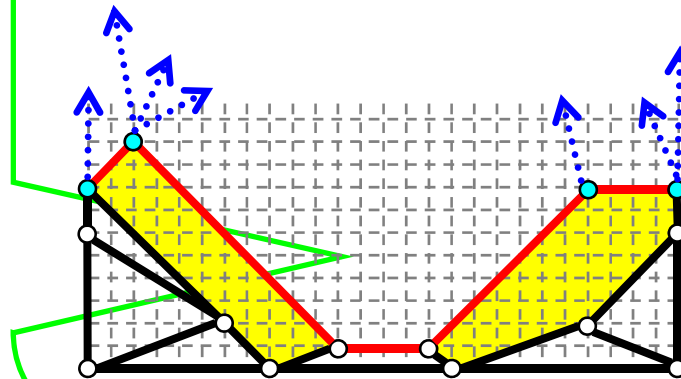
① convex polygon

new “shift method”



Algorithm

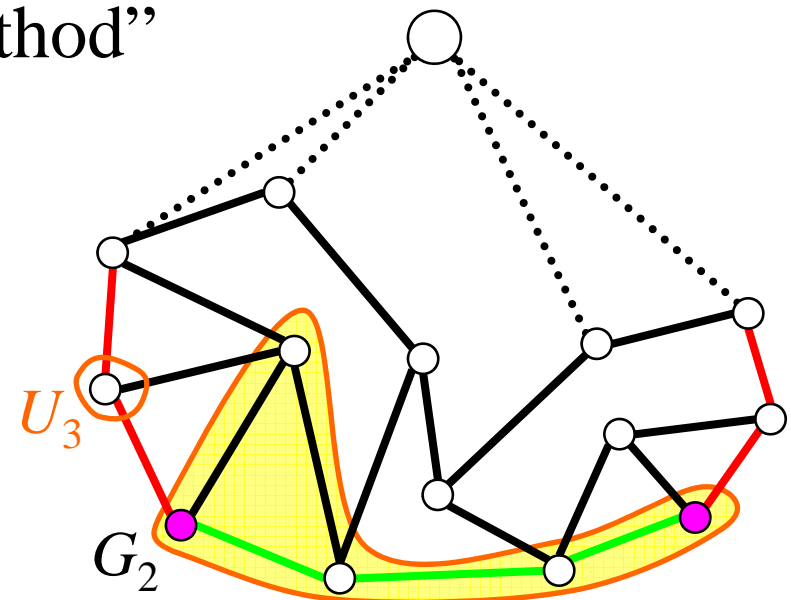
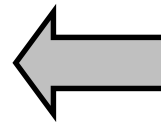
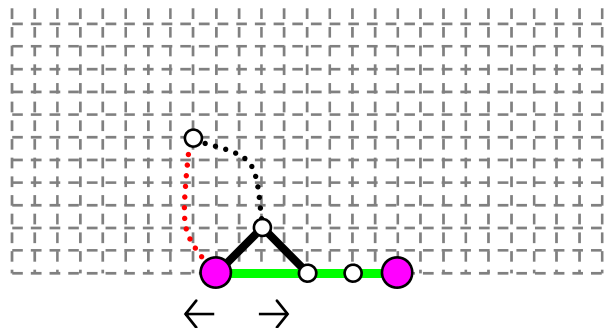
③ convex apex ● has upper neighbors



②
slope = 0 or ± 1

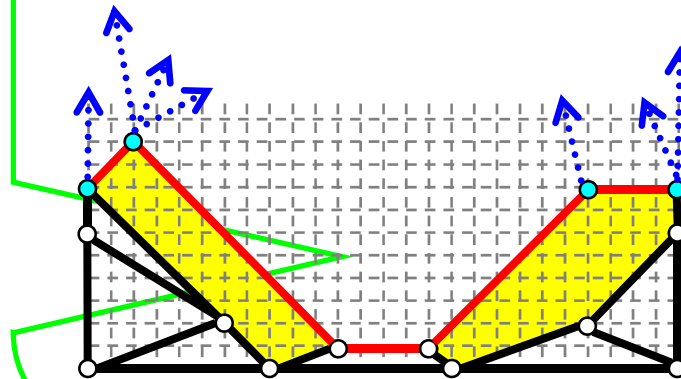
①
convex polygon

new “shift method”



Algorithm

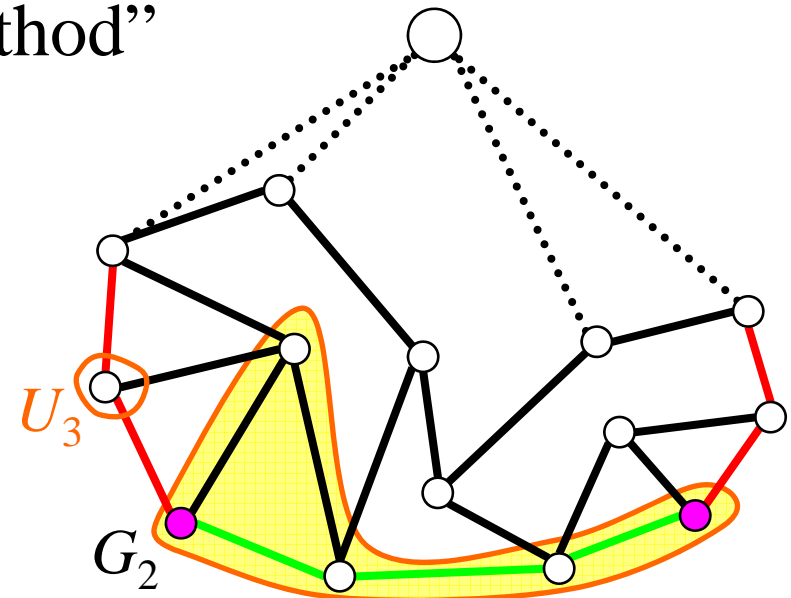
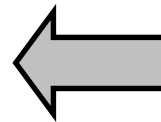
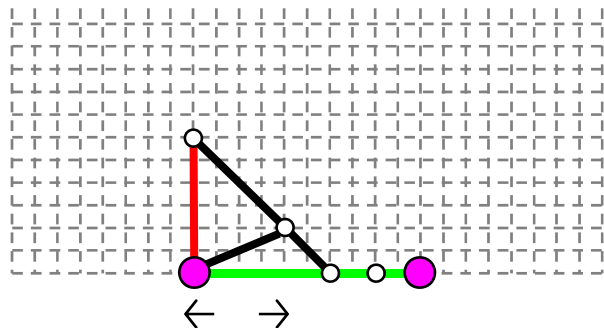
③ convex apex ● has upper neighbors



②
slope = 0 or ±1

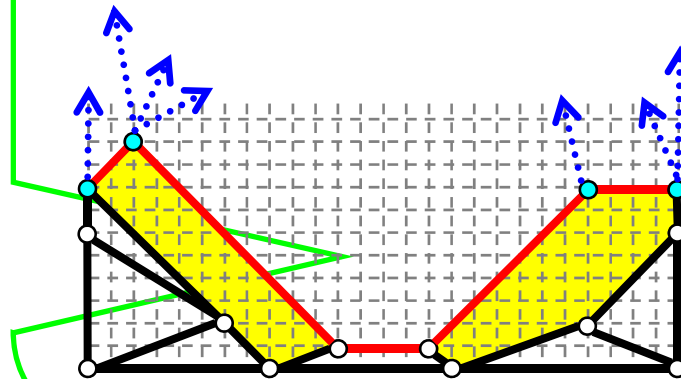
①
convex polygon

new “shift method”



Algorithm

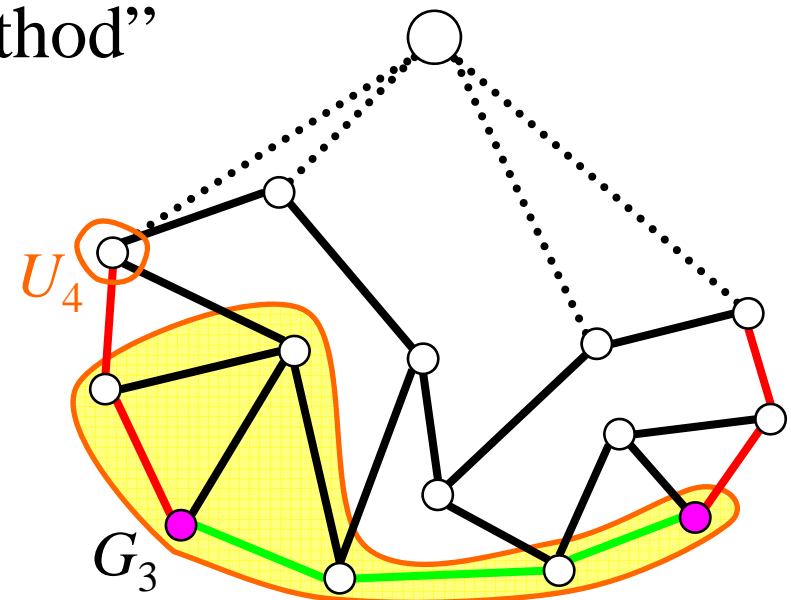
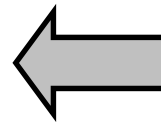
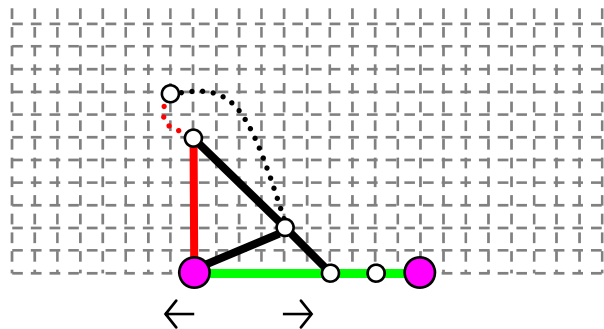
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

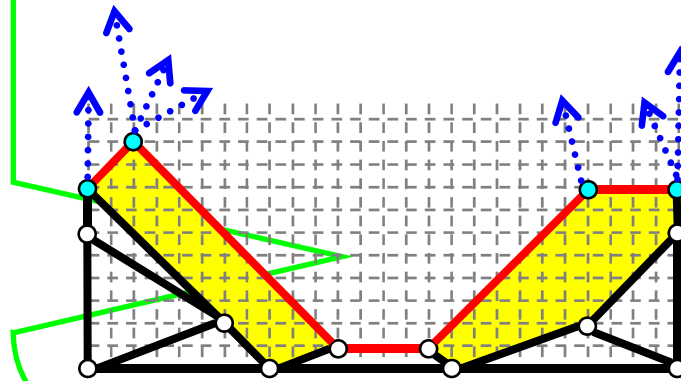
① convex polygon

new “shift method”



Algorithm

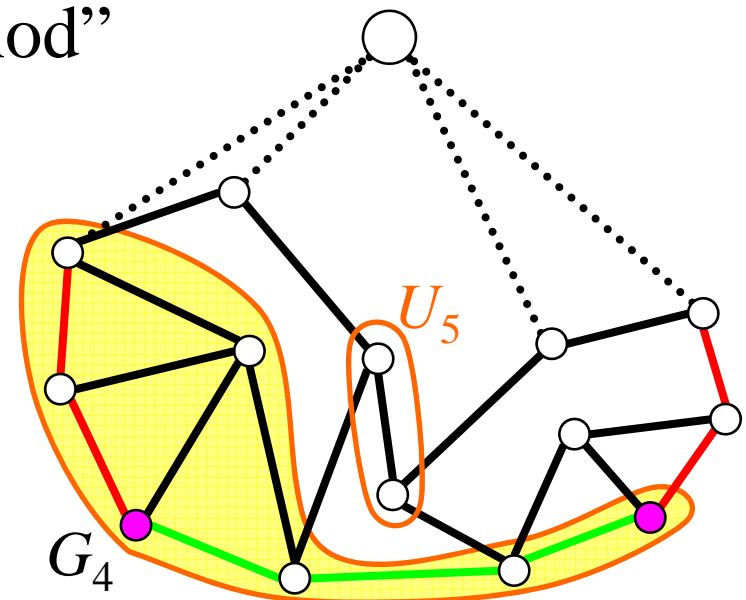
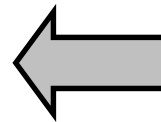
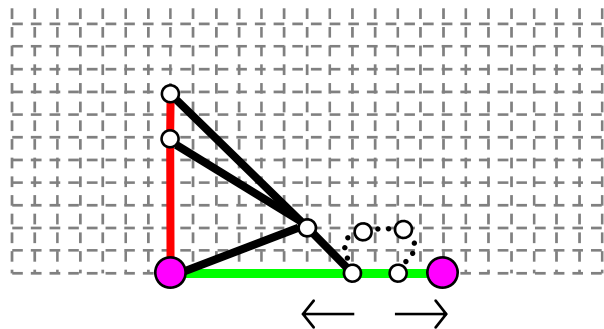
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

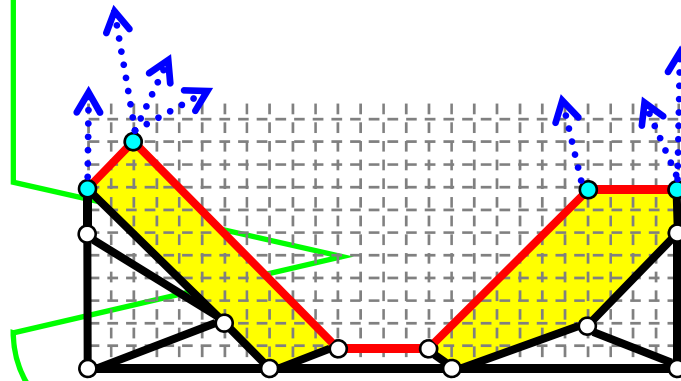
① convex polygon

new “shift method”



Algorithm

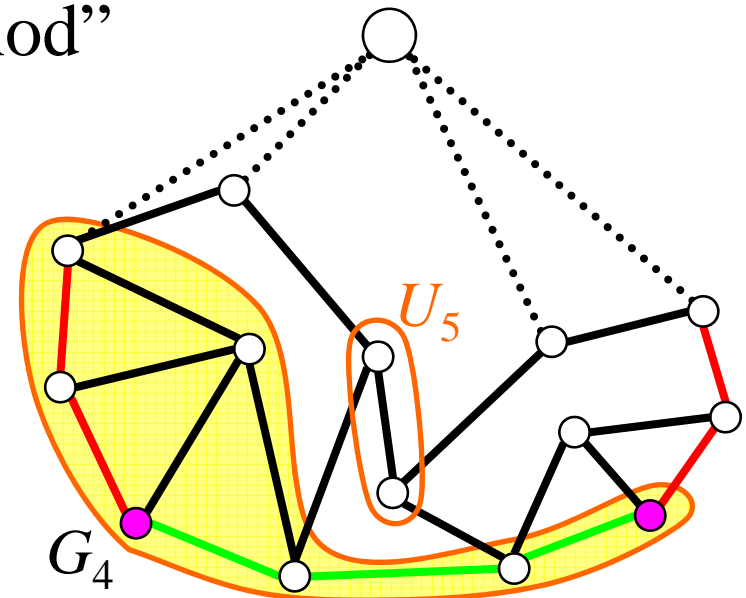
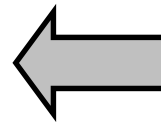
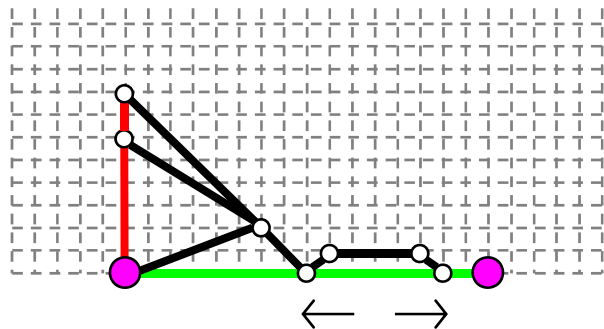
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

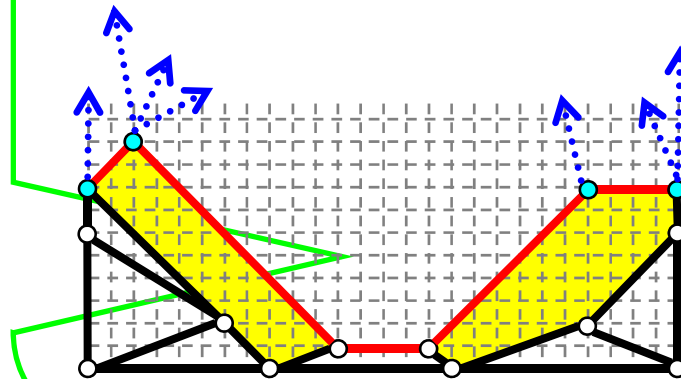
① convex polygon

new “shift method”



Algorithm

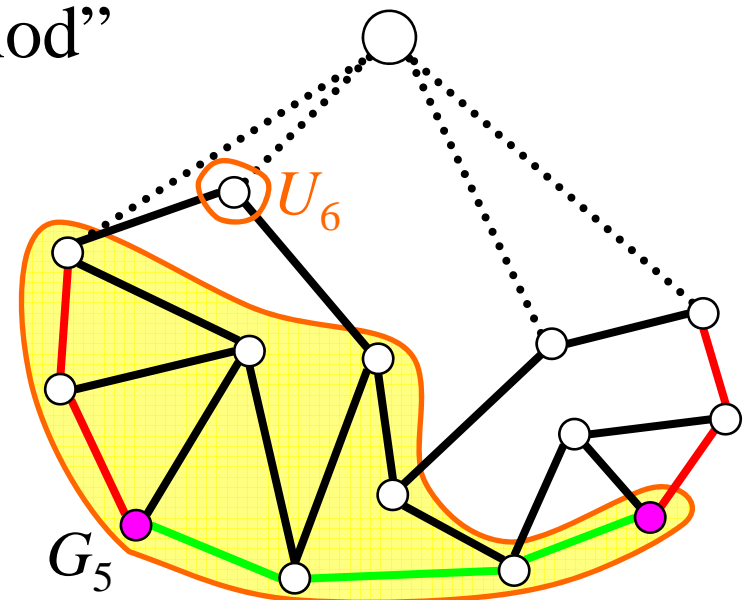
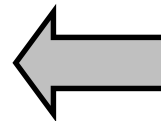
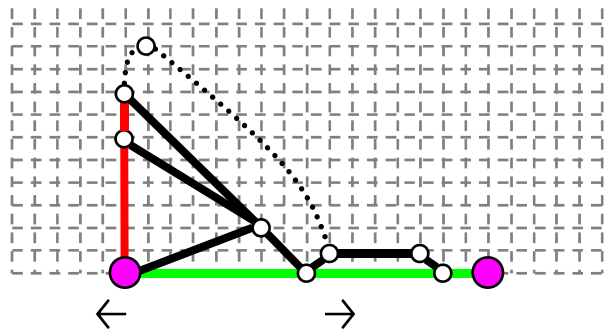
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

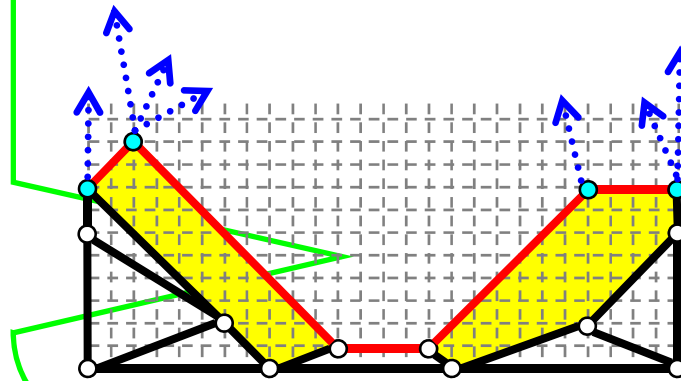
① convex polygon

new “shift method”



Algorithm

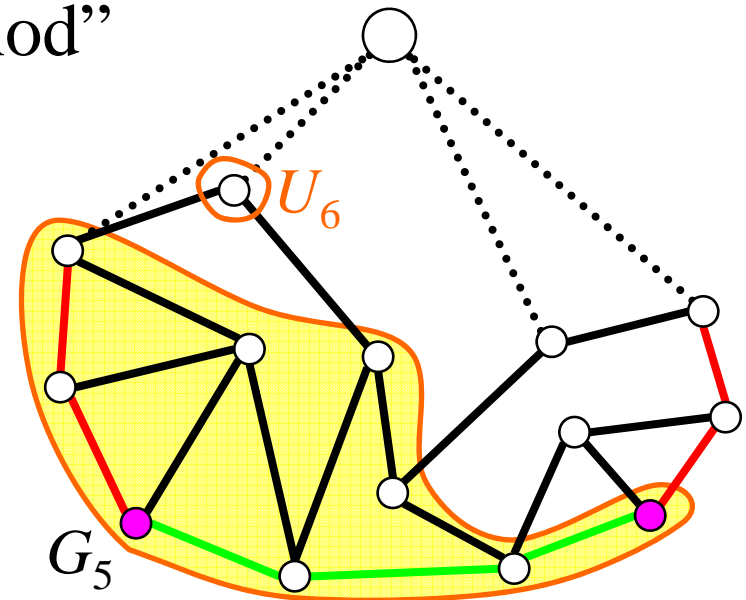
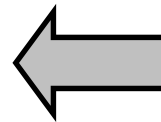
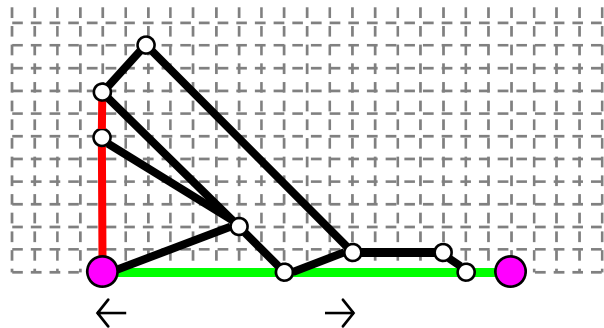
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

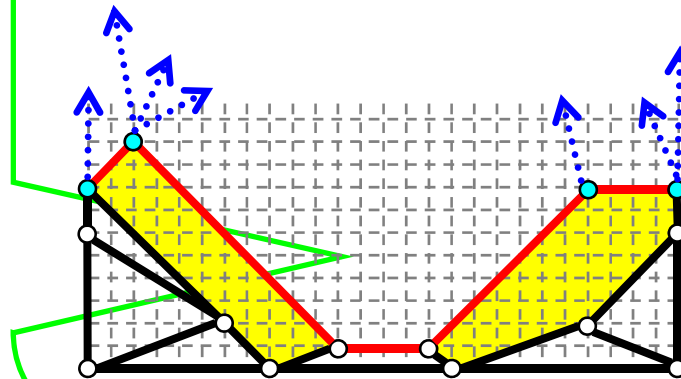
① convex polygon

new “shift method”



Algorithm

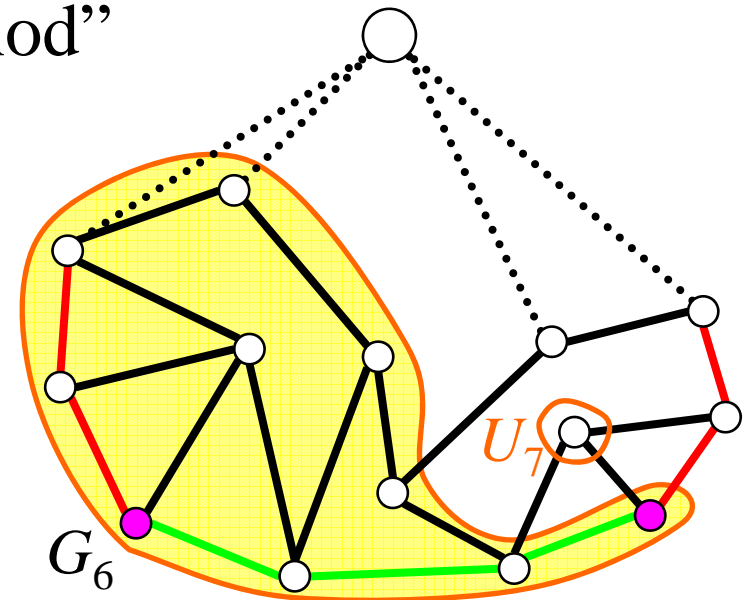
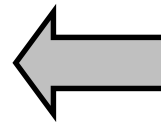
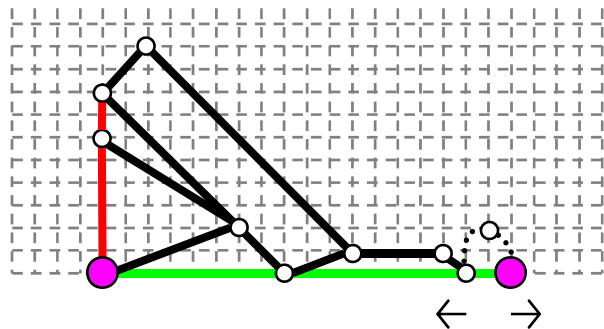
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

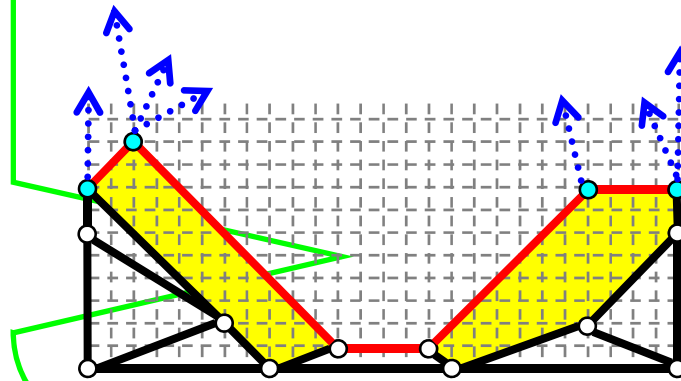
① convex polygon

new “shift method”



Algorithm

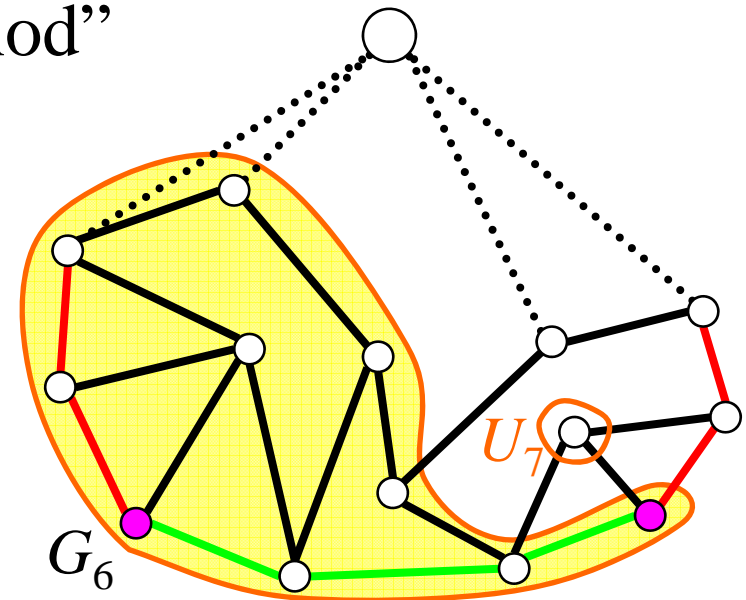
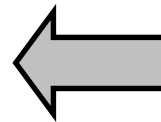
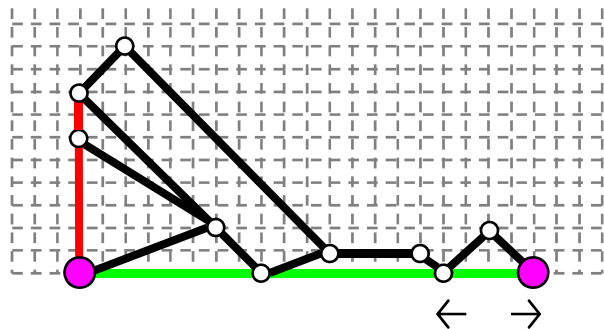
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

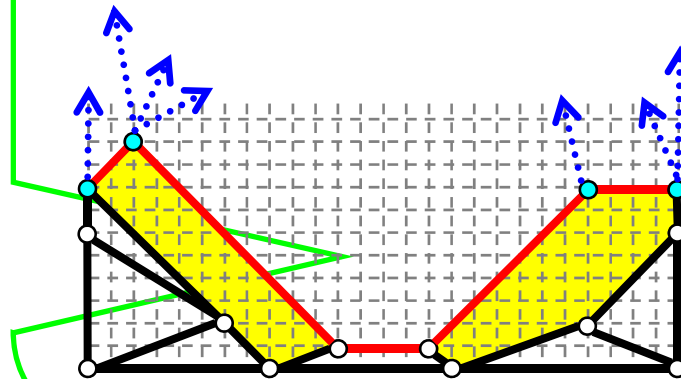
① convex polygon

new “shift method”



Algorithm

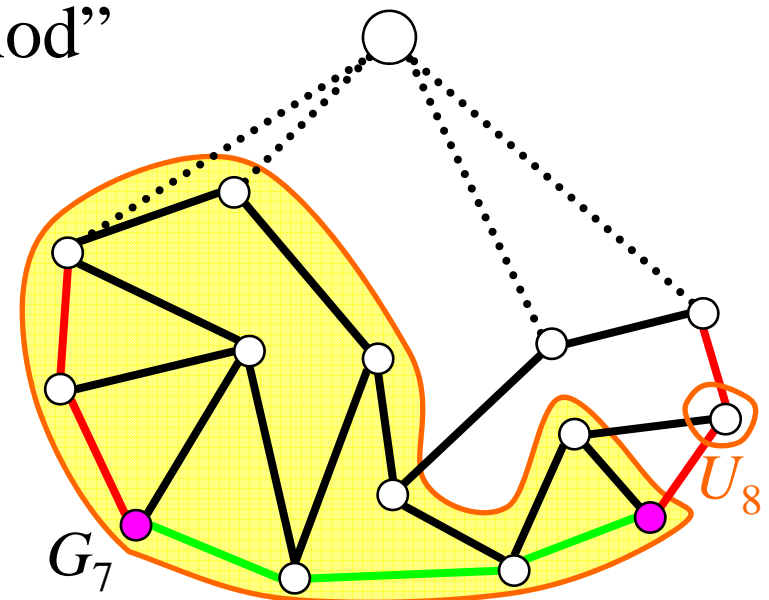
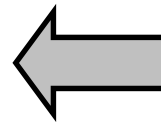
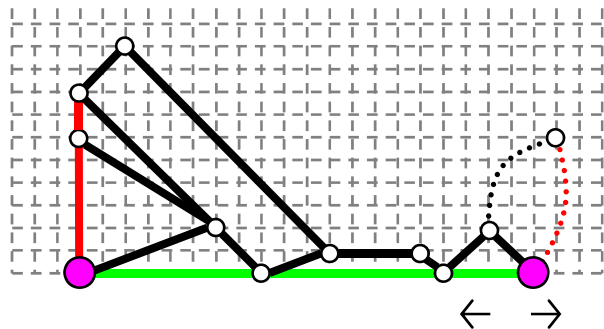
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

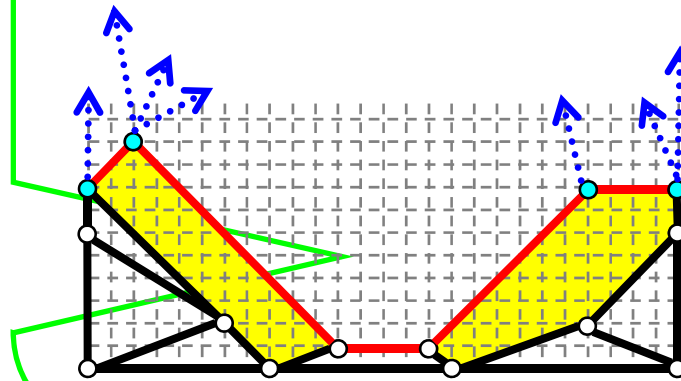
① convex polygon

new “shift method”



Algorithm

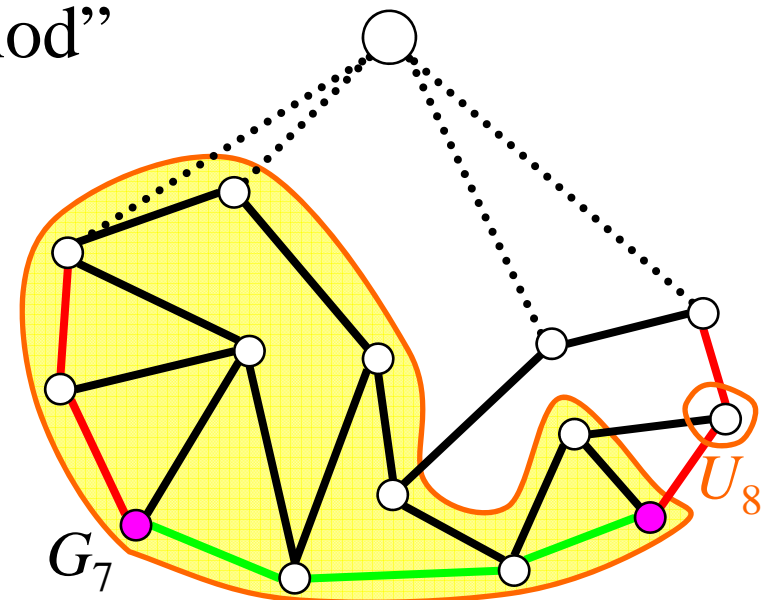
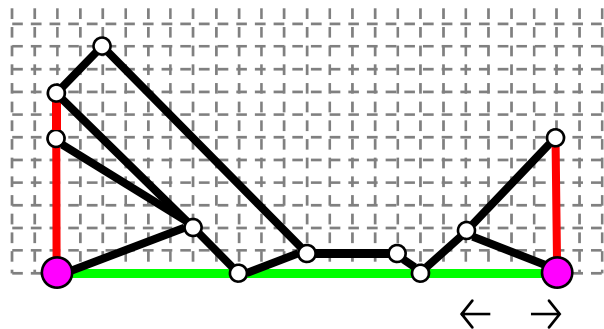
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

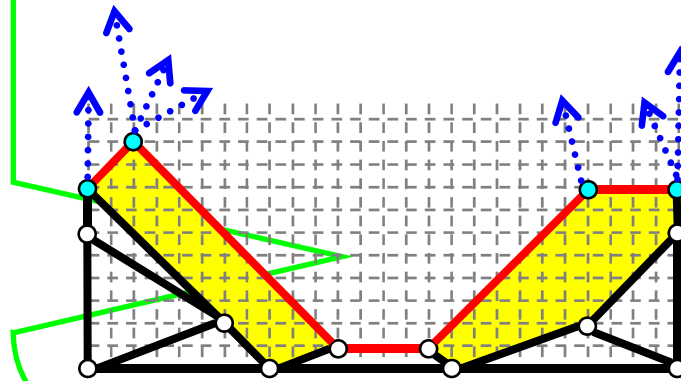
① convex polygon

new “shift method”



Algorithm

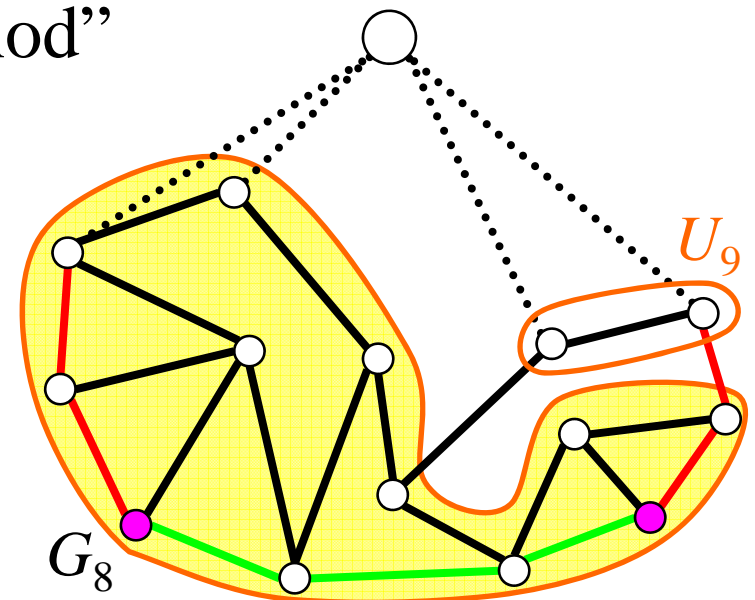
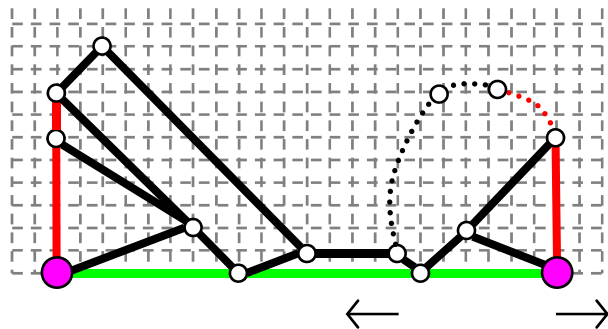
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

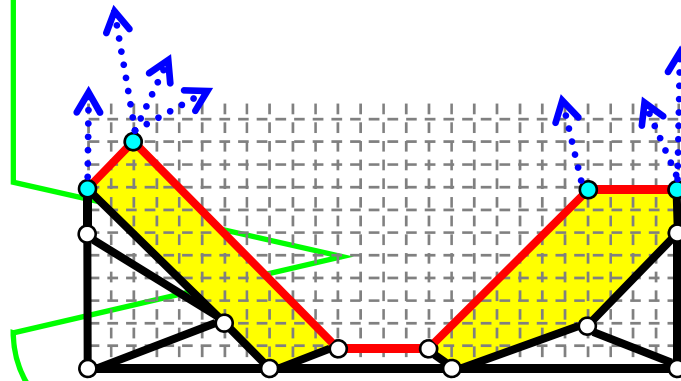
① convex polygon

new “shift method”



Algorithm

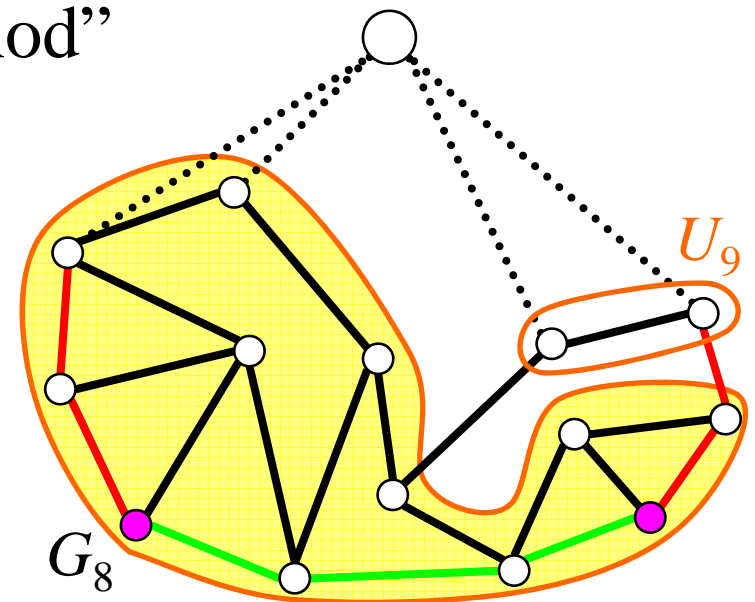
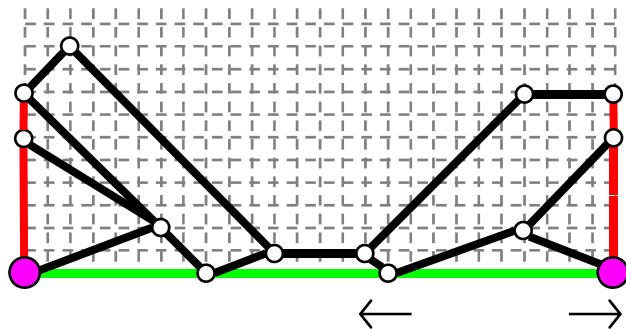
③ convex apex ● has upper neighbors



② slope = 0 or ± 1

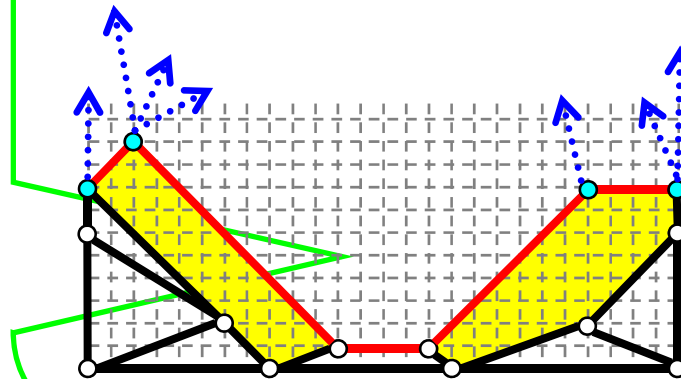
① convex polygon

new “shift method”



Algorithm

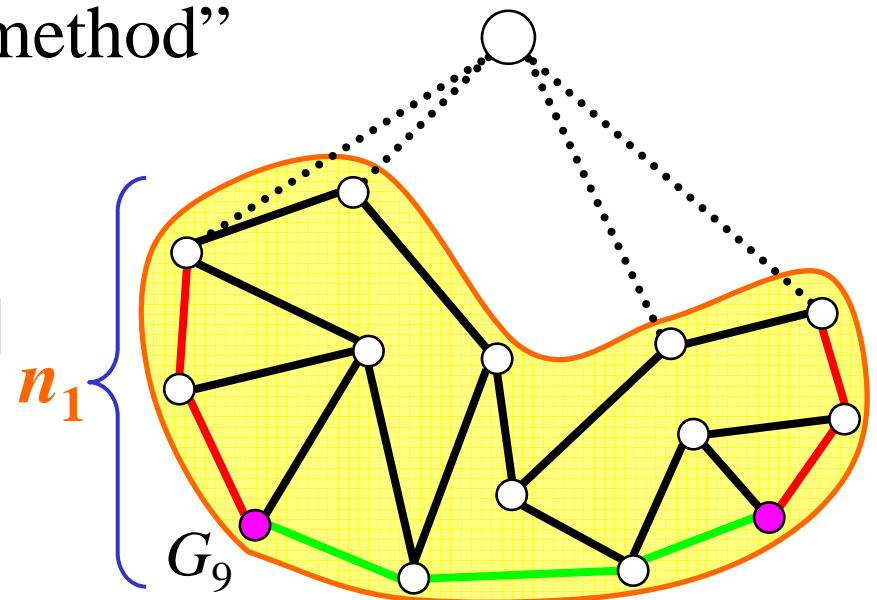
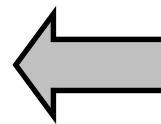
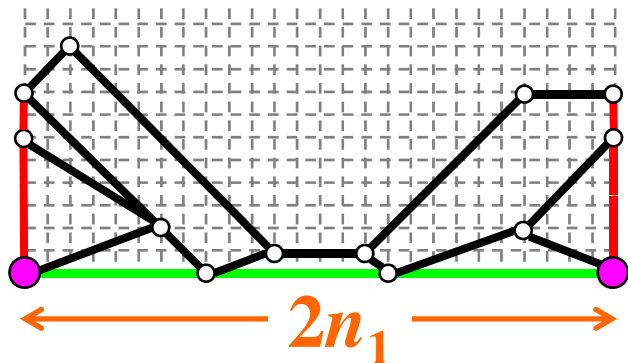
③ convex apex ● has upper neighbors



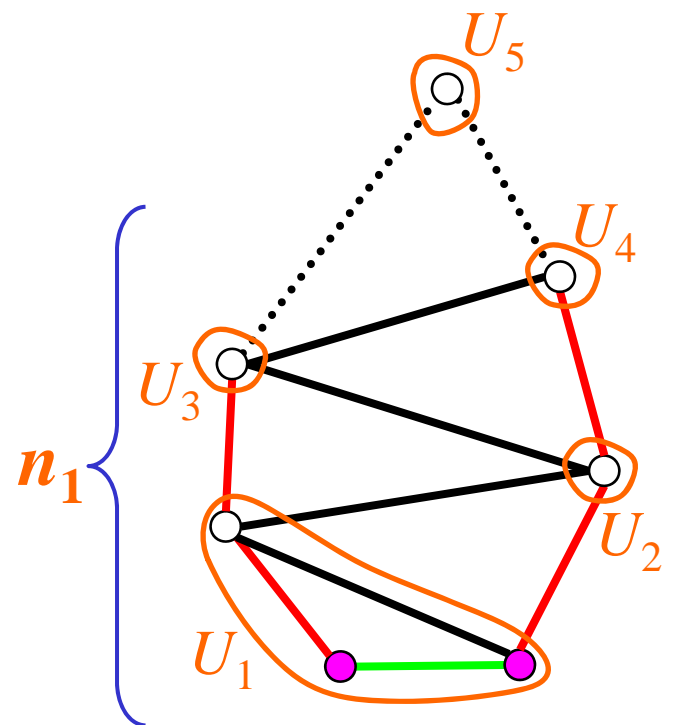
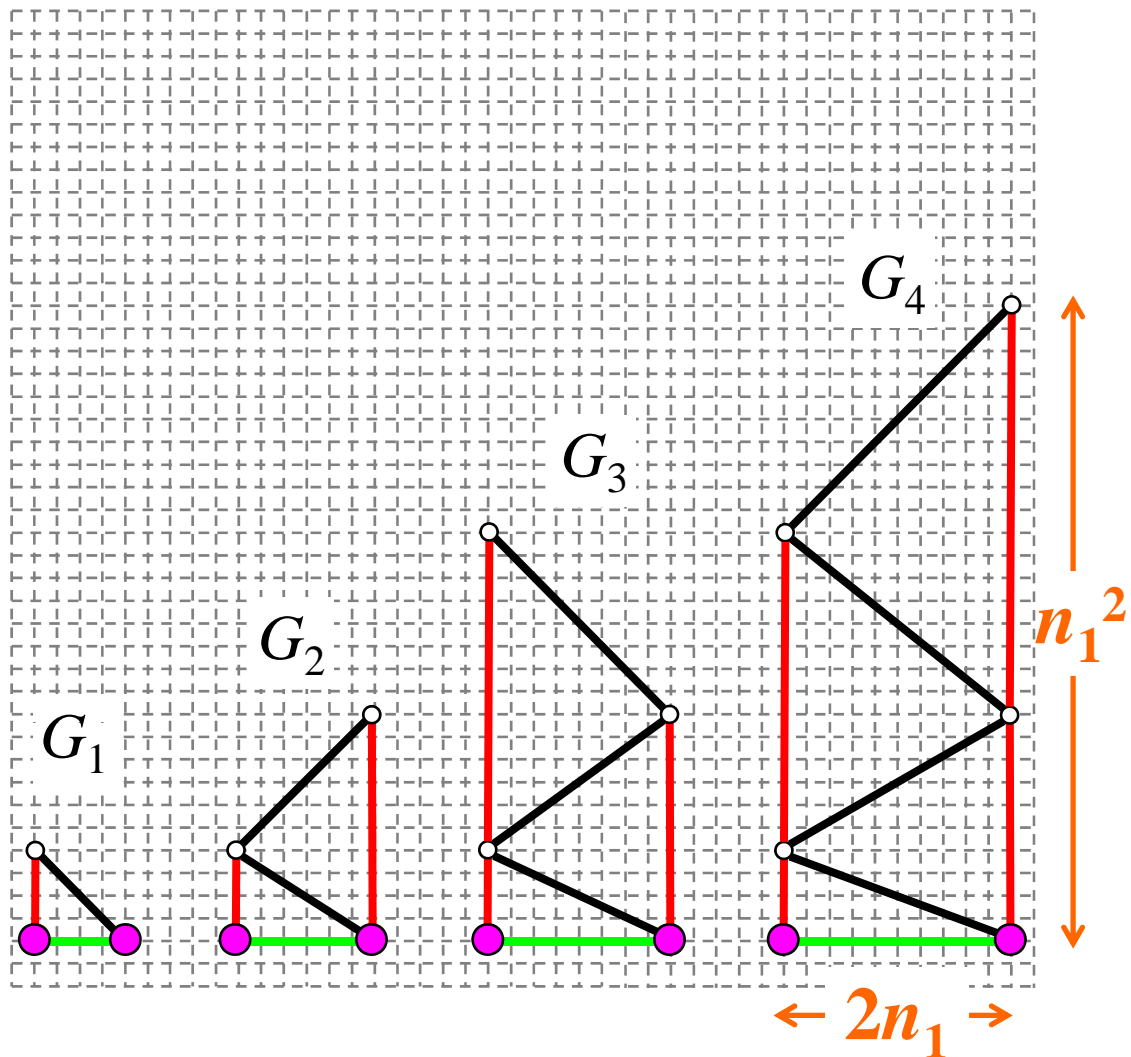
②
slope = 0 or ±1

①
convex polygon

new “shift method”



Grid size



Algorithm

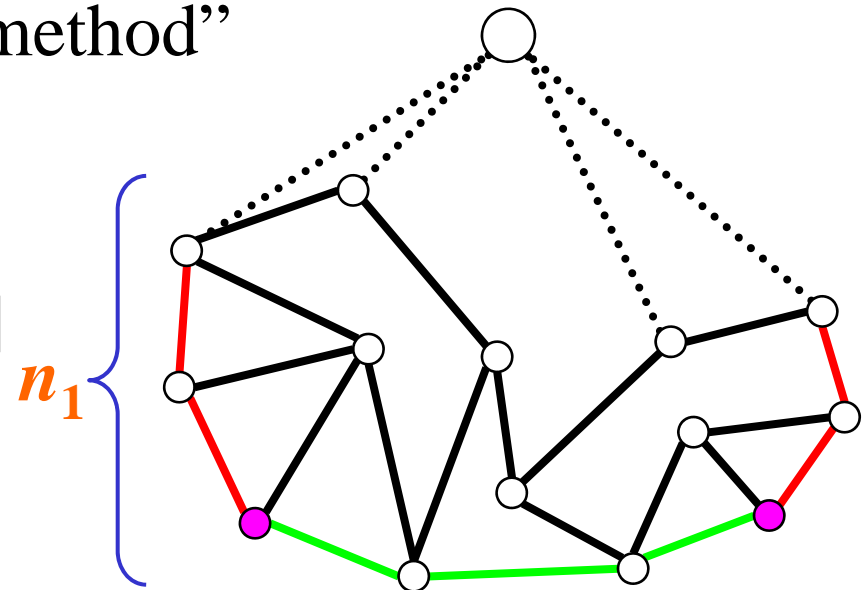
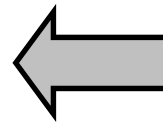
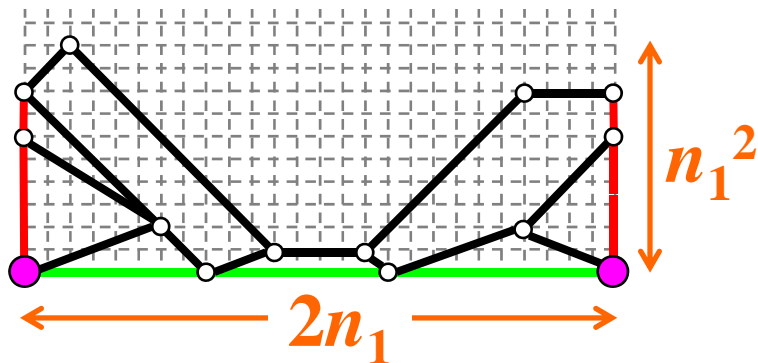
inner convex grid drawing



internally 3-connected graph

leaves = 2

new “shift method”

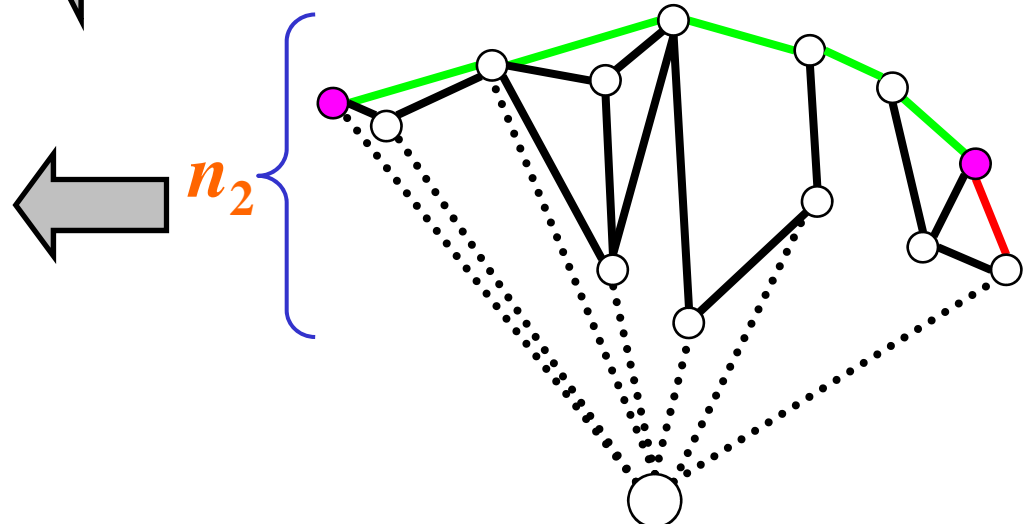
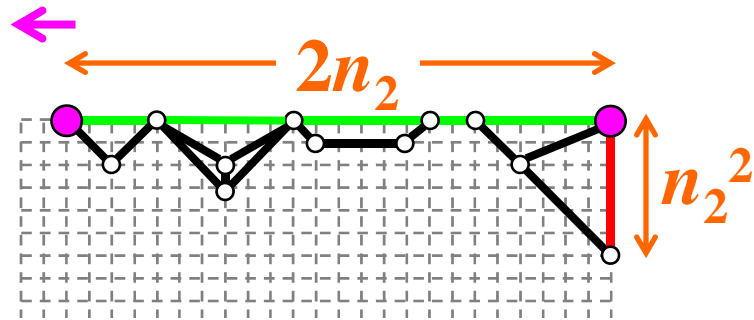


Algorithm

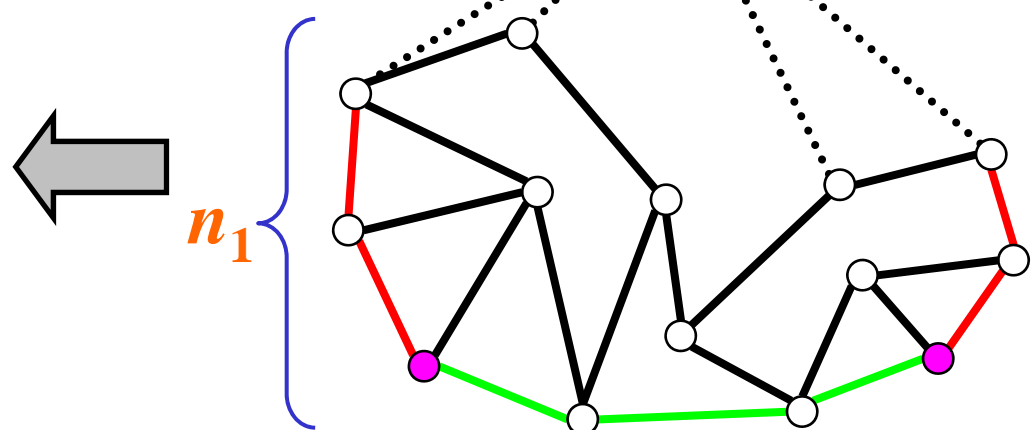
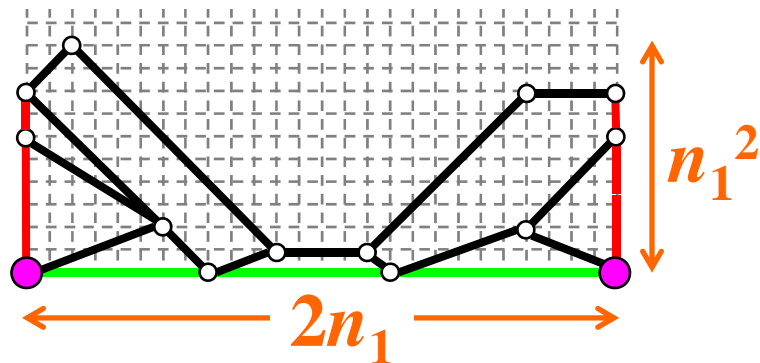
inner convex grid drawings

internally 3-connected graphs

leaves = 2

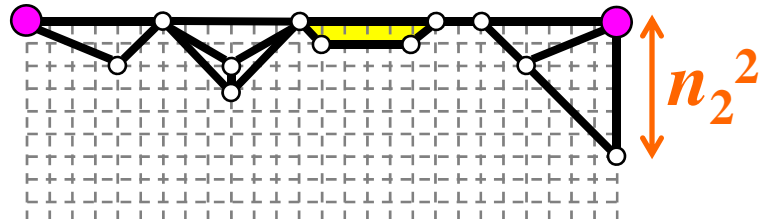


new "shift method"



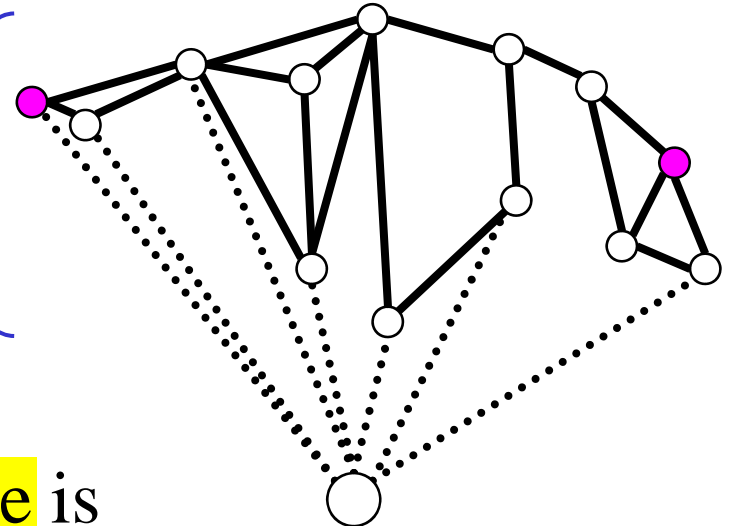
Algorithm

inner convex grid drawings

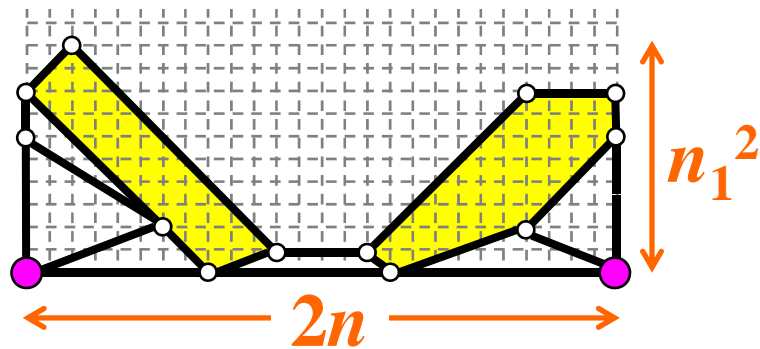


internally 3-connected graphs

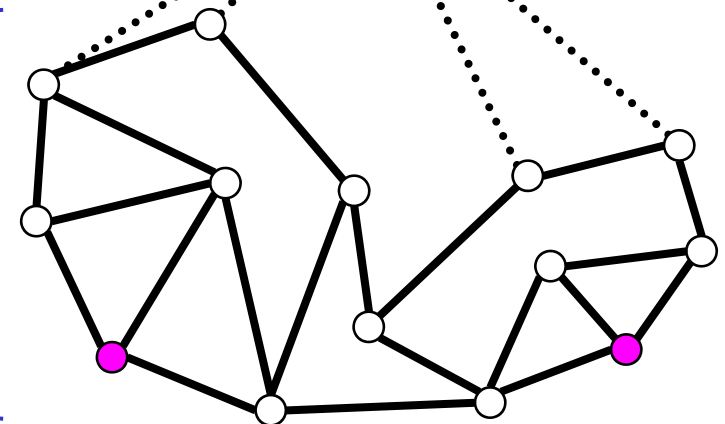
leaves = 2



every inner face is a convex polygon

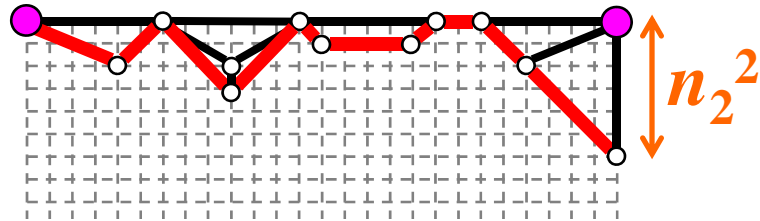


n_1

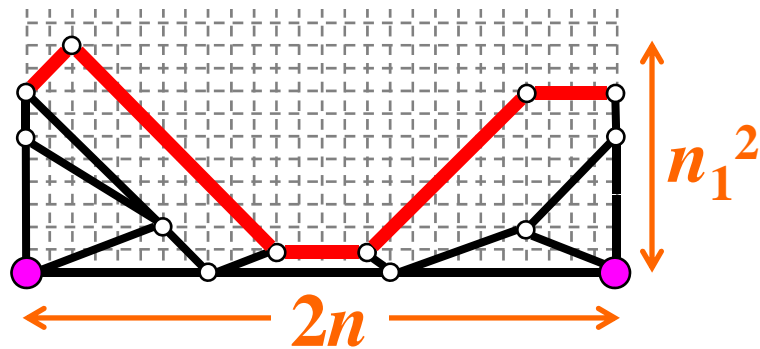


Algorithm

inner convex grid drawings

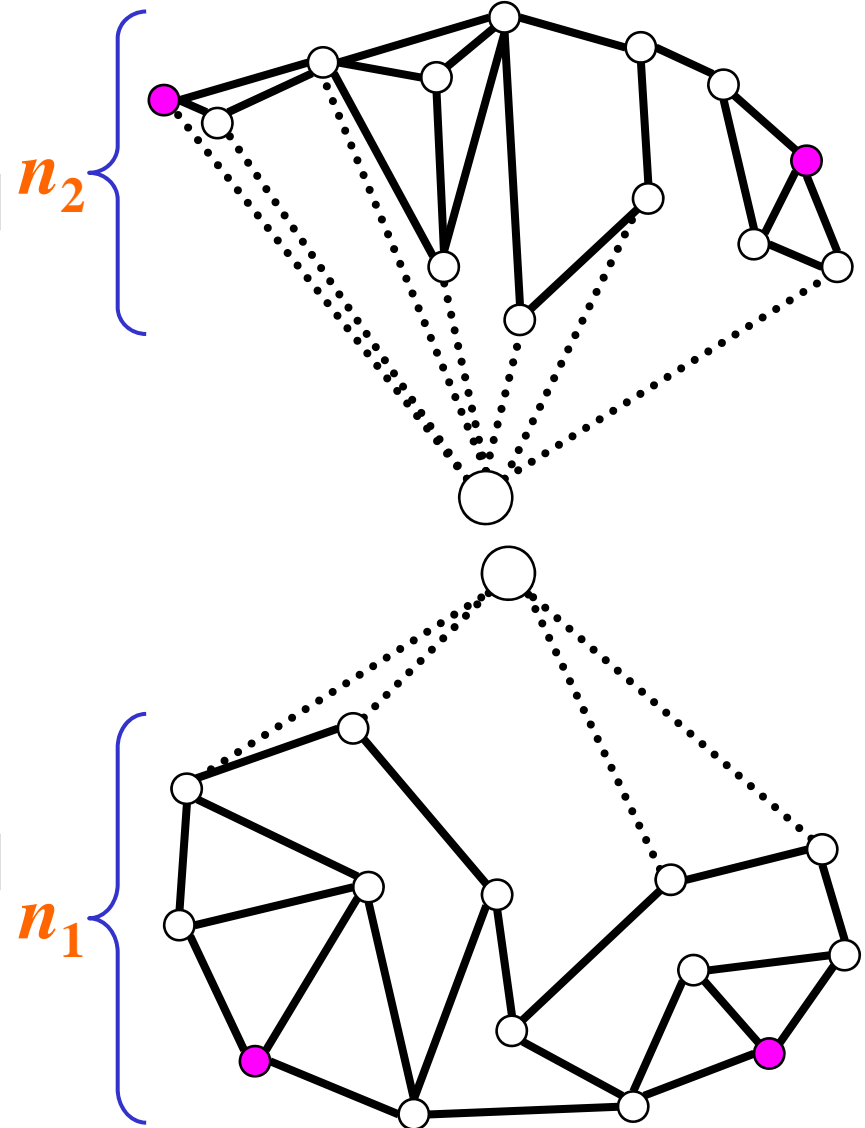


$|\text{slope}| \leq 1$



internally 3-connected graphs

leaves = 2

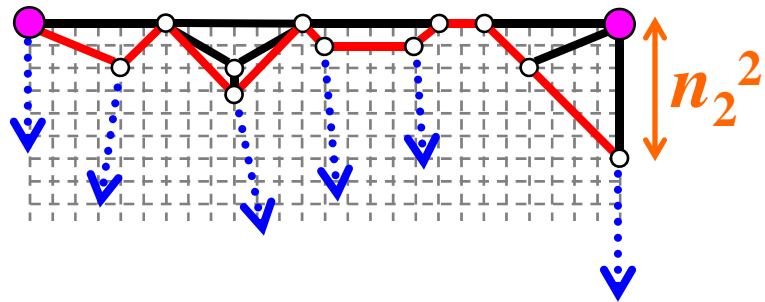


Algorithm

inner convex grid drawings

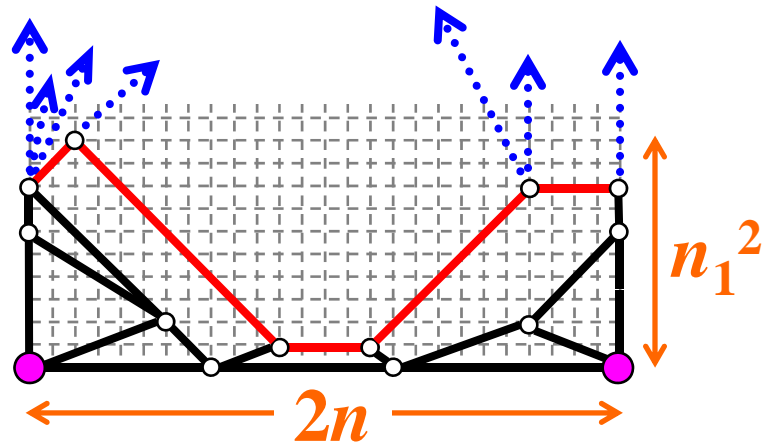
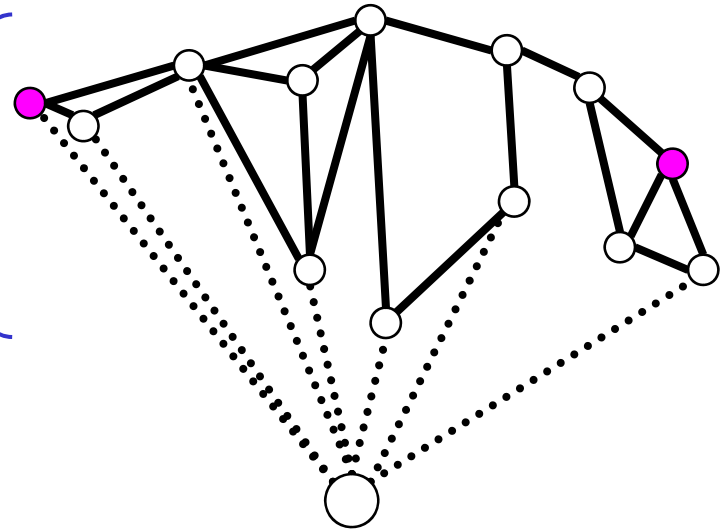
internally 3-connected graphs

leaves = 2

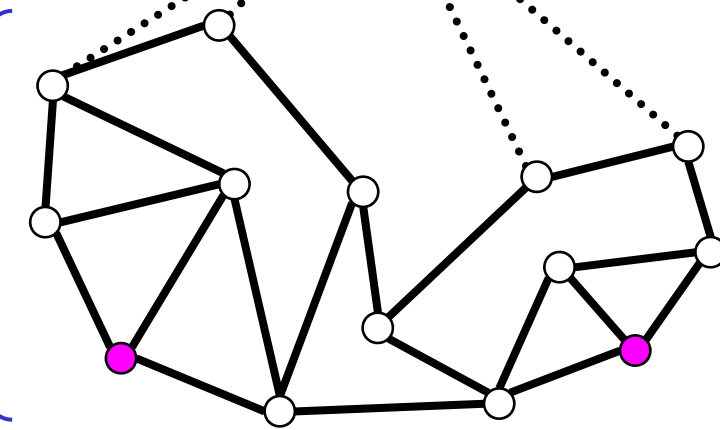


| slope | ≤ 1

n_2



n_1

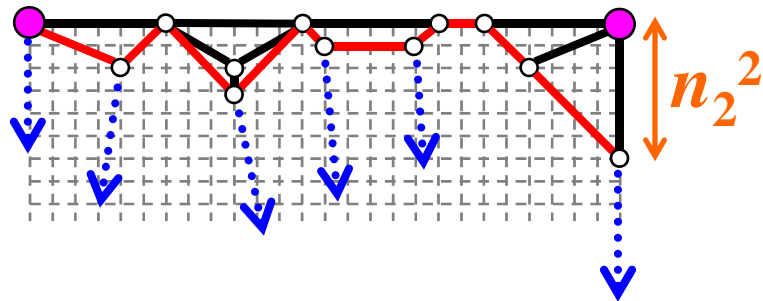


Algorithm

inner convex grid drawings

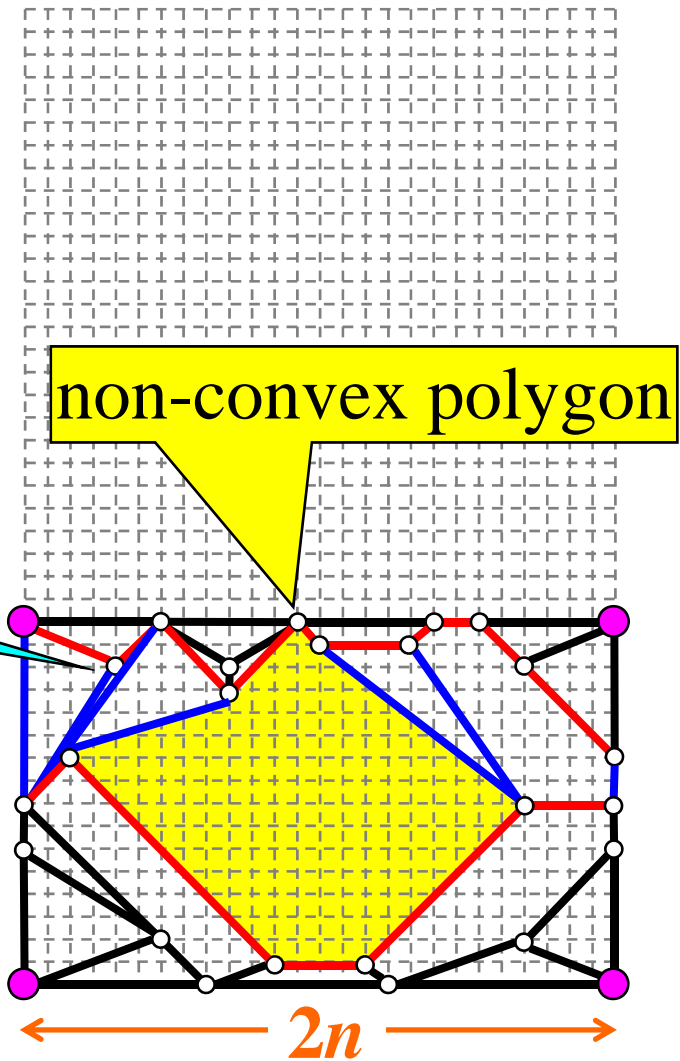
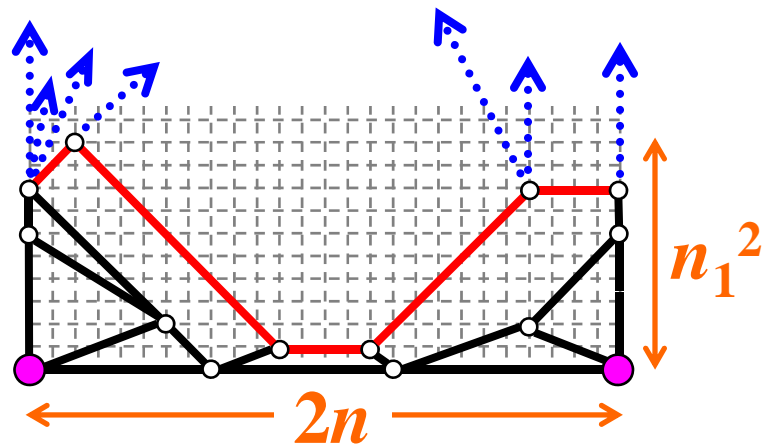


convex grid drawing



$|\text{slope}| \leq 1$

edge-intersection

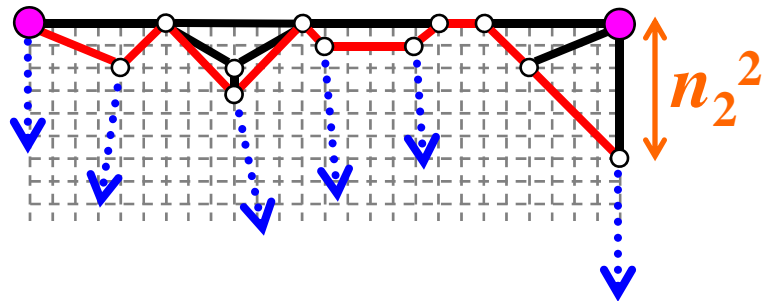


Algorithm

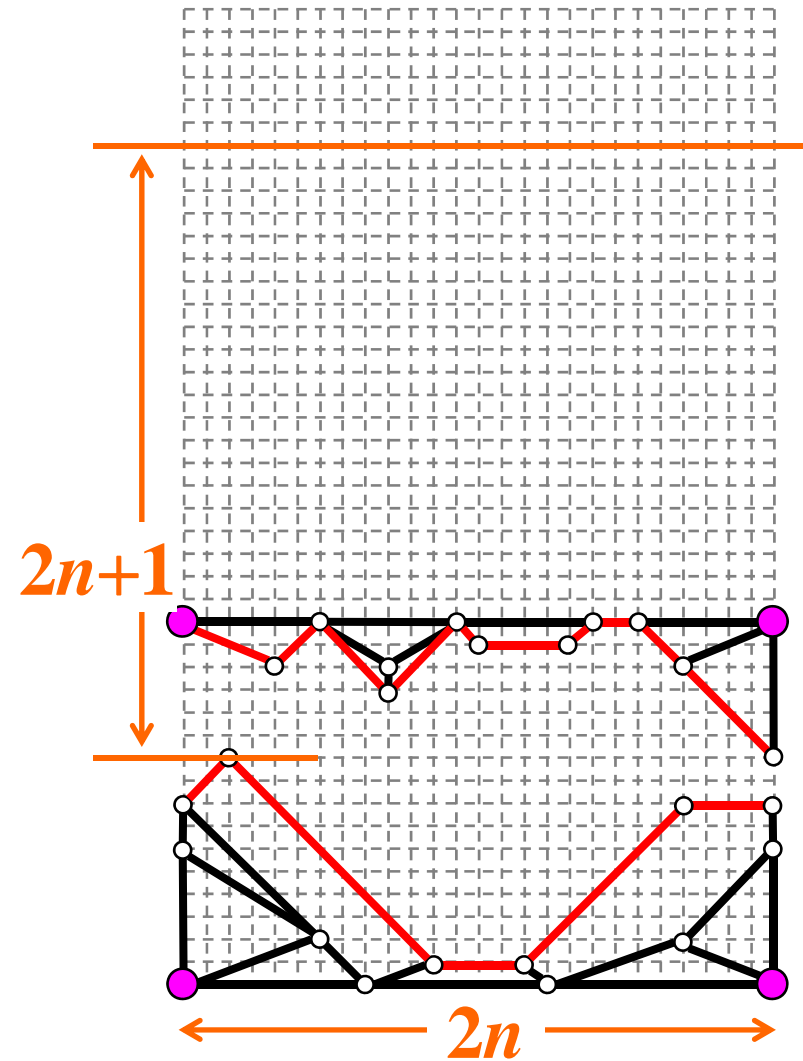
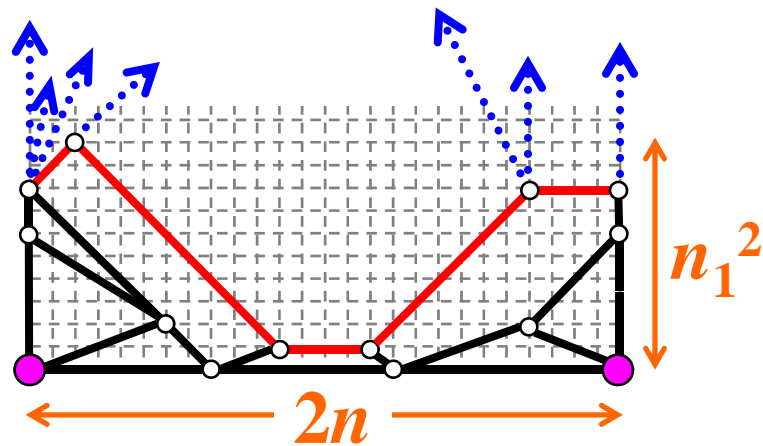
inner convex grid drawings



convex grid drawing



$$|\text{slope}| \leq 1$$

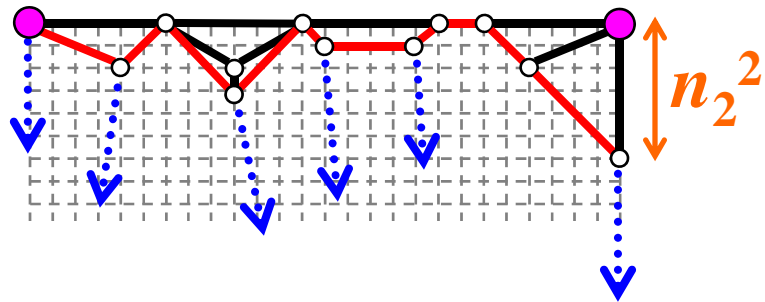


Algorithm

inner convex grid drawings

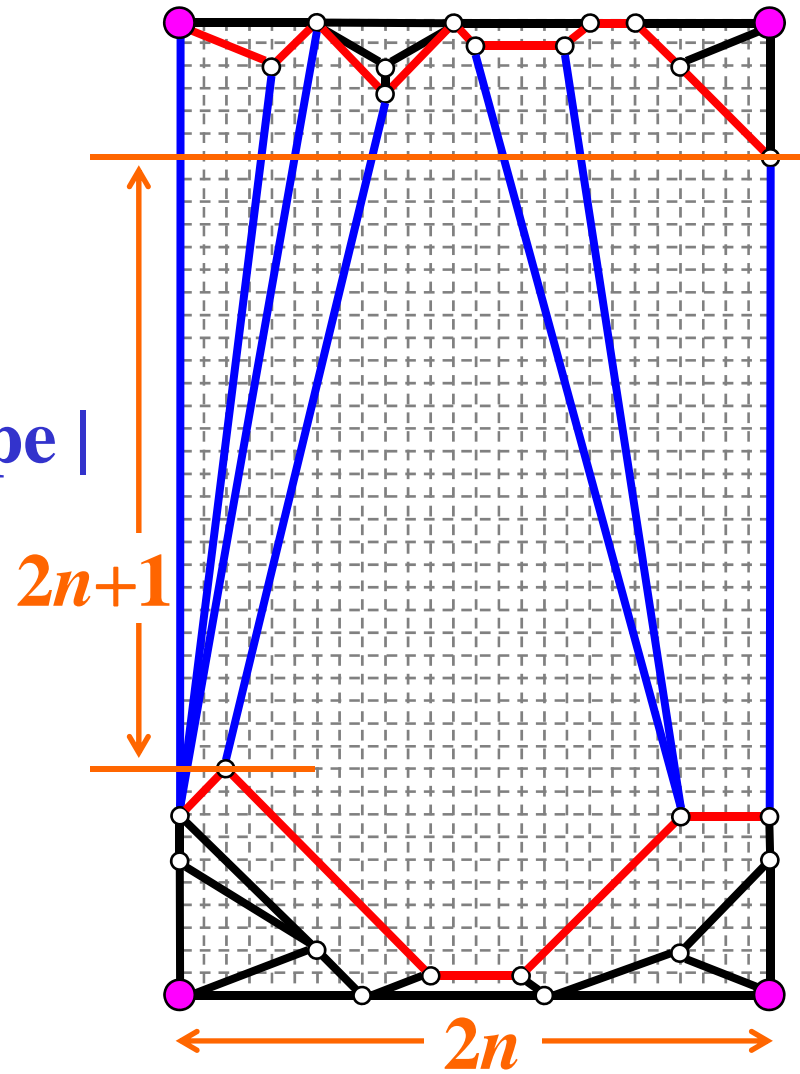
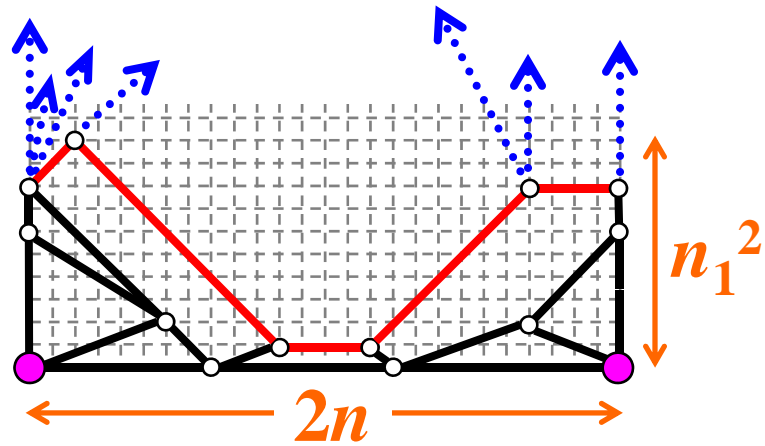


convex grid drawing



$|\text{slope}| \leq 1$

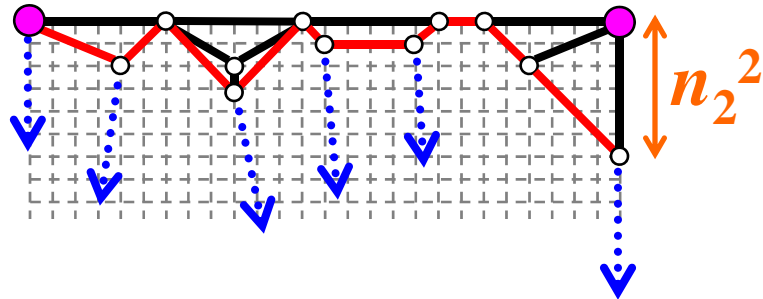
$1 < |\text{slope}|$



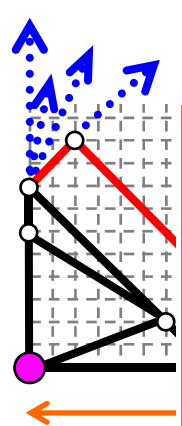
Algorithm

inner convex grid drawings 

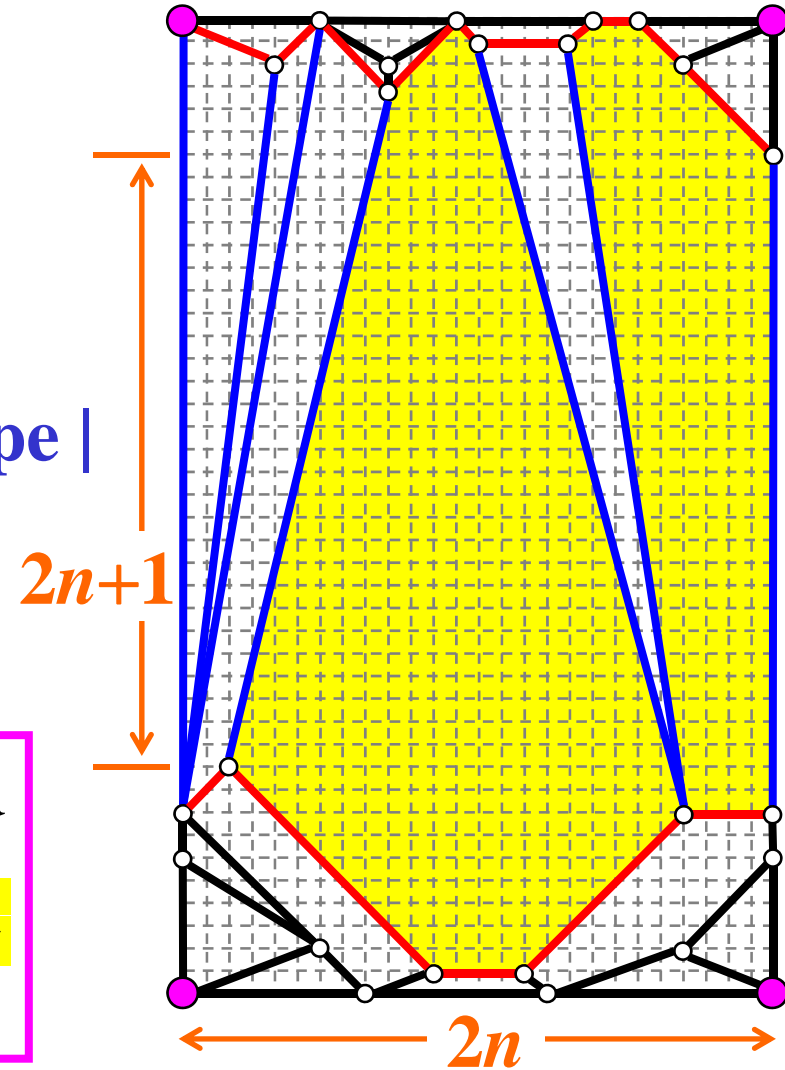
convex grid drawing



$|\text{slope}| \leq 1$ $1 < |\text{slope}|$



no edge-intersection, and every face newly created is a convex polygon

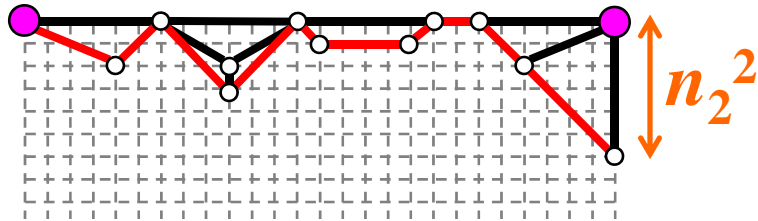


Algorithm

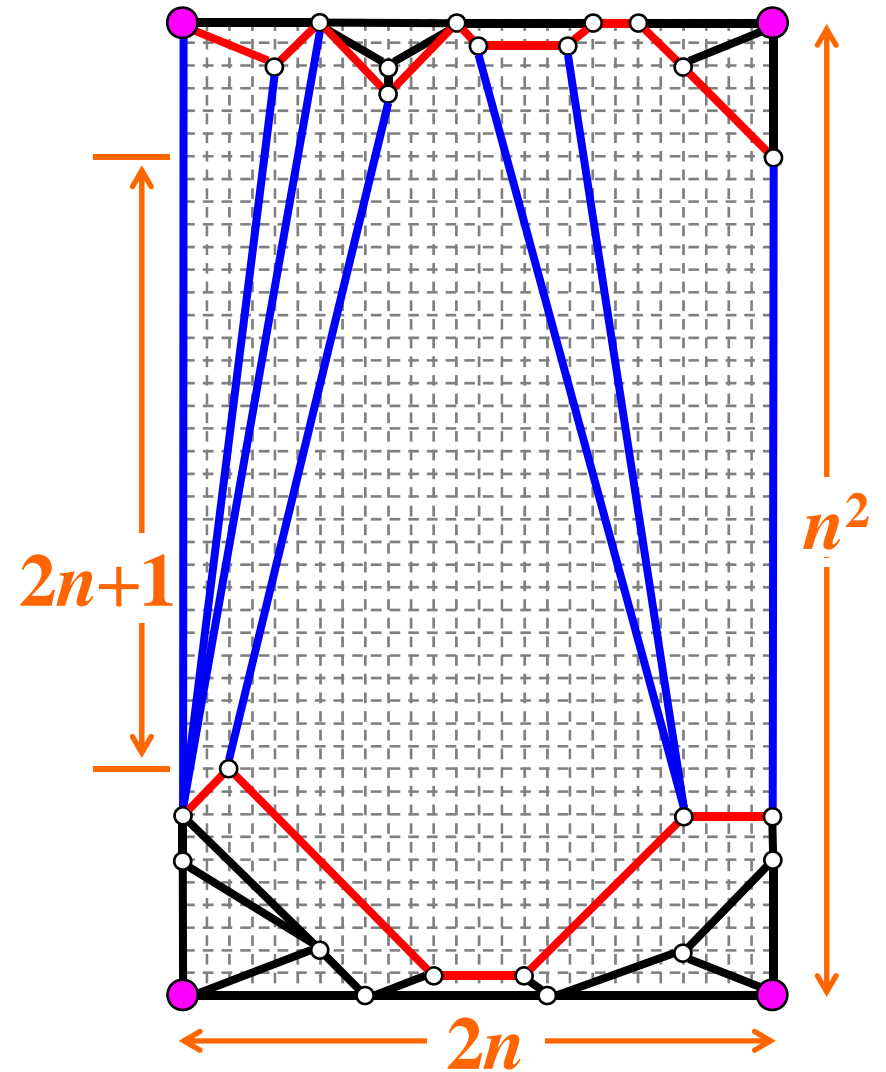
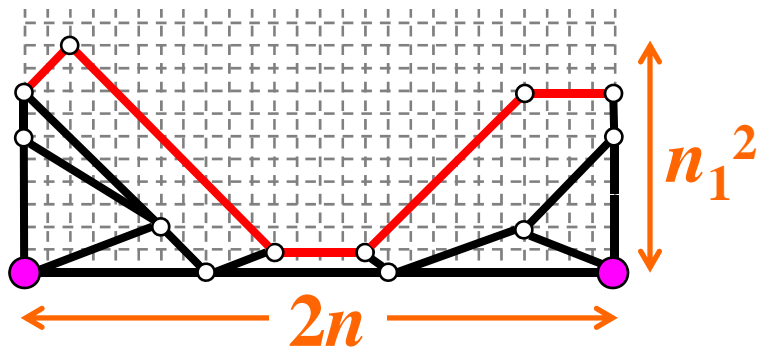
inner convex grid drawings



convex grid drawing

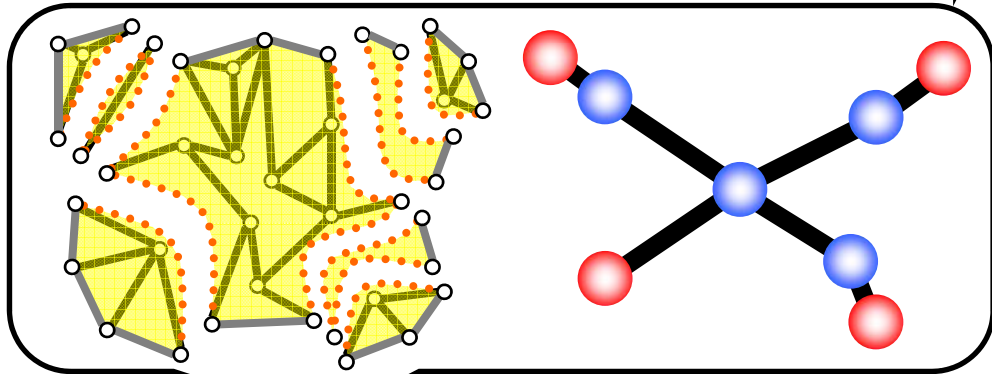


$$H = n_1^2 + 2n + 1 + n_2^2 < n^2$$

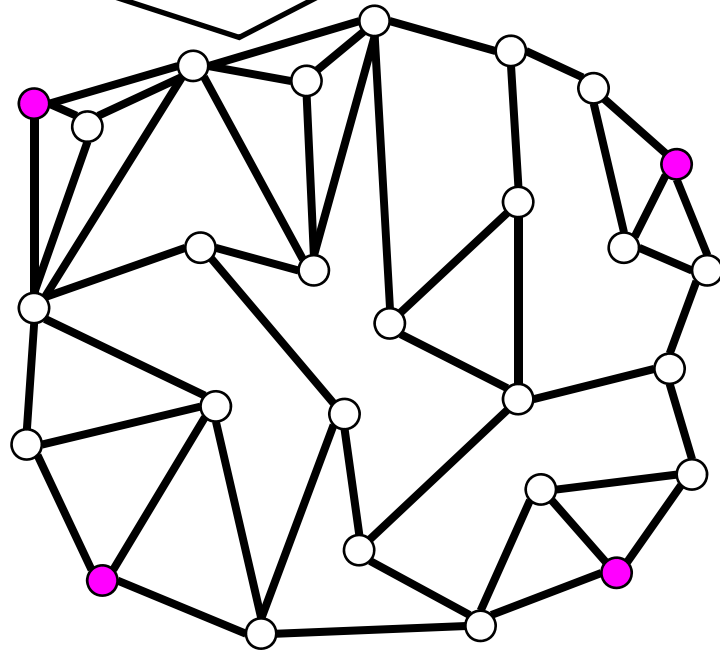


Conclusions

leaves = 4



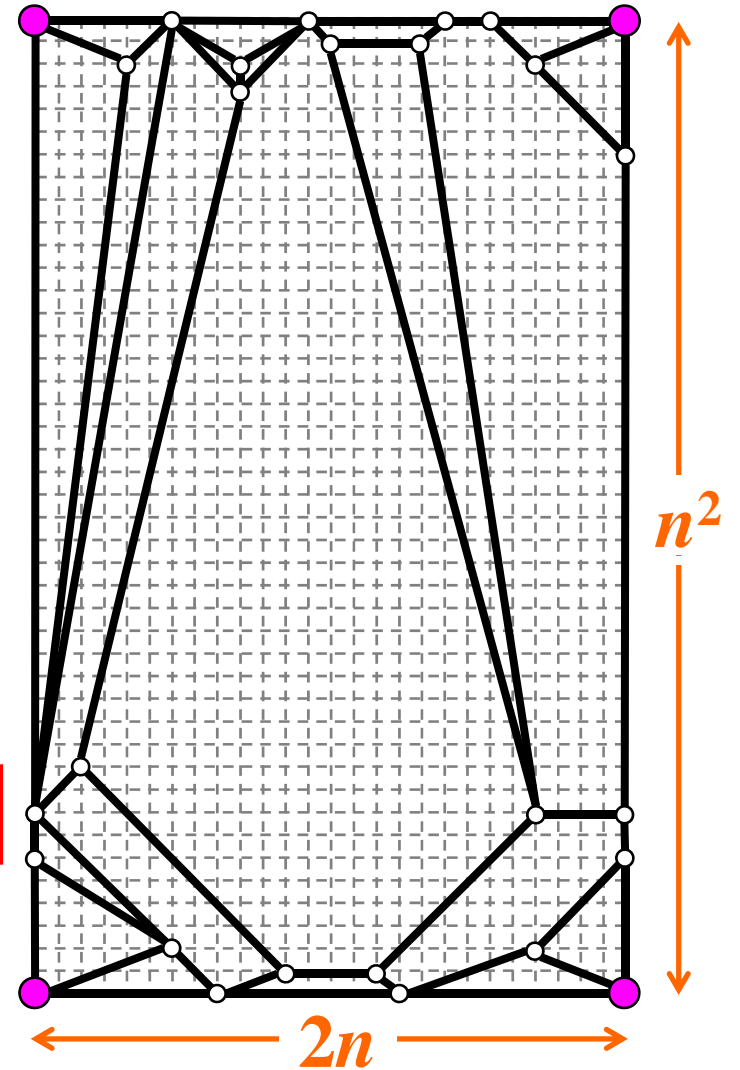
convex grid drawing



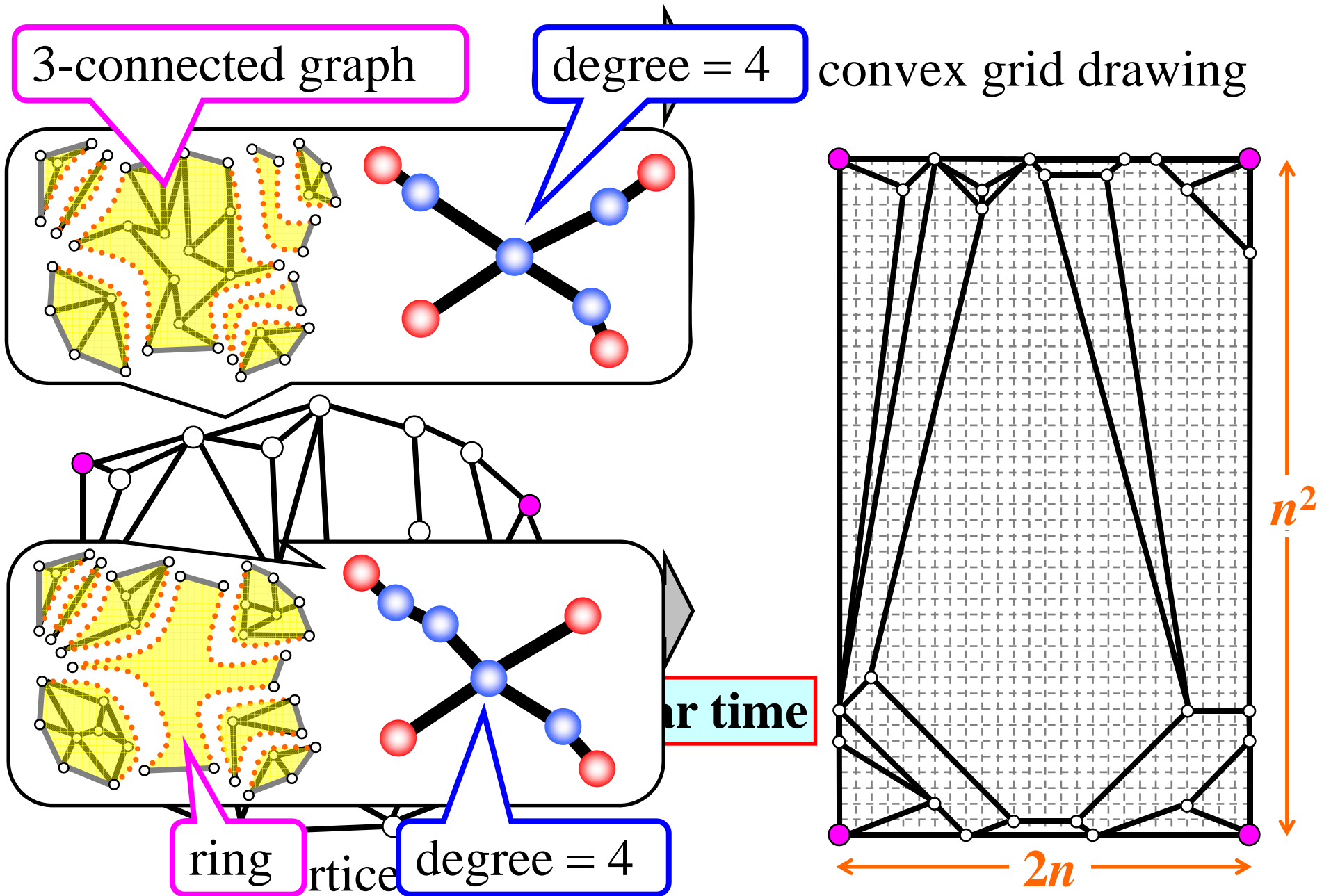
linear time



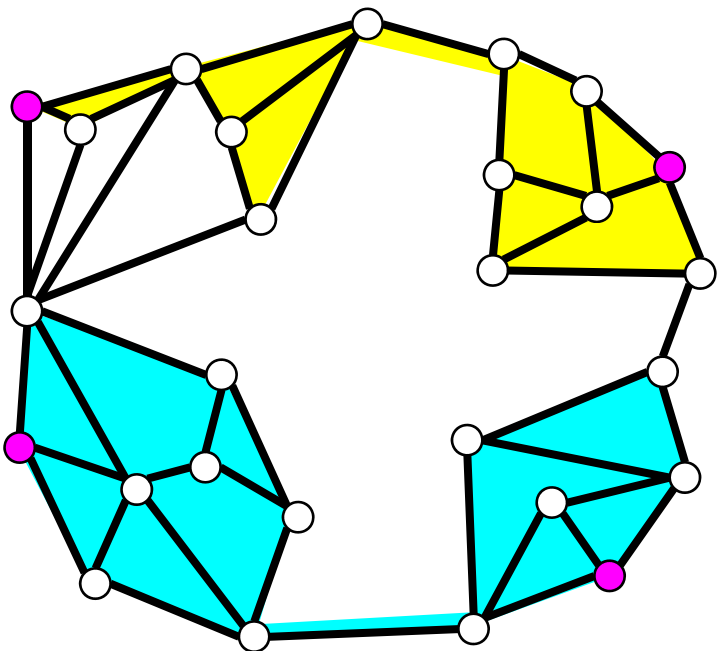
n vertices



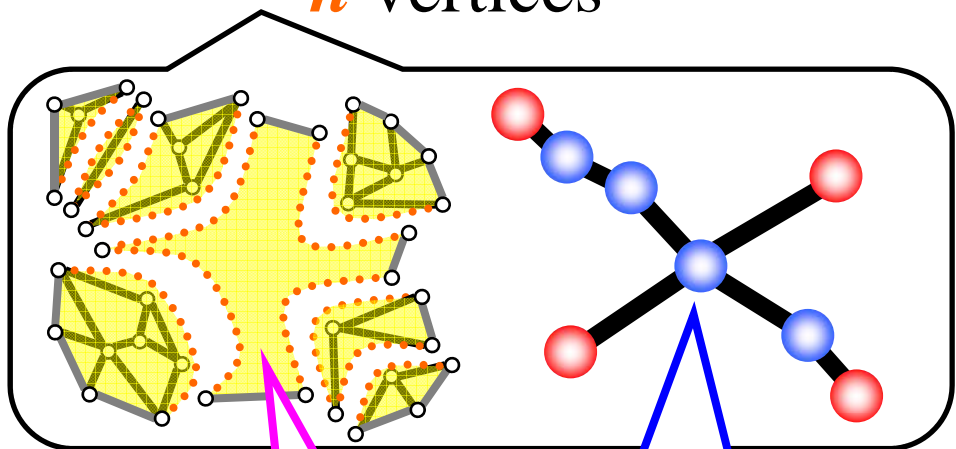
Conclusions



Conclusions

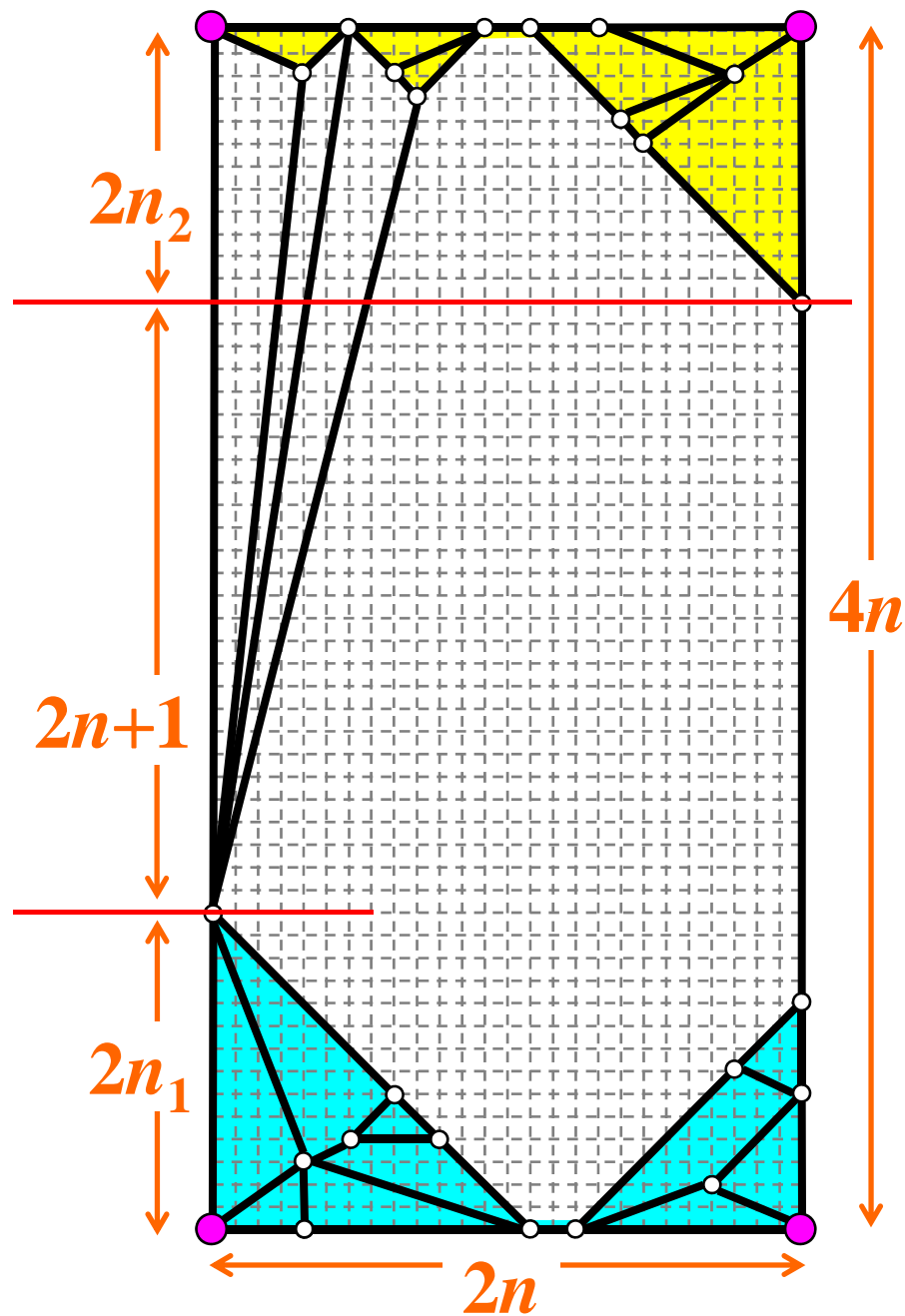


n vertices

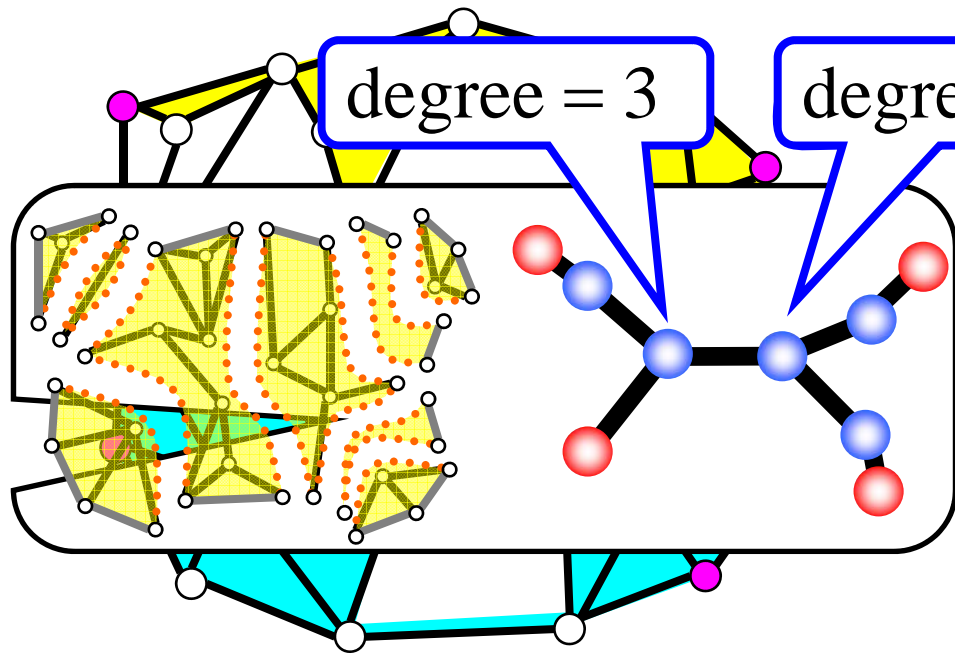


ring

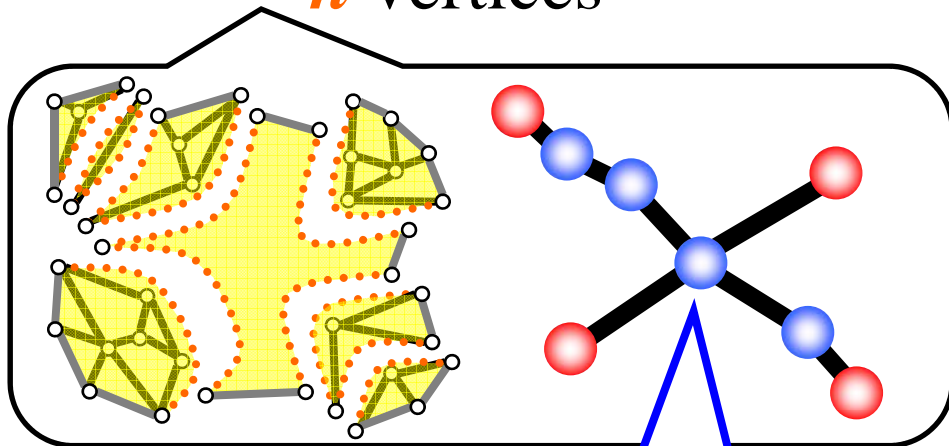
degree = 4



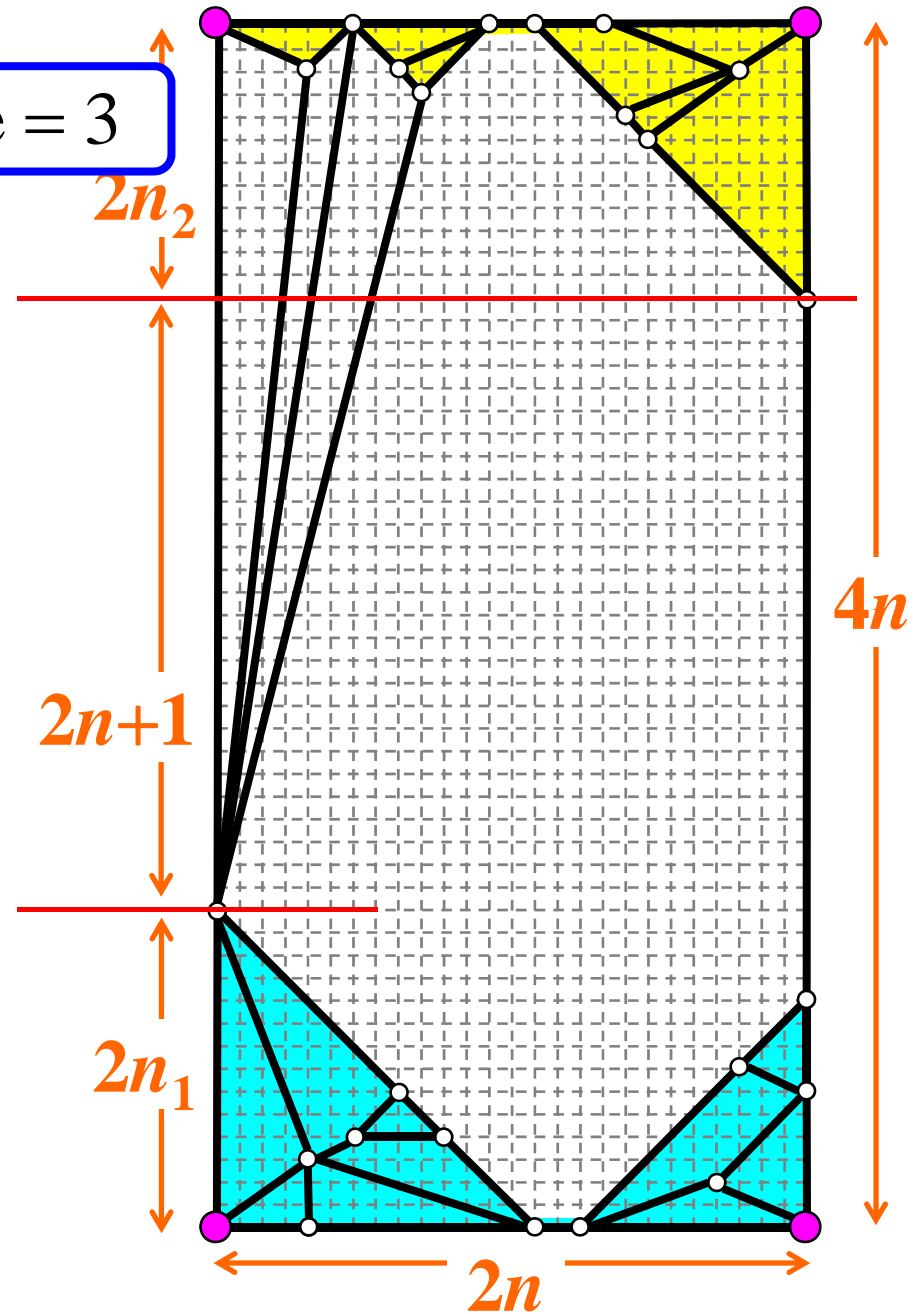
Conclusions



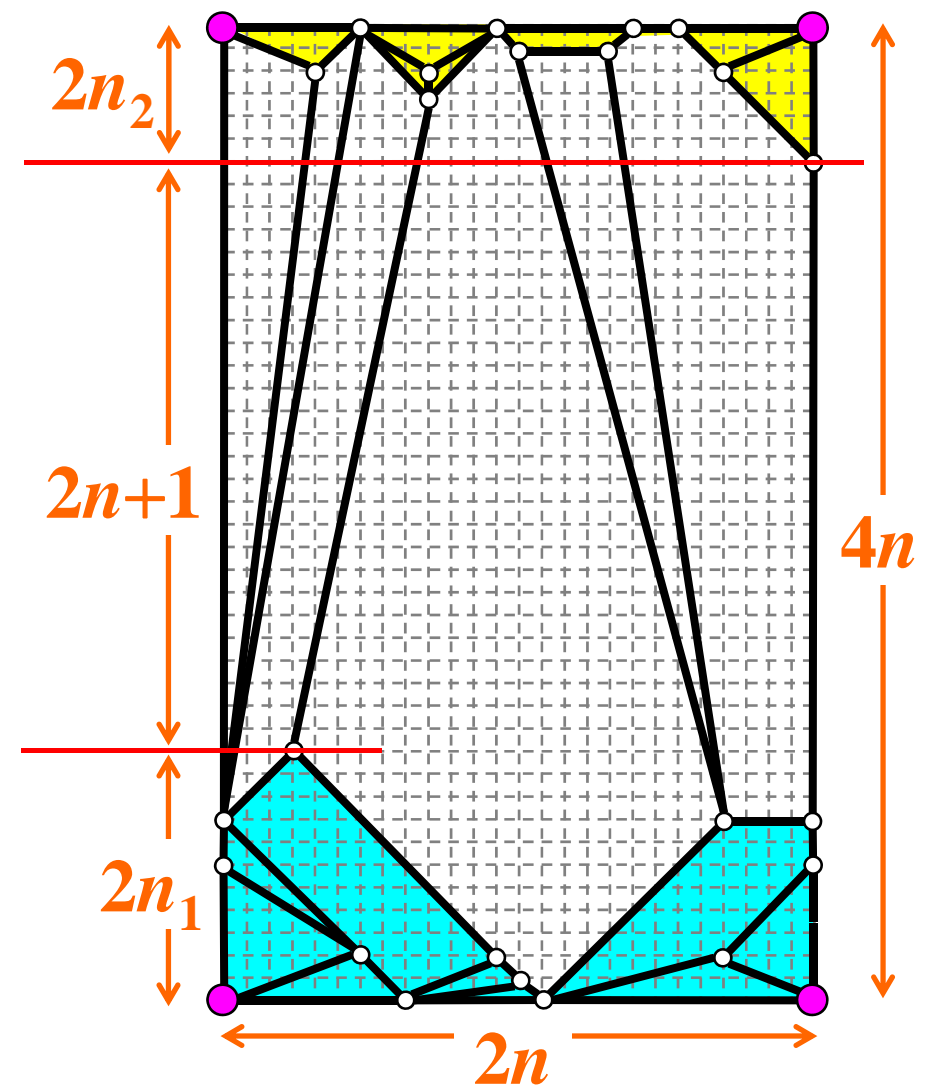
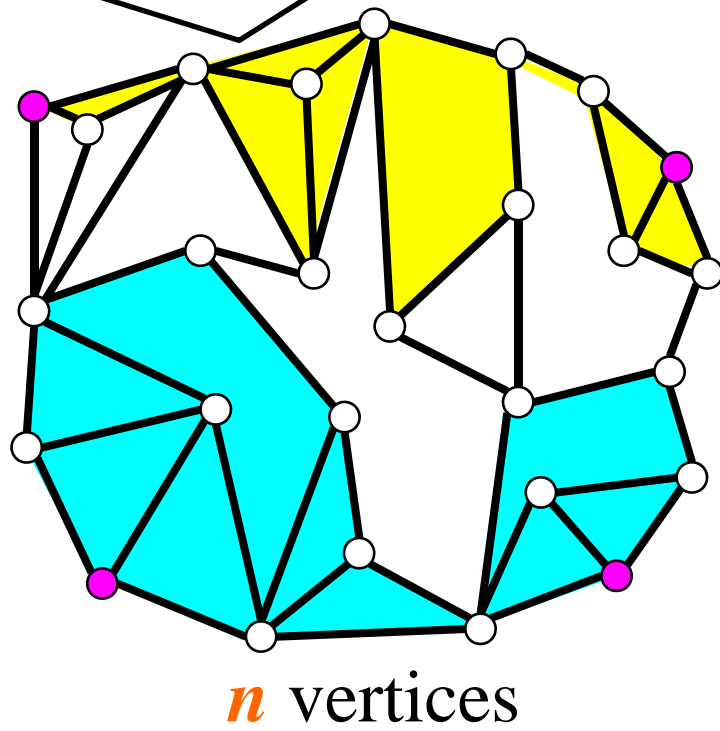
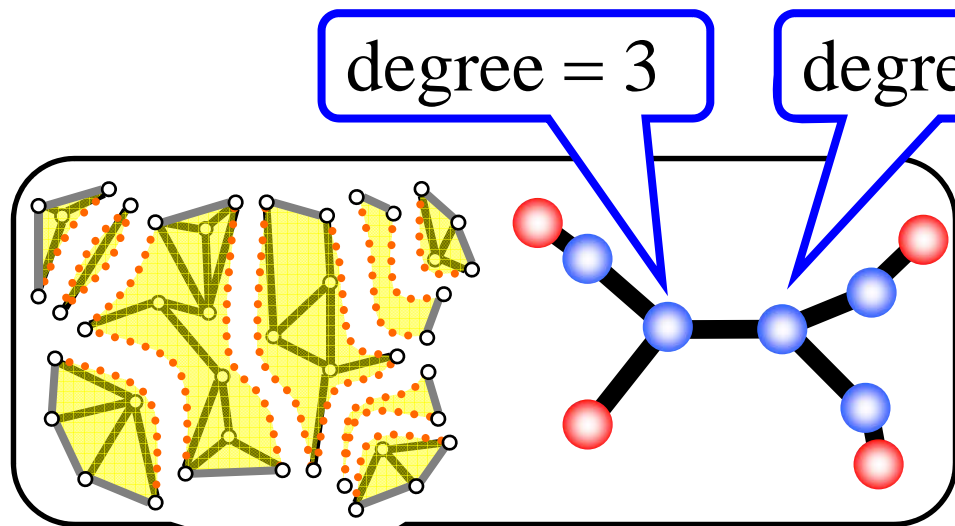
n vertices



degree = 4



Conclusions



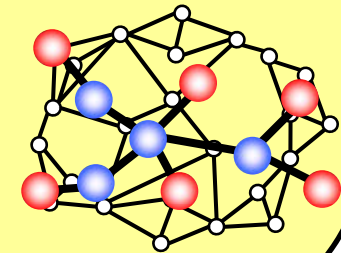
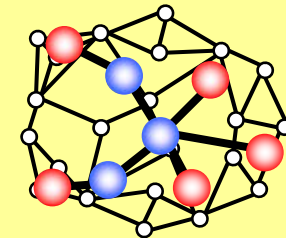
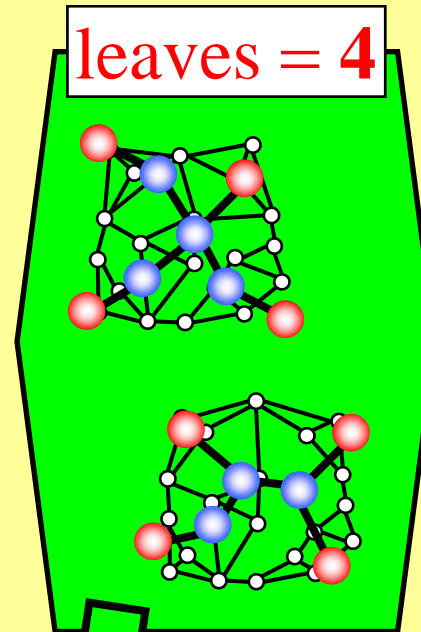
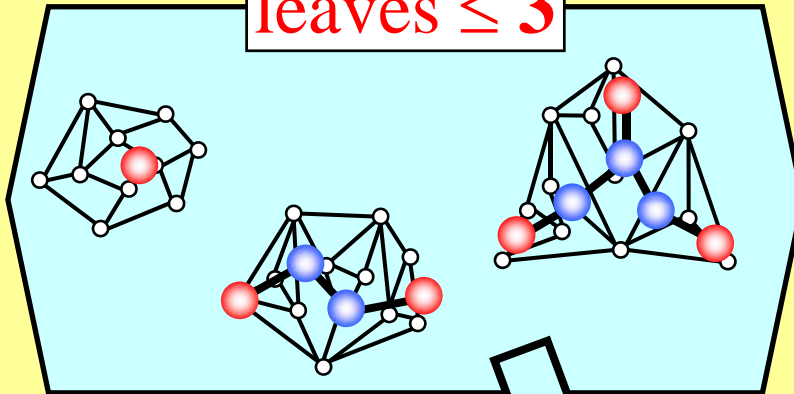
Open problem

internally 3-connected

leaves ≥ 5 : open problem

leaves ≤ 3

leaves = 4



known results (2)

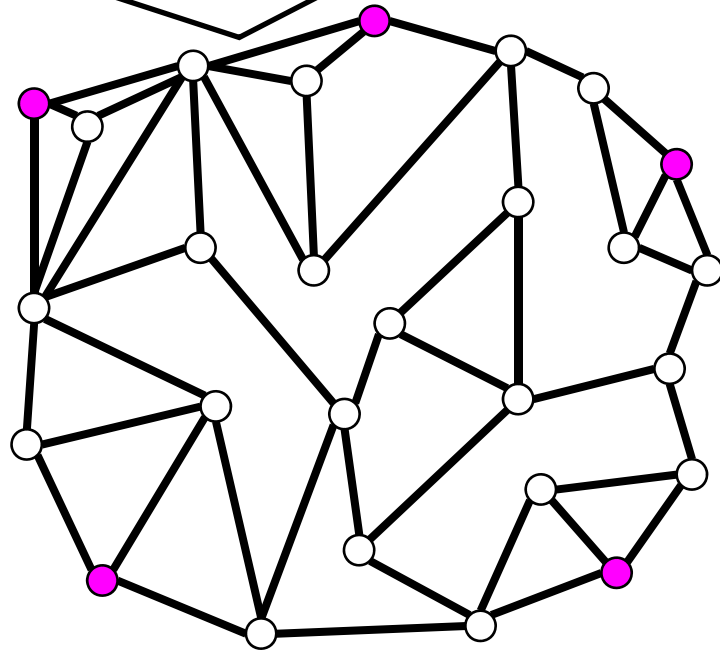
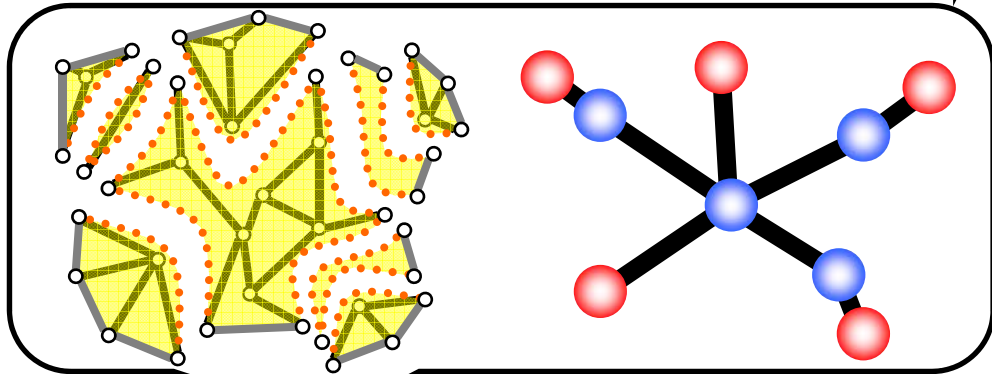
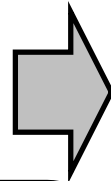
our result

convex grid drawing

$2n \times n^2$ size

Open problem

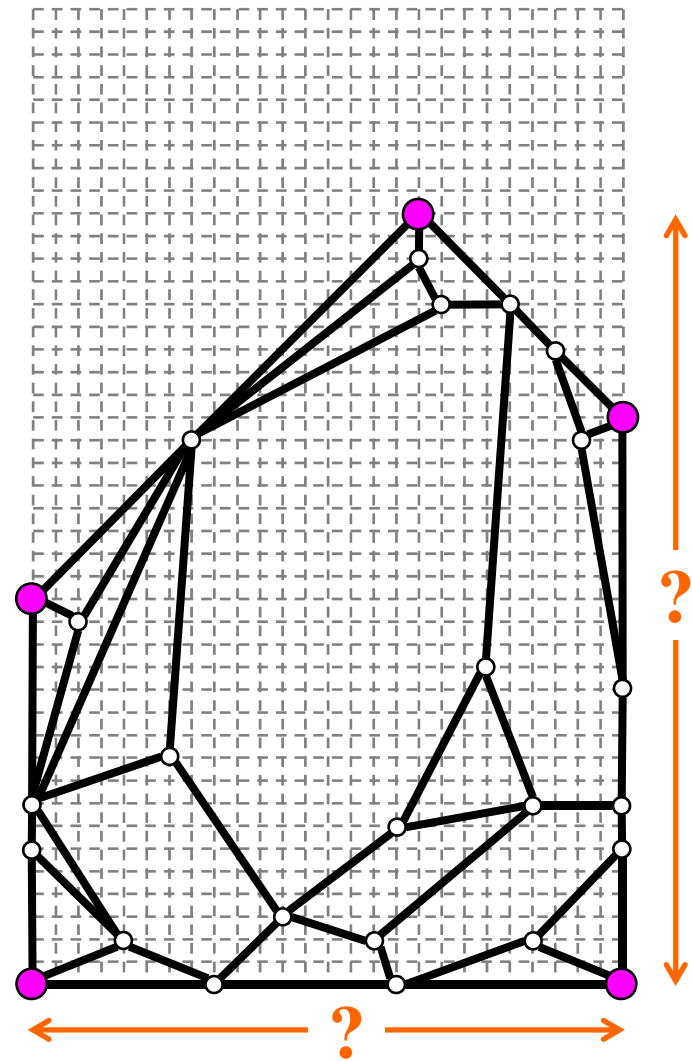
leaves = 5



n vertices



convex grid drawing



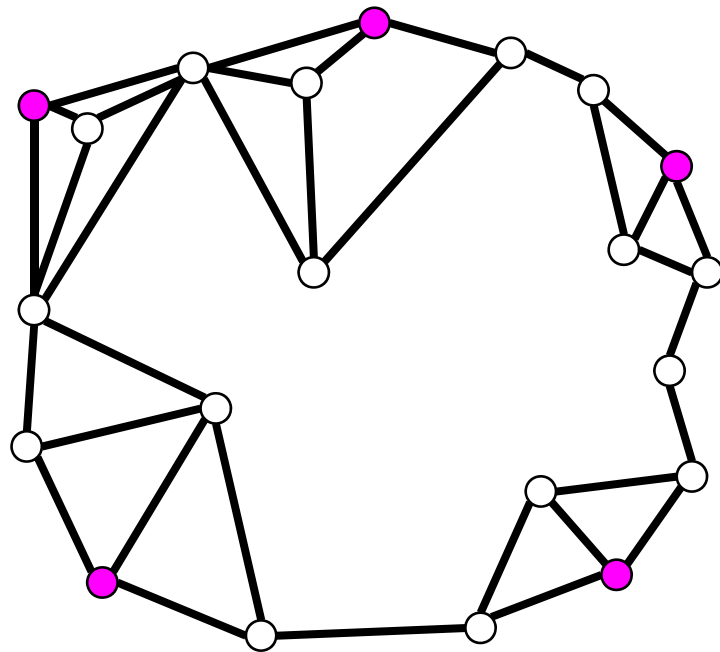


Open problem

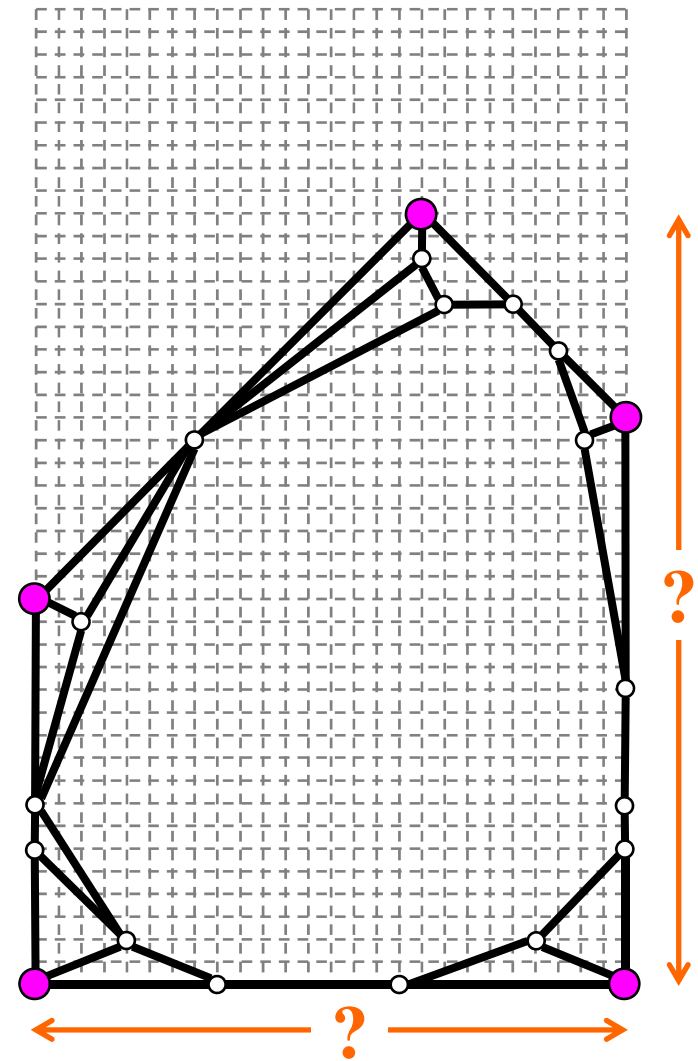
leaves = 5



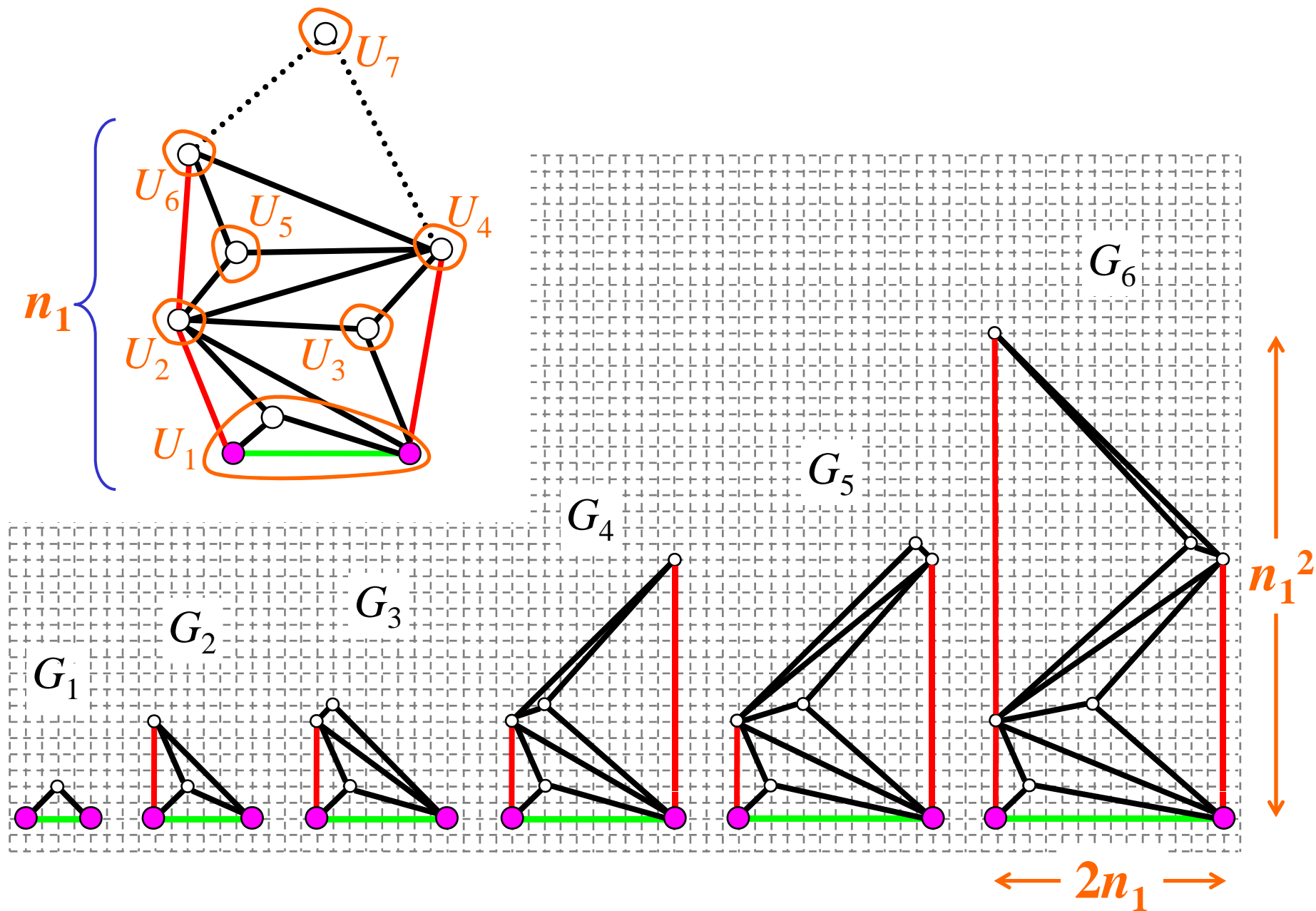
convex grid drawing



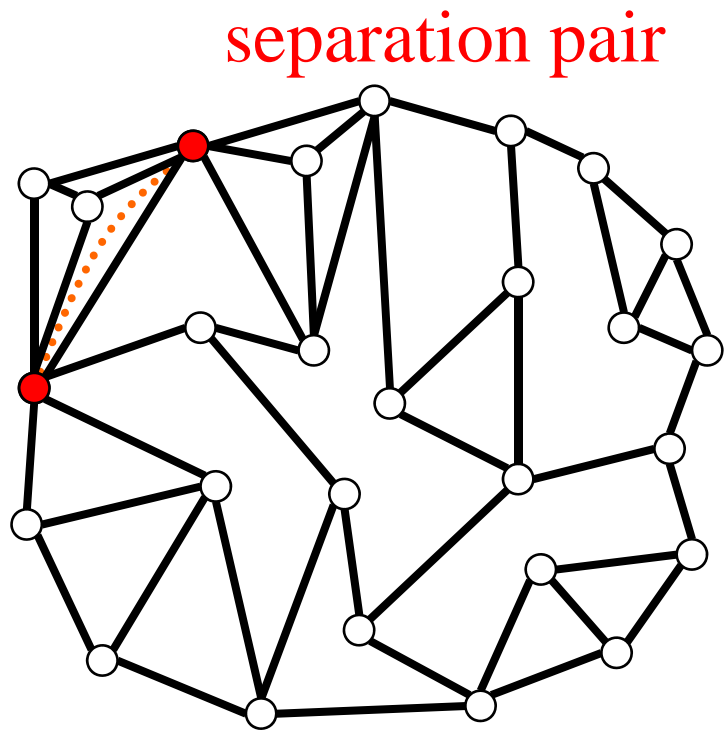
n vertices



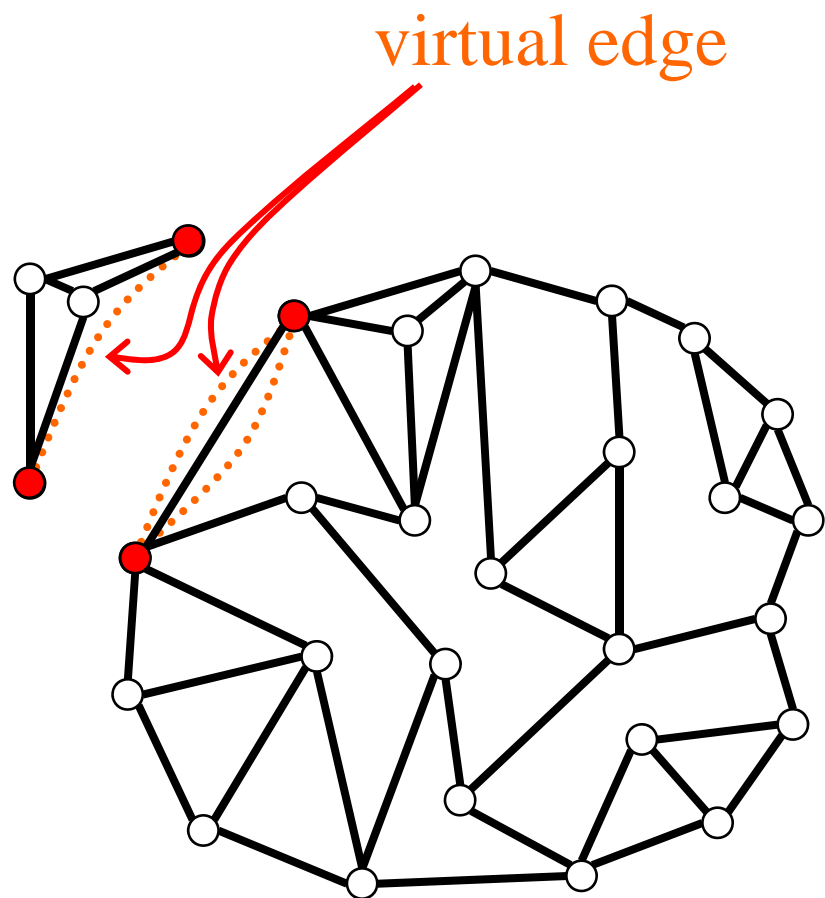
Grid size



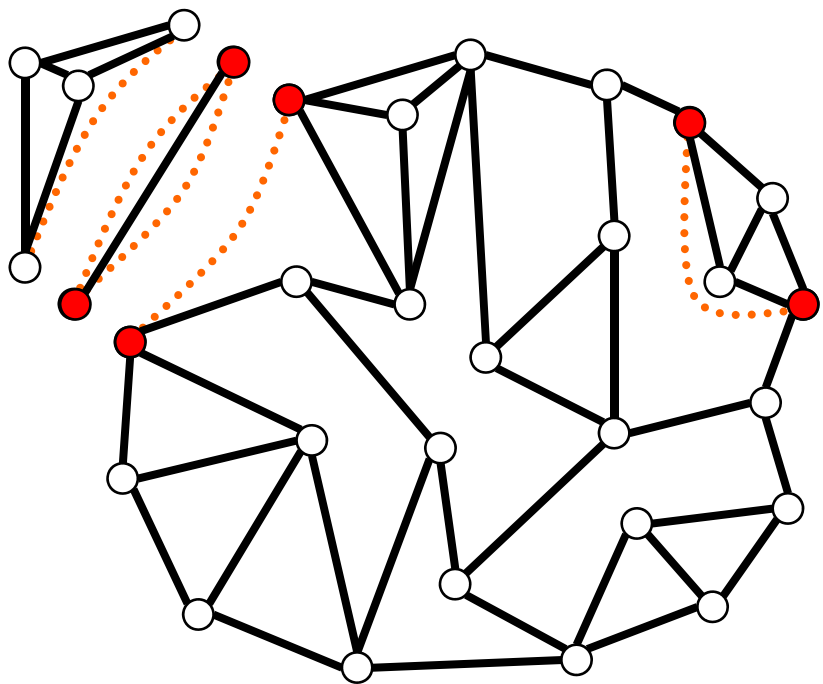
Decomposition tree



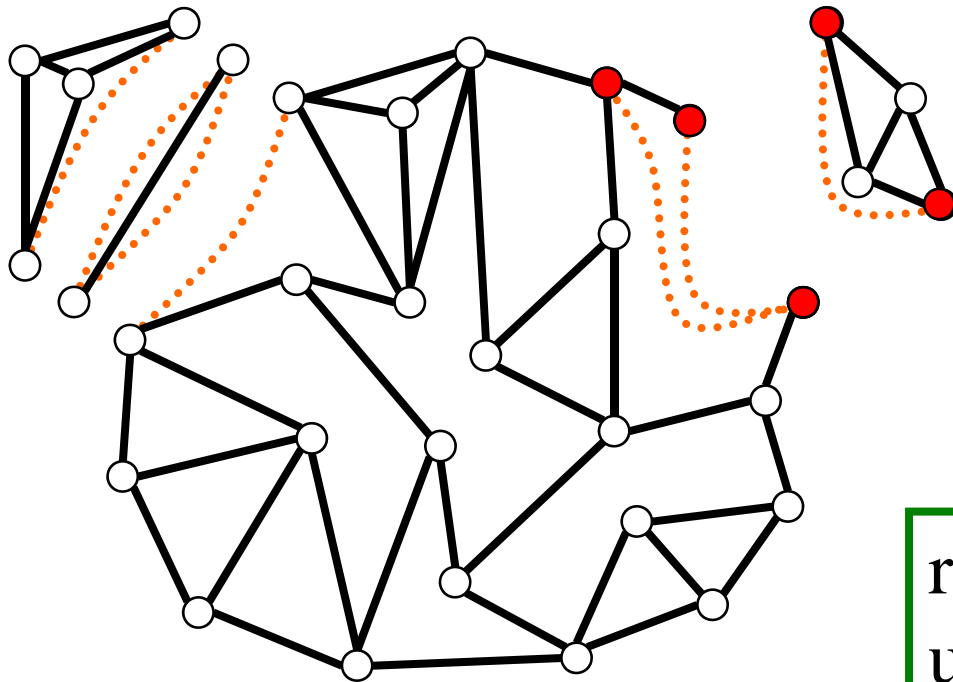
Decomposition tree



Decomposition tree

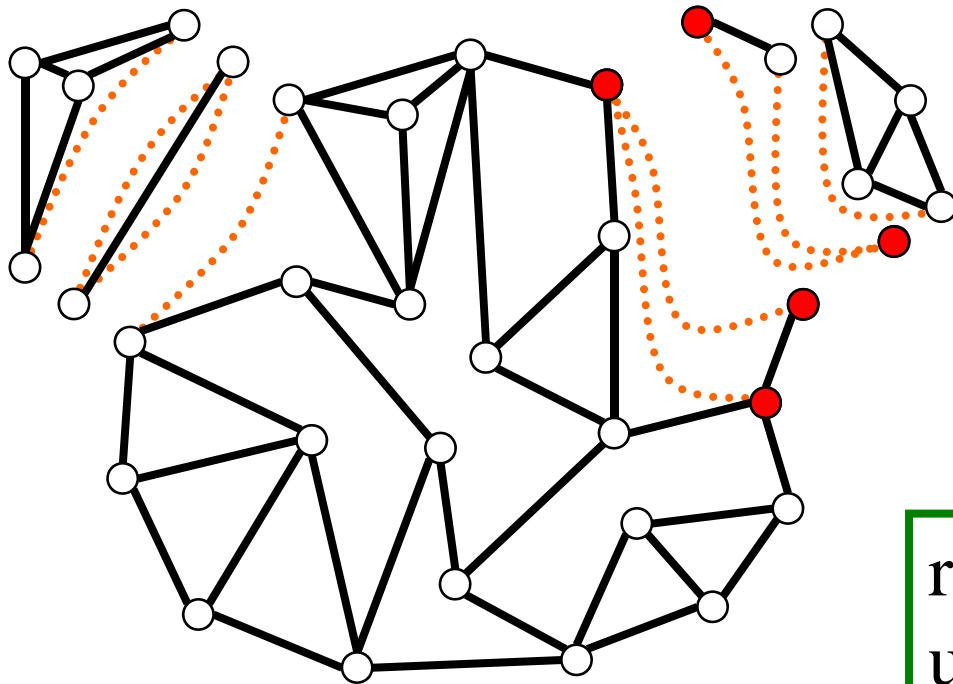


Decomposition tree



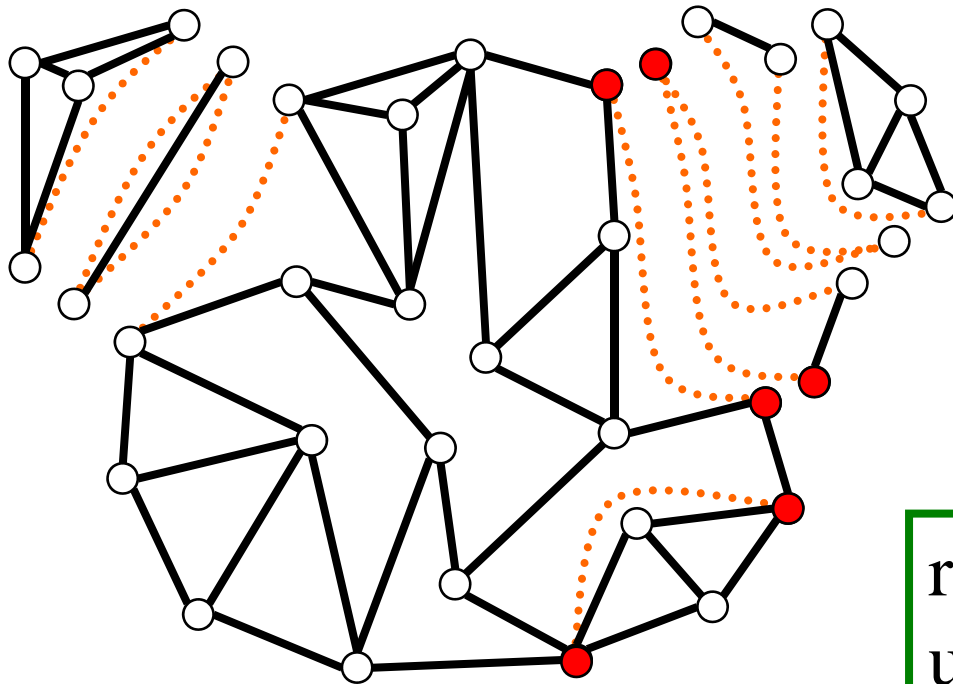
repeat this operation
until no more splits are possible

Decomposition tree



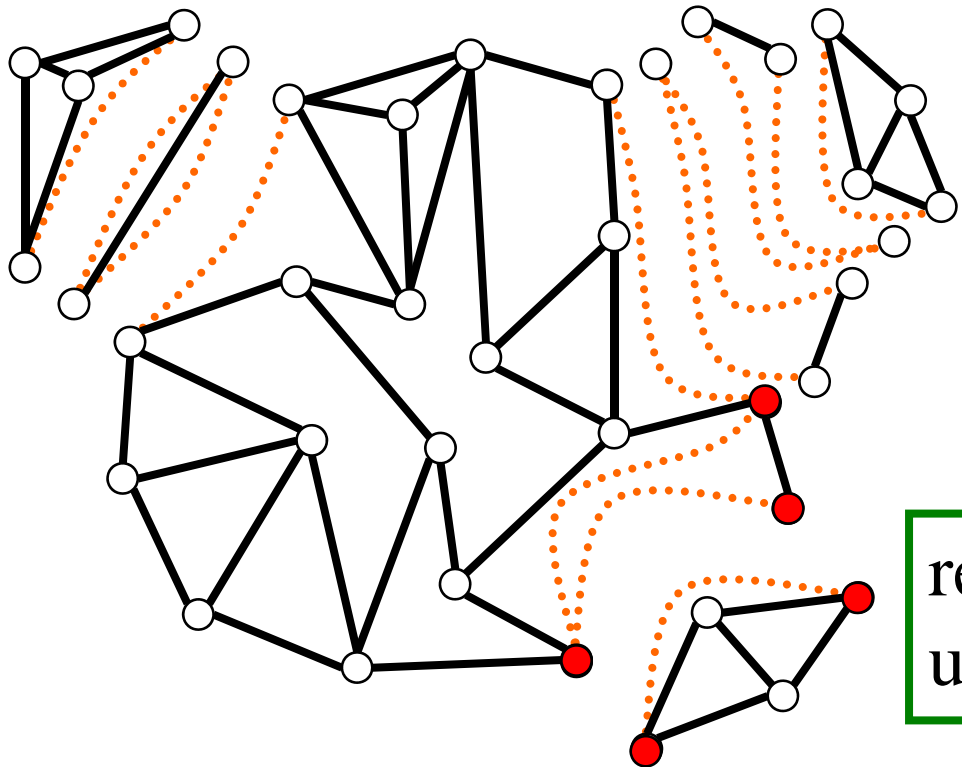
repeat this operation
until no more splits are possible

Decomposition tree



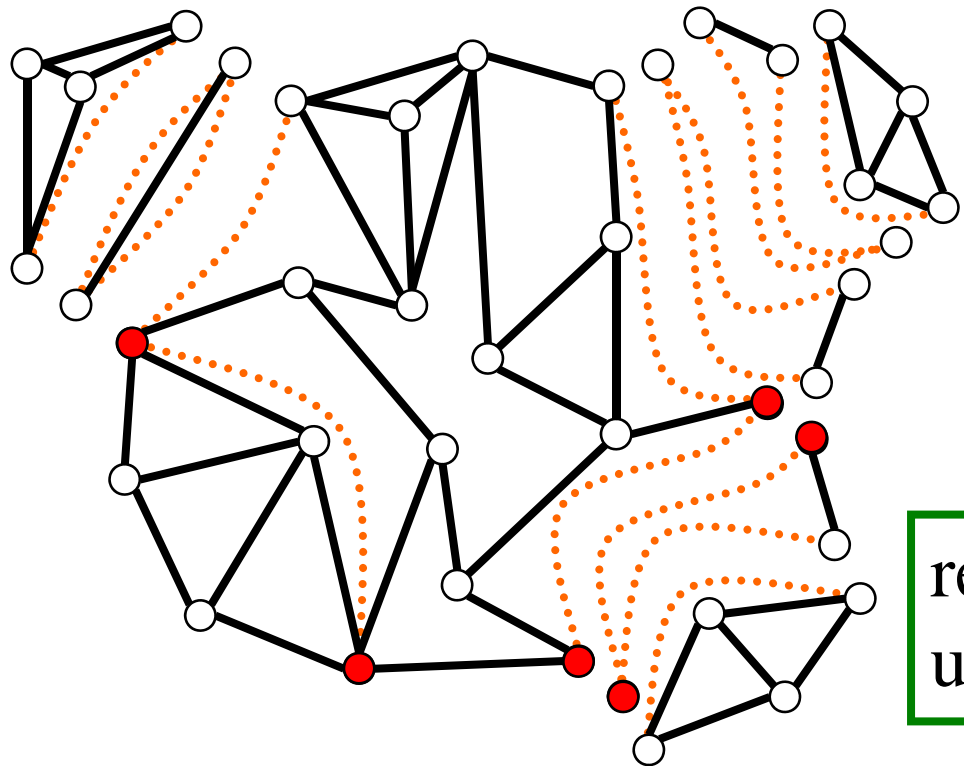
repeat this operation
until no more splits are possible

Decomposition tree



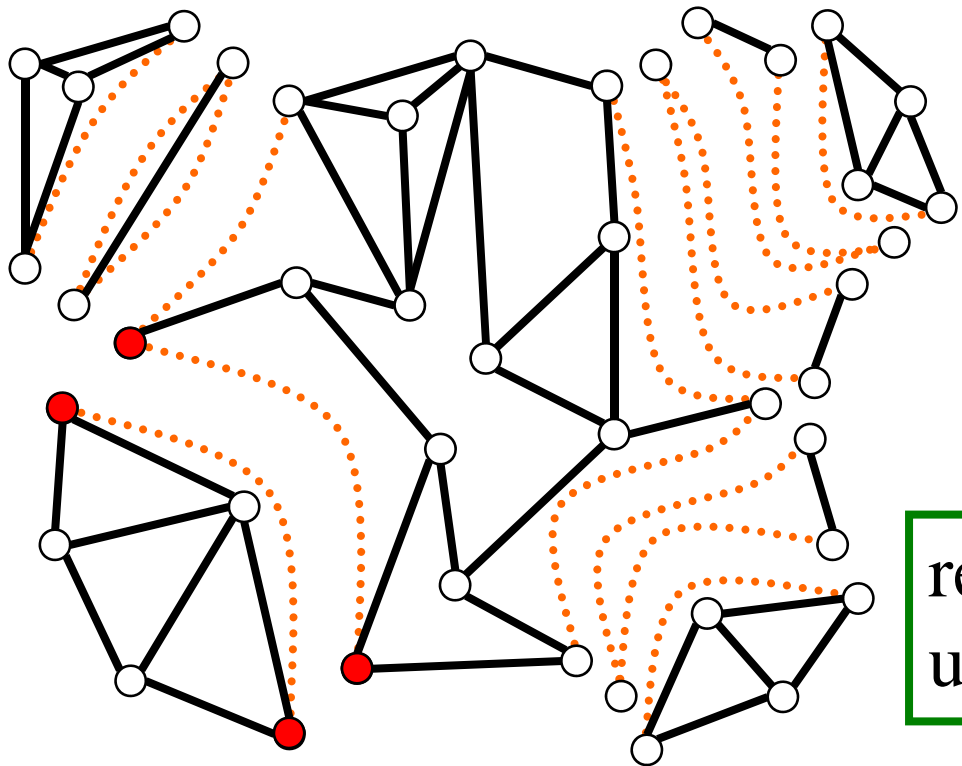
repeat this operation
until no more splits are possible

Decomposition tree



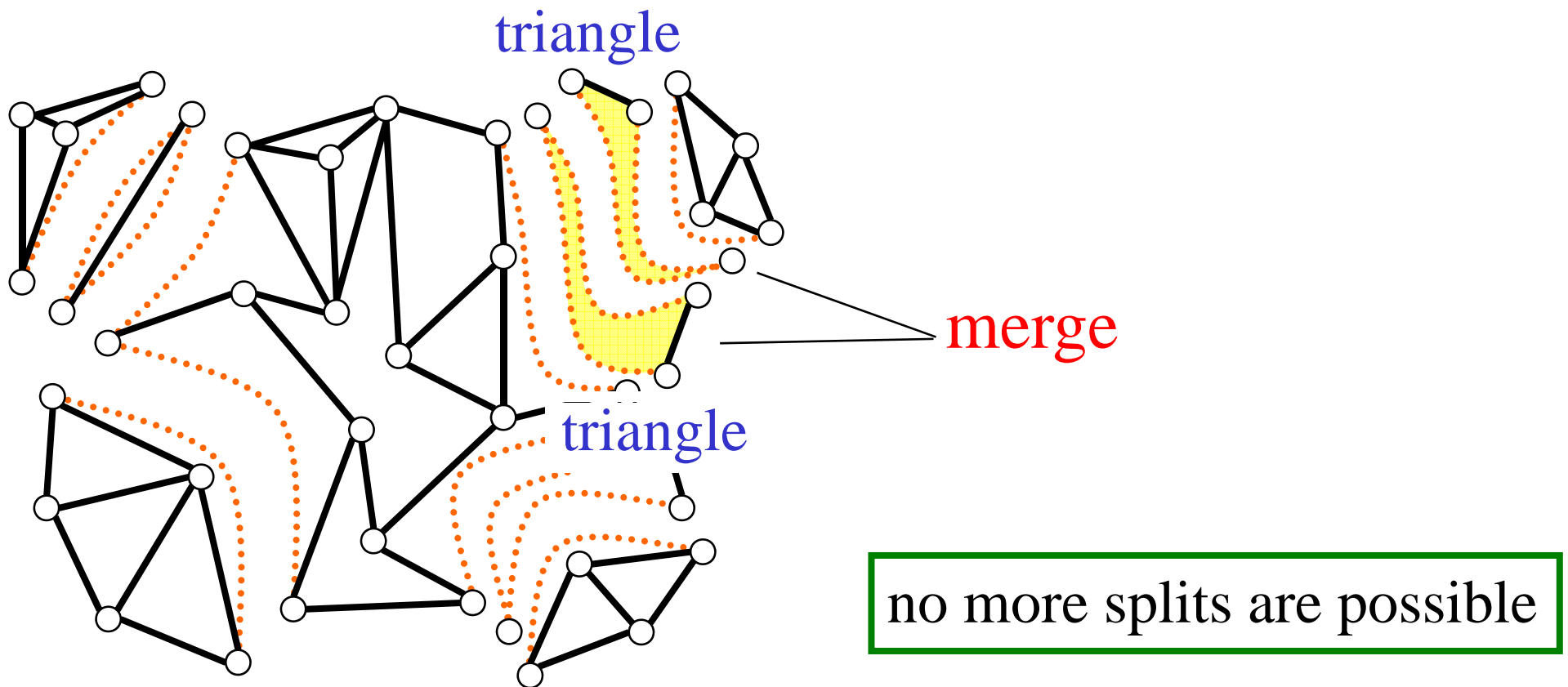
repeat this operation
until no more splits are possible

Decomposition tree

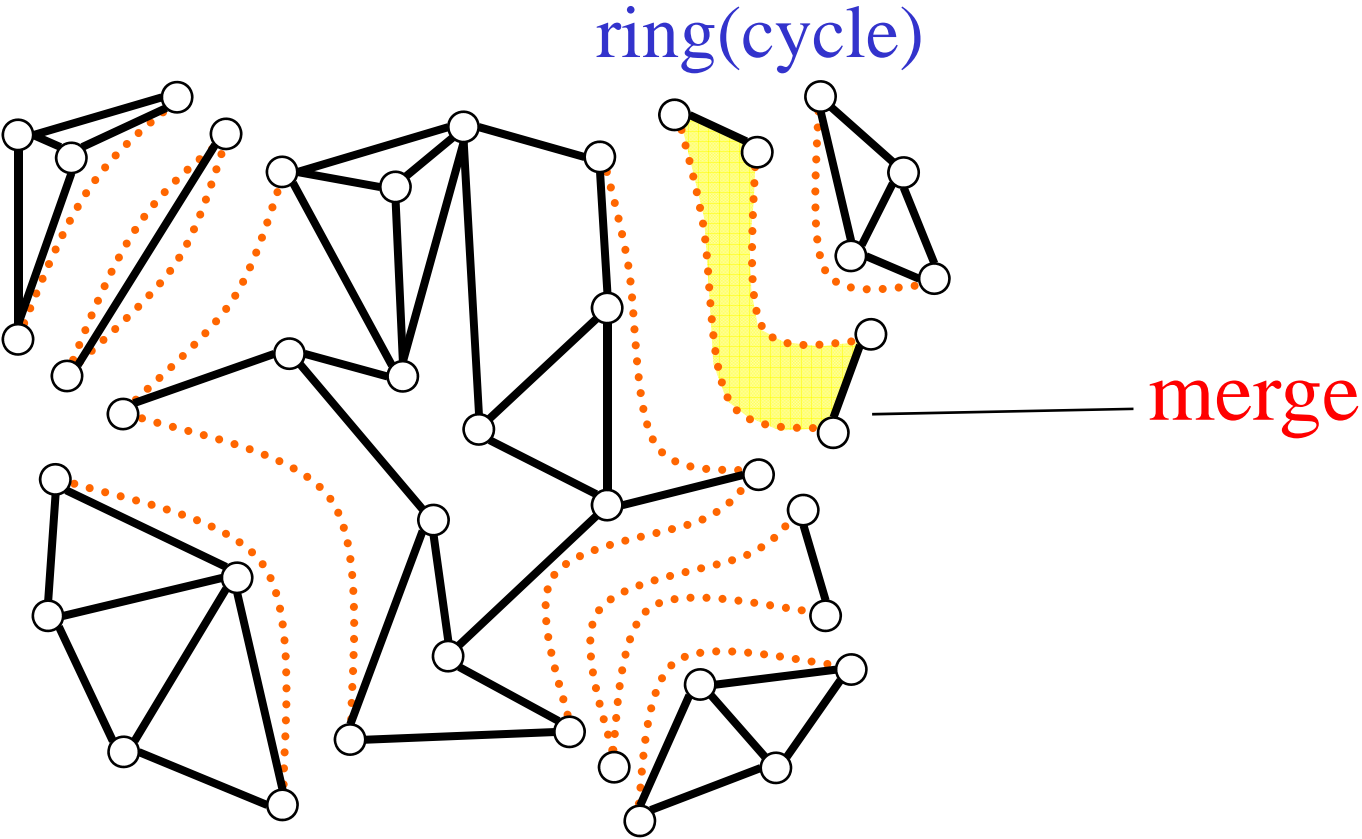


repeat this operation
until no more splits are possible

Decomposition tree

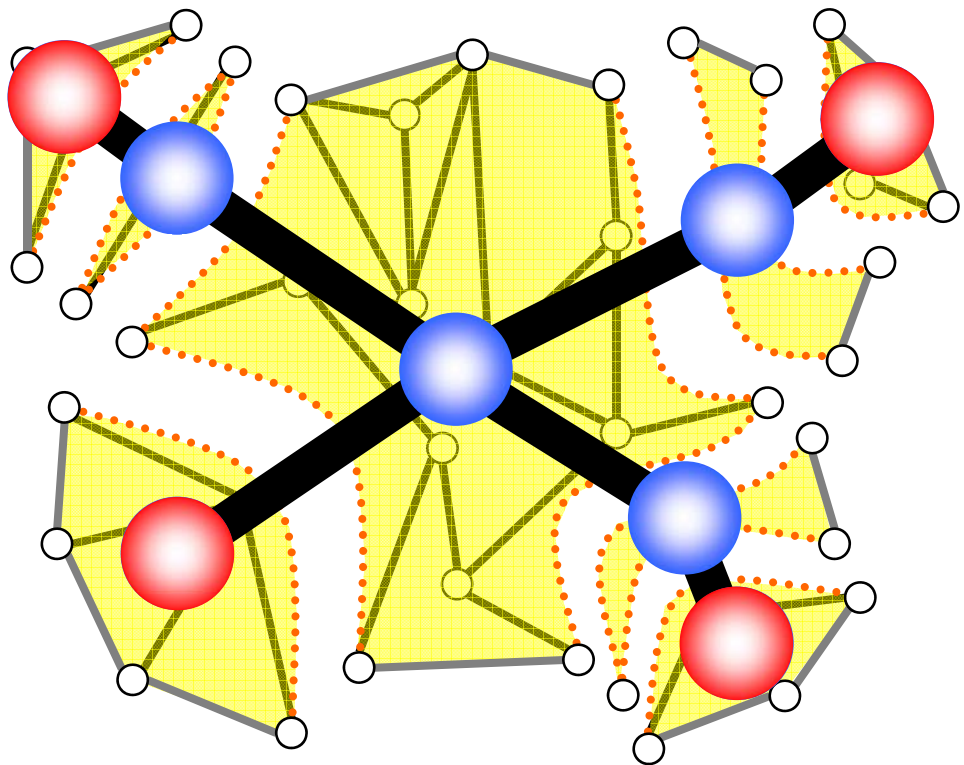


Decomposition tree



Decomposition tree

3-connected component decomposition tree [HT73]

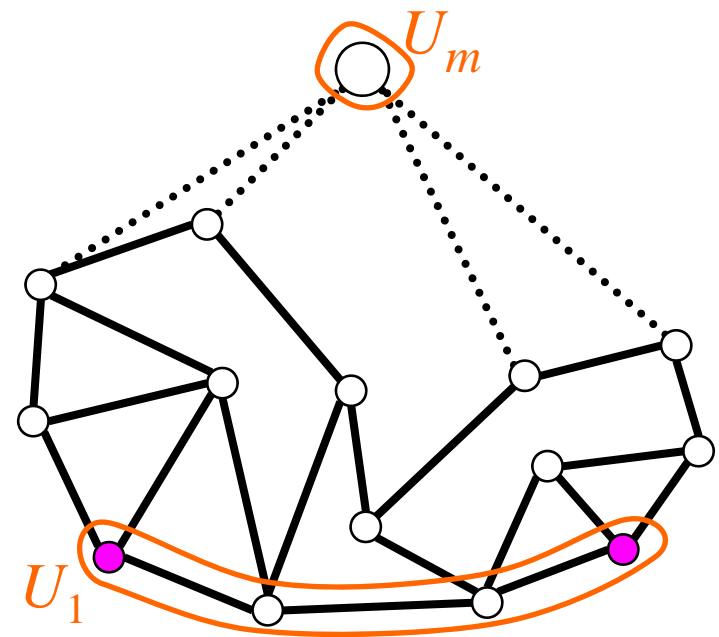


● : leaf

Canonical decomposition

canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

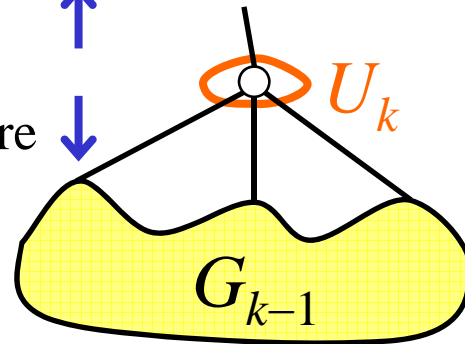


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

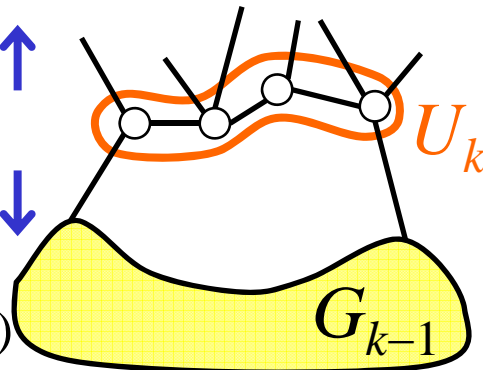
one or more
(each vertex)



exactly one

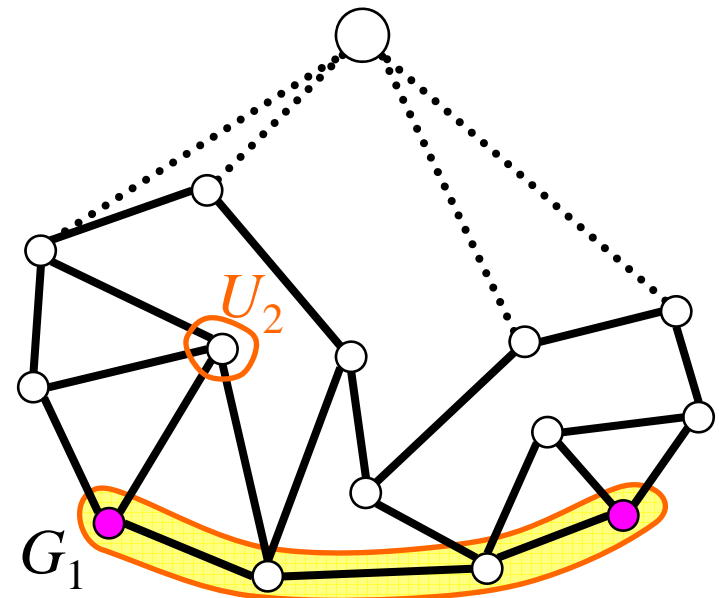


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

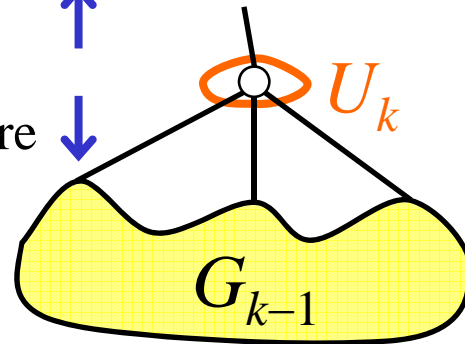


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

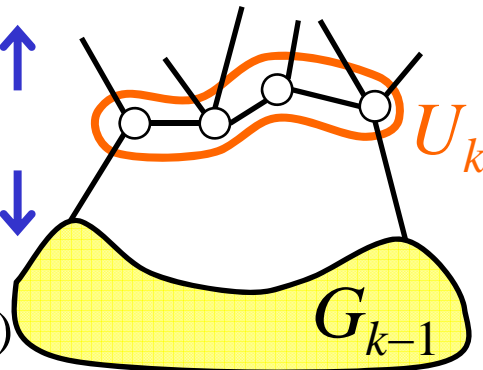
one or more
(each vertex)



exactly one

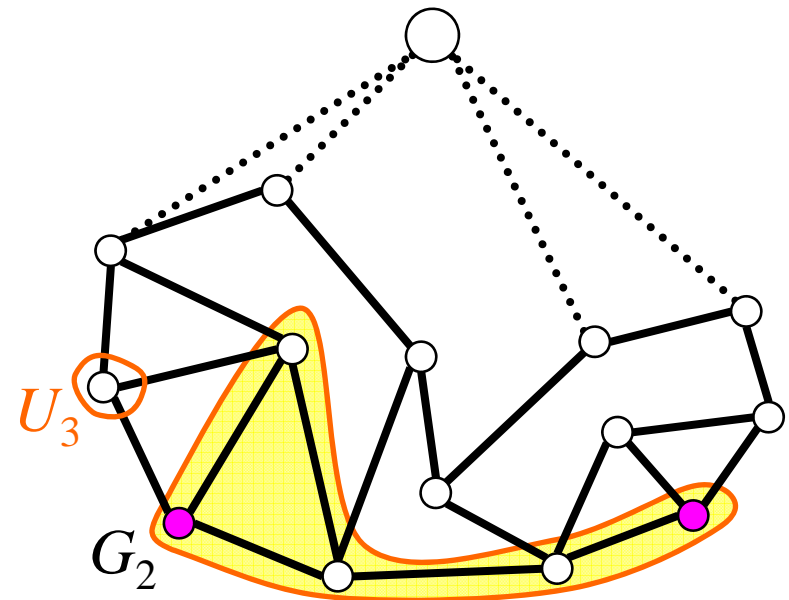


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

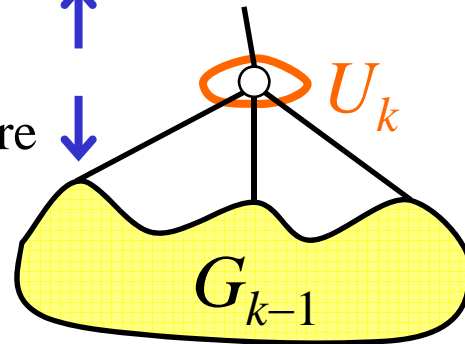


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

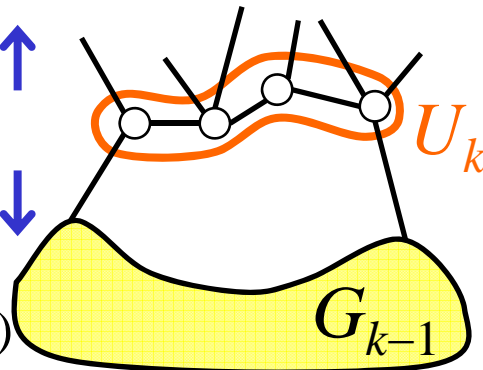
one or more
(each vertex)



exactly one

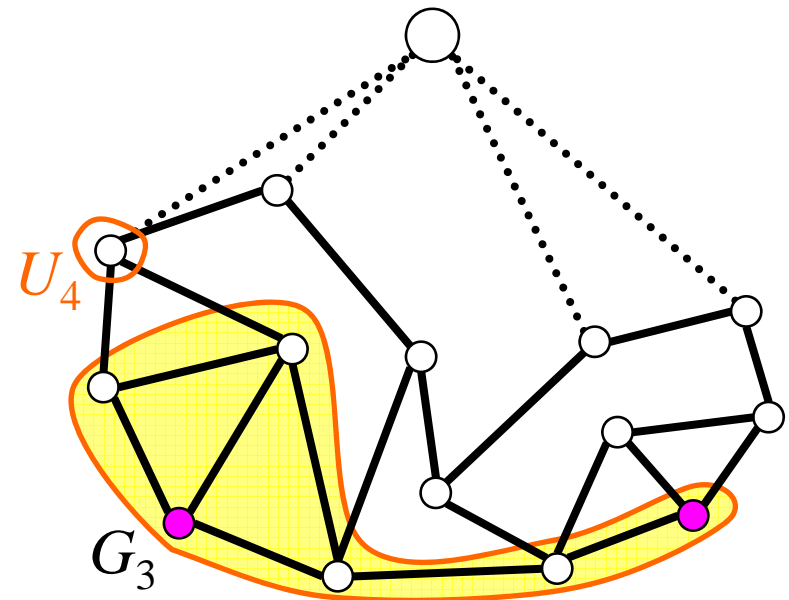


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

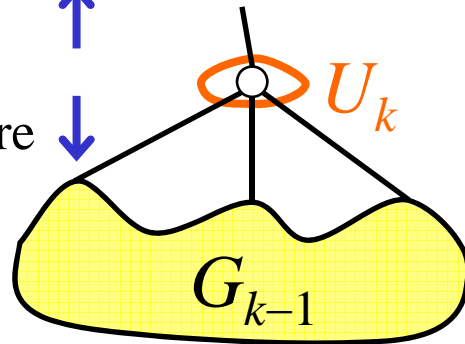


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

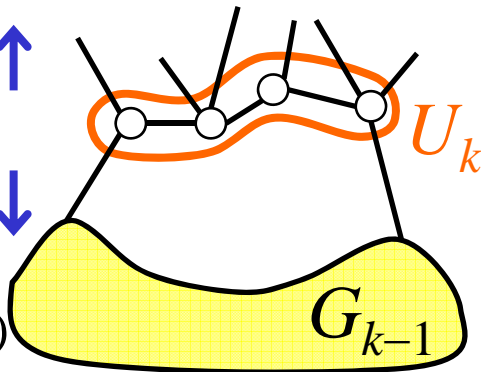
one or more
(each vertex)



exactly one

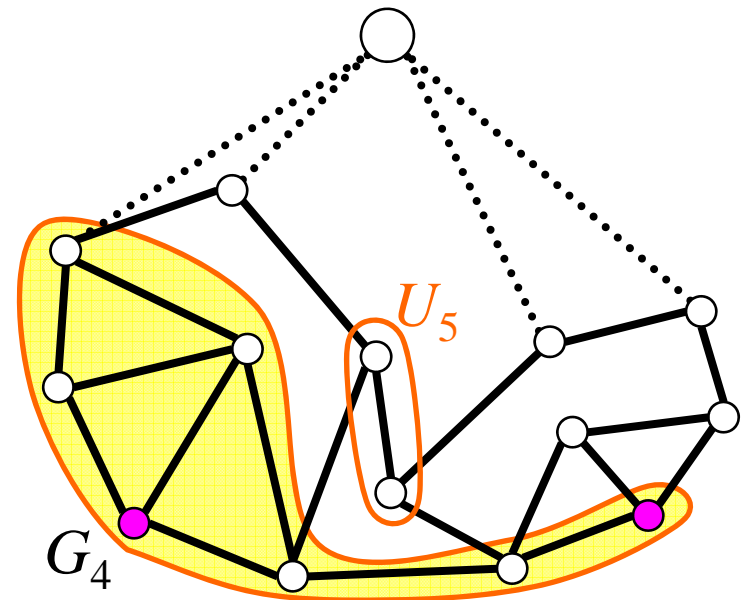


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

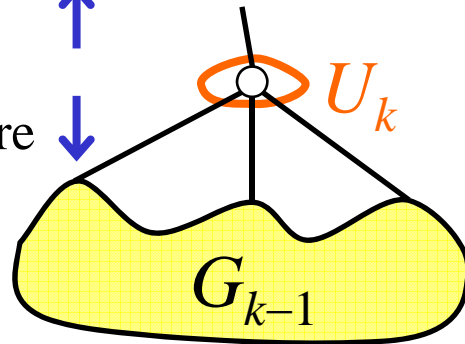


Canonical decomposition

one or more
neighbors



two or more



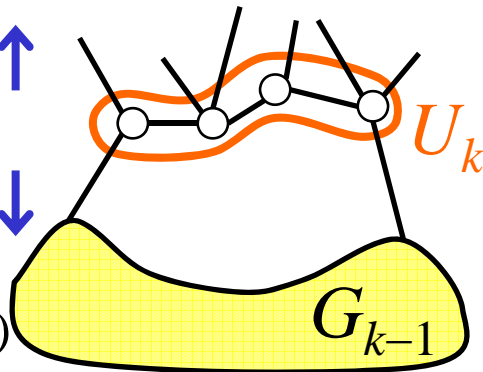
canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

one or more
(each vertex)

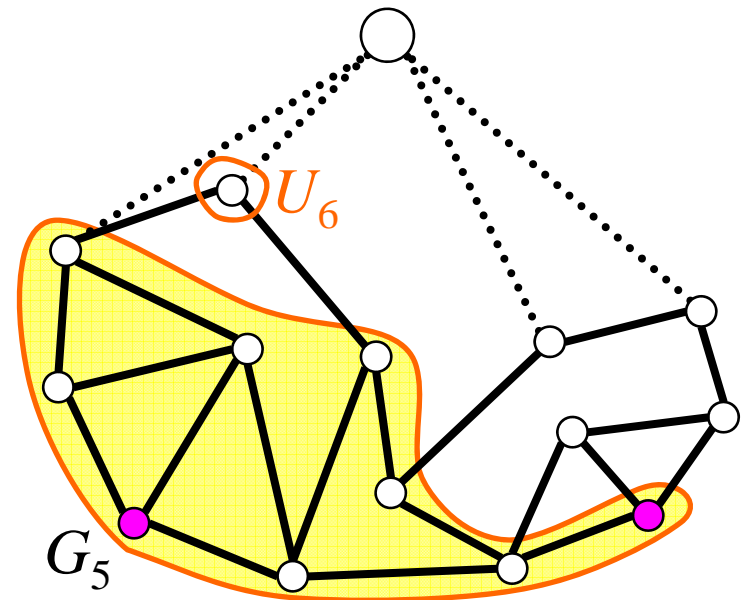


exactly one
(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

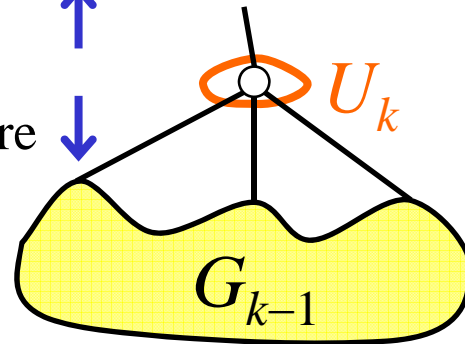


Canonical decomposition

one or more
neighbors



two or more



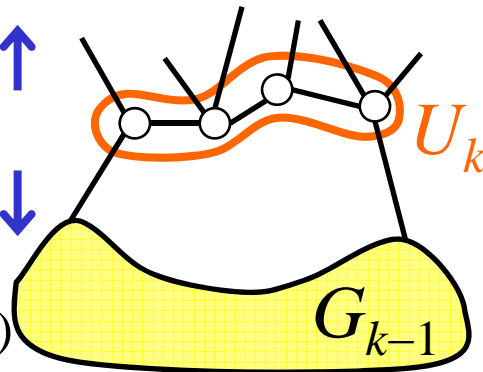
canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

one or more
(each vertex)

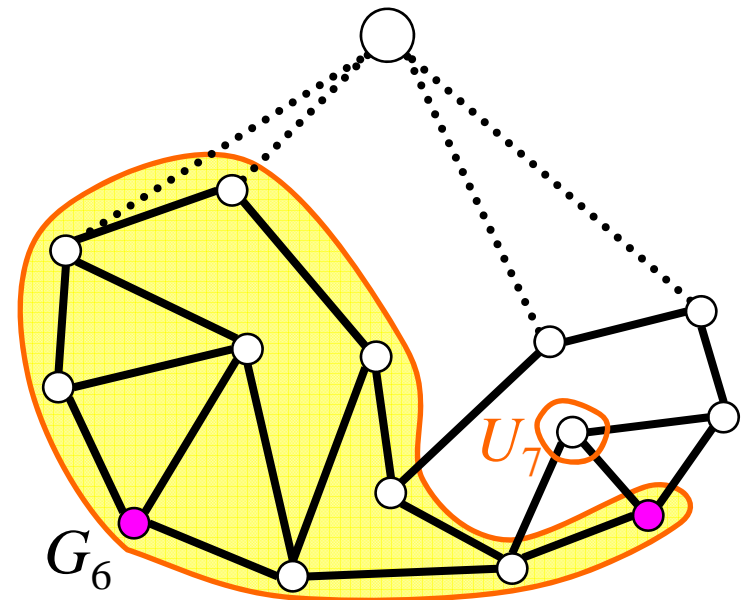


exactly one
(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

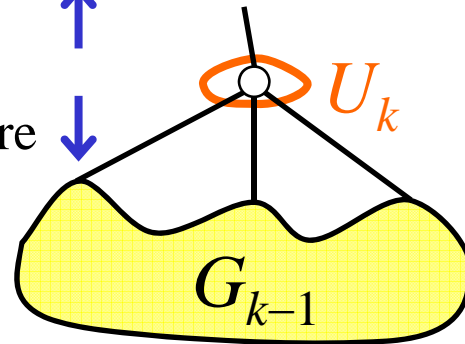


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

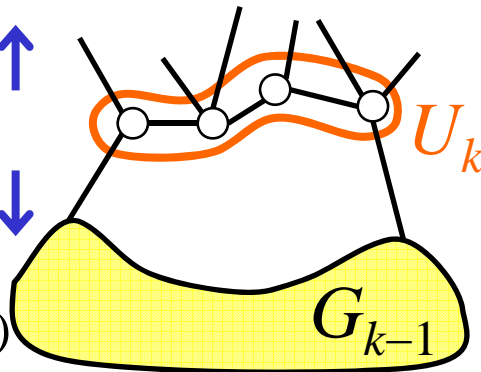
one or more
(each vertex)



exactly one

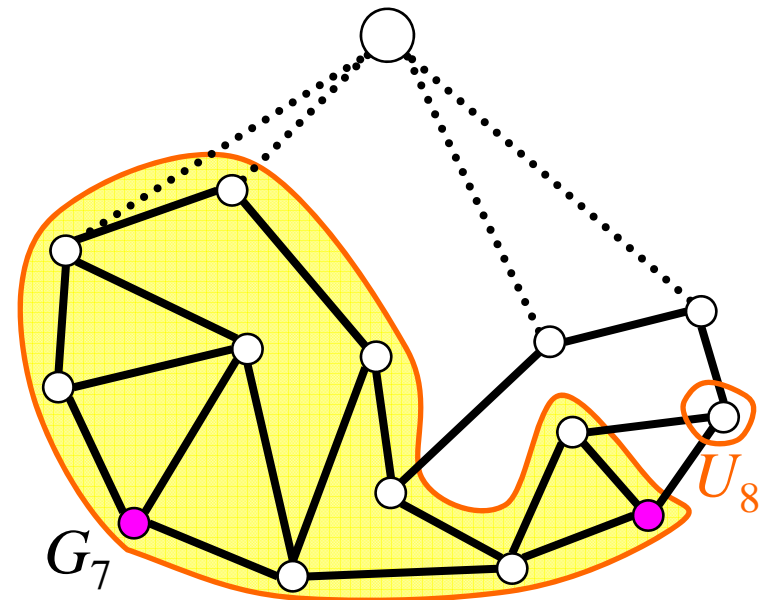


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

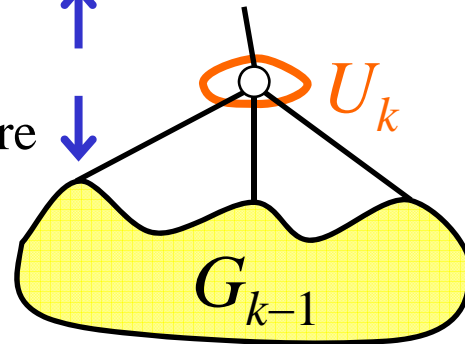


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$

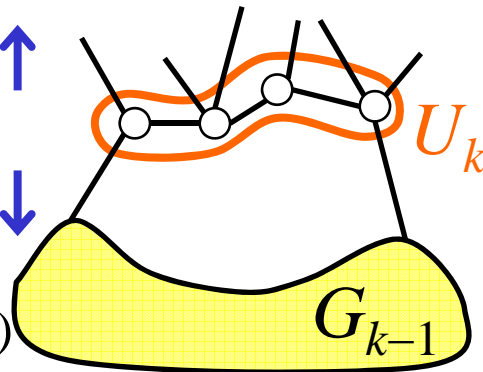
one or more
(each vertex)



exactly one

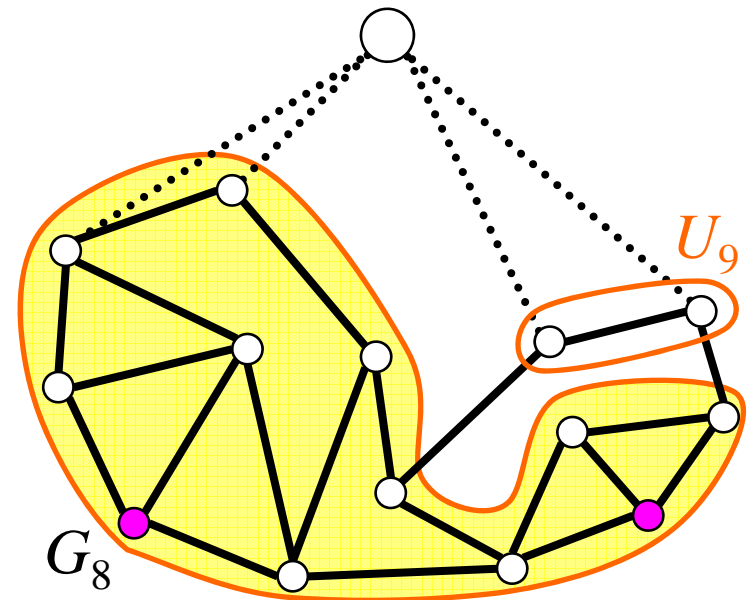


(leftmost and
rightmost vertices)



G_k is induced by

$$U_1 \cup U_2 \cup \dots \cup U_k$$

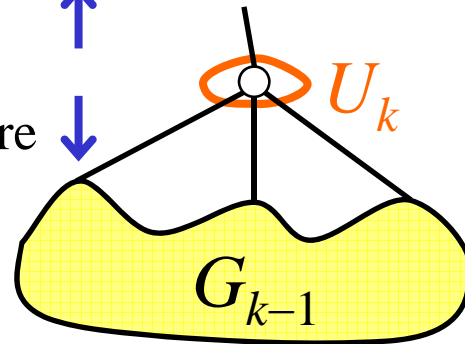


Canonical decomposition

one or more
neighbors



two or more



canonical decomposition

$$\Pi = (U_1 , U_2 , \dots , U_{m-1} , U_m)$$

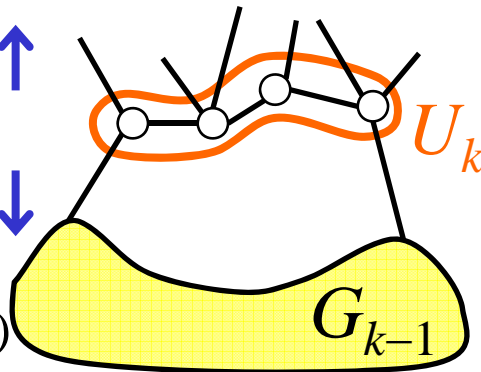
one or more
(each vertex)



exactly one

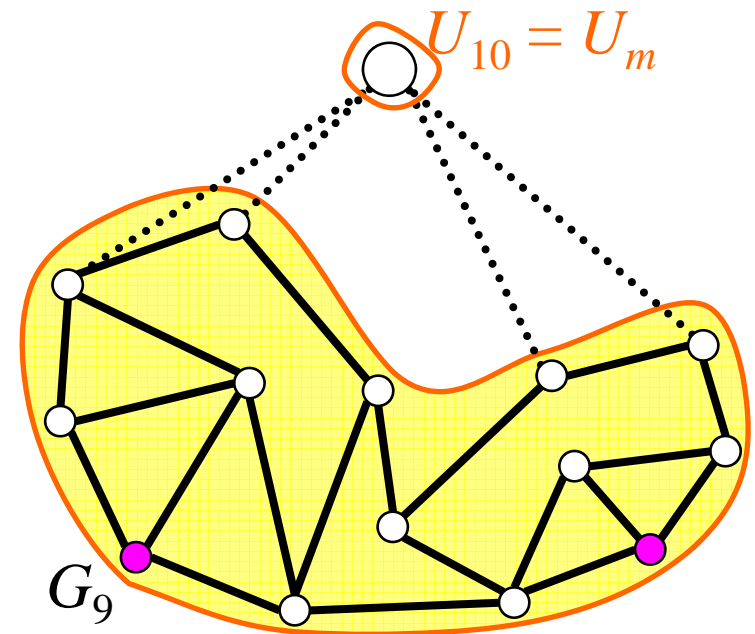


(leftmost and
rightmost vertices)



G_k is induced by

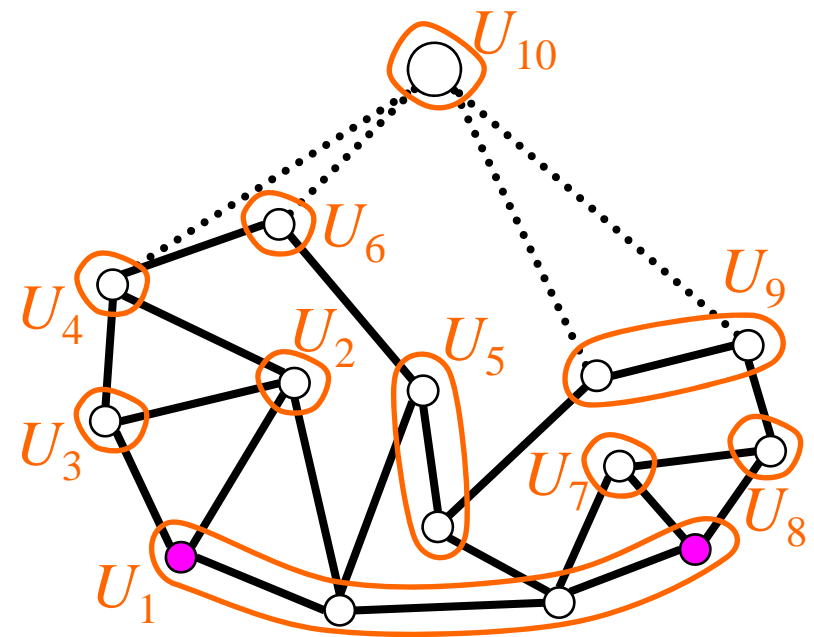
$$U_1 \cup U_2 \cup \dots \cup U_k$$



Canonical decomposition

canonical decomposition

$$\Pi = (U_1, U_2, \dots, U_{m-1}, U_m)$$



$2n \times n^2$ size

convex grid drawing

$$\begin{aligned} & n_1^2 + n_2^2 + 2n+1 \\ = & (n_1 + n_2)^2 - 2n_1n_2 + 2n+1 \\ \leq & n^2 \end{aligned}$$

$$n = n_1 + n_2$$

$$n_1, n_2 \geq 5$$

